

# Introduction; Signals and Noise

Chem 221  
Instrumental Analysis  
Spring 2005

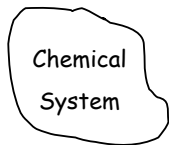
## What is Analytical Chemistry?

- "Analytical chemistry is what analytical chemists DO!"
- "The study of methods for determining the composition of substances."
- Two areas:
  - 1) *Qualitative Analysis (what?)*
  - 2) *Quantitative Analysis (how much?)*

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## The Chemical System

First, we need something to study:



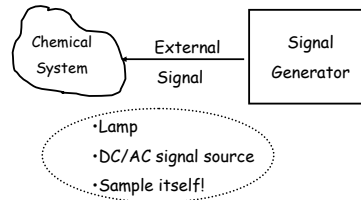
• Can be anything:

- Coal
- Blood
- Gas
- Food
- Reaction mixture

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## The Signal Generator

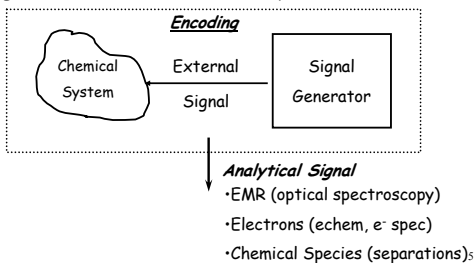
- Interacts with the *Chemical System* to produce an *Analytical Signal*:



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## The Analytical Signal

- Produced by the interaction of the *signal generator* with the *chemical system*: **ENCODING**



## Decoding the Analytical Signal

- How do we decipher the *chemical information* encoded in the *analytical signal*?
- **Four Steps:**
  1. **Disperse** the analytical signal (selectivity)
  2. **Convert** to an *electrical* signal
  3. **Process** the electrical signal
  4. **Output** the resultant signal

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## Dispersive Element

- Enables the *selective* measurement of the analytical signal

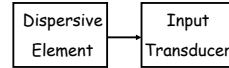
### Examples:

- ✓ *Monochromator* (optical spectroscopy)
- ✓ *Magnetic Field* (mass spectrometry)
- ✓ *Chromatographic Column* (separations)

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## Input Transducer

- Converts the *analytical signal* to an *electrical signal*:



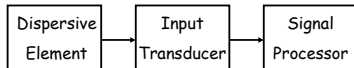
### Examples:

- **Photomultiplier tube (PMT)**  
(photons → electrons)
- **Electrode**  
(chem potential → electrical potential)

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## Signal Processor

- Buffers* input and output transducers (*impedance matching*)



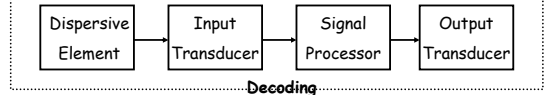
### Examples:

- Amplification
- Current-to-voltage conversion
- AC-to-DC conversion
- Modulation/waveshaping
- ADC and/or DAC
- Math (log, FT, integration)

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## Output Transducer

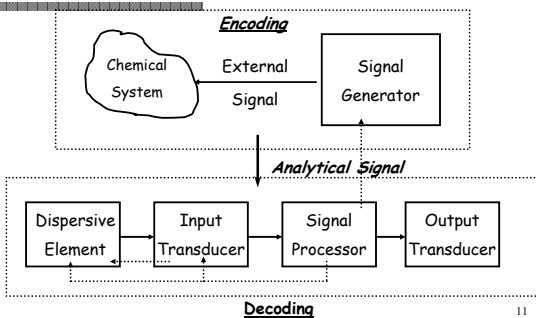
- Converts electrical signal into a "human-understandable" signal



- Most often, a computer
- Also does much of the signal processing

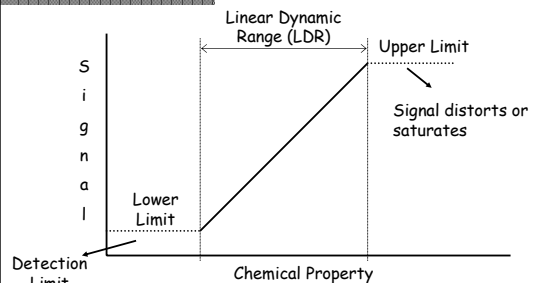
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## The General Instrument



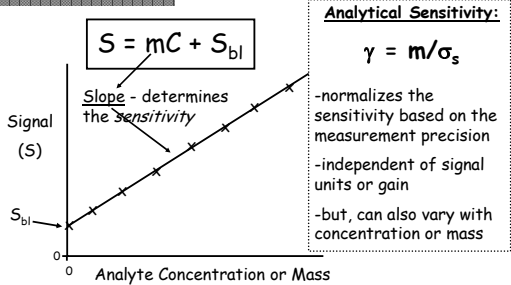
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## Quantitative Properties of Analytical Instrumentation



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## The Analytical Curve



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## Detectability

### Bottom Line Question:

Is the Analytical Signal distinguishable from the Blank?

### Example: Pb analysis

Concentration	Signal	NET Signal
0 ppm (blank)	0.136	0.000
10. ppm	0.721	0.585
1.0 ppm	0.195	0.059
0.10 ppm	0.142	0.006
0.010 ppm	0.137	0.001

We need to know the uncertainty of the measurements.

Std Deviation ( $\sigma$ ) (NOISE)

Which of these are detectable?

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## Defining the Detection Limit

- We use the Signal-to-Noise Ratio (S/N) as the defining figure of merit.

- Most commonly accepted definition:

The detection limit is the concentration of analyte needed to produce a **S/N = 3**

- Where:  $S$  = signal due to analyte  
 $N = \sigma_{\text{blank}}$

Signal different from blank at about 89% confidence level

So, Det. Limit occurs when **S = 3  $\sigma_{\text{blank}}$**

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## Finding the Detection Limit

- BUT:** recall that the signal that is measured includes the blank ( $S_{\text{blank}}$ ), so we define:

$S_m$  = signal measured at the det. Limit

So:

$$\frac{S_m - S_{\text{blank}}}{\sigma_{\text{blank}}} = 3$$

**REMEMBER:** It is not the magnitude of the blank ( $S_{\text{blank}}$ ) that limits detection -- rather, it is the fluctuation or uncertainty of the blank ( $\sigma_{\text{blank}}$ ) that limits detectability.

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## Back to our example

Concentration	Signal	NET Signal
0 ppm (blank)	0.136	0.000
10. ppm	0.721	0.585
1.0 ppm	0.195	0.059
0.10 ppm	0.142	0.006
0.010 ppm	0.137	0.001

Suppose that:

$$\sigma_{\text{blank}} = 0.002$$

$$S = 3 \sigma_{\text{blank}} = 3 (0.002) = 0.006$$

$$\text{So: } S_m = S_{\text{blank}} + S = 0.136 + 0.006 = 0.142$$

(0.10 ppm Pb)

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## Noise

### What is it?

- any "unwanted" part of the analytical signal
- there is *always* some noise in a signal!

### How can we reduce it?

Simple: -turn down the amplifier gain!

### How can we increase S/N?

**Warning!** There are *hidden costs* associated with S/N enhancement:

- decreased resolution (selectivity)
- increased measurement time
- NEW sources of noise!

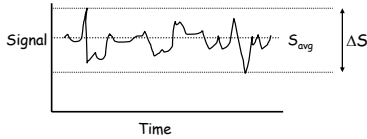
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## Calculating S/N

- For a set of data (replicate measurements):

$$S/N = s_{\text{avg}} / \sigma_s = (\text{RSD})^{-1}$$

- For a temporally-varying signal:



$$\Delta S \approx 5\sigma = 5N$$

$$\underline{S}_0: N \approx \Delta S/5$$

Thus:

$$S/N \approx 5S_{\text{avg}} / \Delta S$$

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## Noise Sources

- We'll characterize by their *frequency response*
- 1. **White Noise** - *amplitude invariant with respect to frequency*

Two types:

- Johnson (Thermal) Noise**

-voltage fluctuations due to random  $e^-$  motion in resistive devices

$$V_{\text{rms}} = (4 k T R \Delta f)^{1/2}$$

Boltzmann's Constant
Absolute Temp
Resistance
Frequency Bandwidth

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## More White Noise

- Shot Noise**

-current fluctuations due to random motion of  $e^-$  across a junction

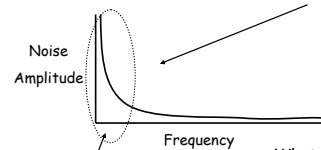
$$i_{\text{rms}} = (2 i_{\text{avg}} e \Delta f)^{1/2}$$

Average Current
Charge on an electron
Frequency Bandwidth

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## More Noise

- 2. **Flicker (1/f) Noise** - *amplitude varies with 1/f*



Most significant at low (<100 Hz) frequencies

What is it?

-drift

-low freq. signal fluctuations

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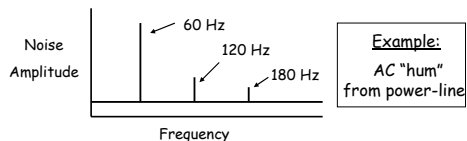
## Still More Noise!

- 3. **Environmental Noise**

Two types:

- Interference Noise**

-predictable; occurs at *known* discrete frequencies



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## More Environmental Noise

- Impulse Noise**

-erratic and unpredictable

-difficult to find source

-motors

-solar flares

-computers

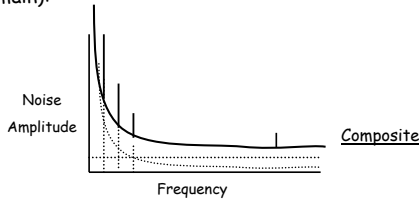
-temperature variations

-difficult to correct!

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## Composite Noise Spectrum

- In order to understand S/N enhancement, need to look at ALL noise sources together (in frequency domain):



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## Strategies for Increasing S/N

- **White Noise:** *reduce  $\Delta f$ , temp, resistance,  $i_{avg}$*

- **Flicker Noise:** *make measurements at frequencies  $>100$  Hz*

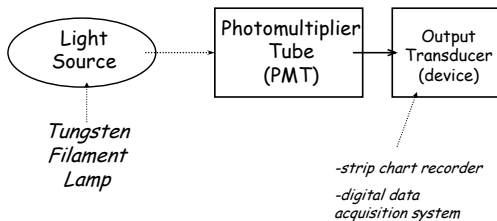
**BUT:**

- **Signal:**
  - often at or near dc (low freq.)
  - often directly proportional to resistance
  - often directly proportional to current
  - often measured with transducers having very LARGE  $\Delta f$

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## Hypothetical Instrument

- Let's explore the signal and noise behavior of a simple light measurement instrument:



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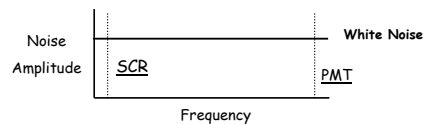
## Reducing $\Delta f$

- Look at *frequency response* of instrument components:

**PMT:**  $10^7$  Hz

**SCR:**  $10^0$  Hz

**DDA:**  $10^0 - 10^7$  Hz (variable)



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## S/N Enhancement: Impact of $\Delta f$

- **Output device/transducer limits  $\Delta f$ :**

$$\frac{S/N(\Delta f = 10^0)}{S/N(\Delta f = 10^7)} \approx 10^3$$

- $\Delta f$  can be easily adjusted using a *low-pass* frequency filter

- **BUT:** remember that  $\Delta f$  also affects ability to measure the signal (at  $f_s$ ):  $f_s > 0$

So, object is to keep  $\Delta f$  to a *minimum*, without reducing the **SIGNAL**

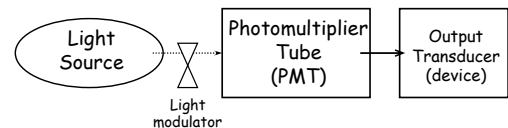
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## Reducing 1/f Noise

- We need to *move  $f_o$*  to  $>100$  Hz ... **HOW?**

→ **MODULATE** the source

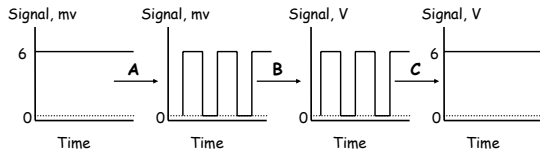
-analytical signal "encoded" at a freq. where 1/f noise is negligible



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## Tuned Amplification: Chopper Amplifiers

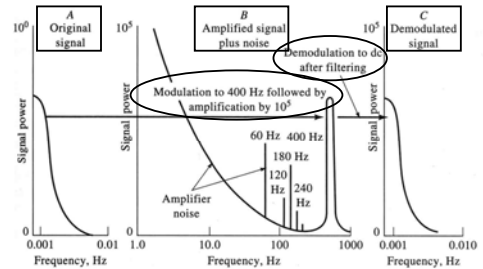
- If we **amplify** the signal **at the modulation frequency**, then we can also **increase the signal** while we **reduce the noise**:



**A: modulate B: amplify C: demodulate**

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## Chopper Amplifiers: In the Frequency Domain



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## Lock-In Amplification

- Tuned (chopper) amplification is limited by stability of  $f_0$  reference
  - this limits the effective  $\Delta f$  to about 1 Hz
- *Lock-in* amplification tunes the amplifier to **both**  $f_0$  as well as the **phase** of the signal
  - results in an effective reduction of  $\Delta f$  to about 0.01 Hz

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## Signal Averaging

- Need a *repeatable* signal (time domain method)
- Sum digitally-stored replicate signals
- How does this improve S/N?
  - Signal:** increases *linearly* with number ( $n$ ) of replicate signals
  - Noise:** increases as  $(n)^{1/2}$
  - So, **S/N increases as  $(n)^{1/2}$**

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## Signal Averaging: Example

- Suppose we wish to *mass* a 10-mg object on an analytical balance ( $\sigma = 0.1$  mg)

For a single ( $n=1$ ) measurement:

$$S = 10. \text{ mg}, N = 0.1 \text{ mg} \rightarrow S/N = \underline{100}$$

For  $n = 4$ :

$$S = n \times 10. \text{ mg} = 4 \times 10. \text{ mg} = 40. \text{ mg}$$

$$N = \sigma_T = (n(\sigma)^2)^{1/2} = (4(0.1)^2)^{1/2} = 2(0.1) = 0.2 \text{ mg}$$

$$S/N = 40./0.2 = \underline{200}$$

For  $n = 16$ : **S/N = 400**

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## Signal Averaging: General

- In general, we can say:

$$(S/N)_n = (n)^{1/2} (S/N)_{n=1}$$

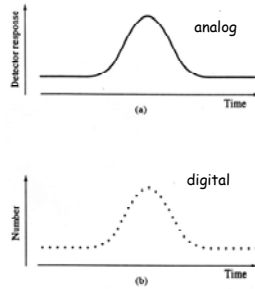
- **Diminishing returns:** *Suppose, it takes 1 second per measurement?*

S/N	n	Time
3	1	1 sec
6	4	4 sec
30	100	100 sec
300	10,000	2.8 hours
3000	1,000,000	11.6 days

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## More Signal Averaging

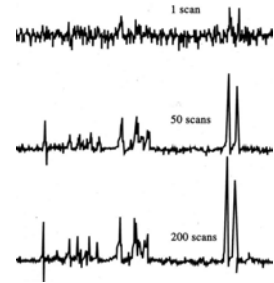
- Signal must be digitized . . . How?
- Digitization frequency?  
- Nyquist Theorem
- Precision of digitization?  
- how many bits?  
8-bit =  $2^8 = 256$  (0.4 %)  
12-bit =  $2^{12} = 4096$  (0.02 %)



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## Signal Averaging a Spectrum

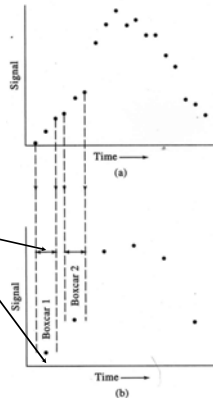
- Get same S/N enhancement:  
- incr. with  $n^{1/2}$
- Need good synchronization for each replicate scan



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## Boxcar Averaging

- Just a *single-channel* signal averager:  
- select a single *delay time*  
- integrate signal over selected *time gate*  
- average signal for *n-replicates*  
- repeat at new *delay time*
- Gives S/N incr. with  $n^{1/2}$  for each data point



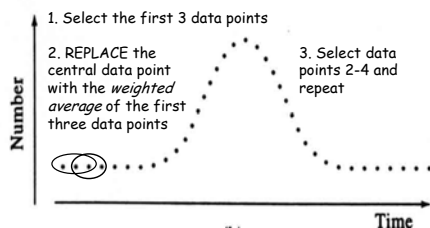
## Digital Filtering

- Can manipulate *digitized signals* to improve S/N  
- can do this *after* data collection  
- don't need a repetitive signal
- Two methods we'll consider:  
- Savitsky-Golay Smoothing (time domain)  
- Fourier Filtering (frequency domain)

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## Savitsky-Golay Smoothing

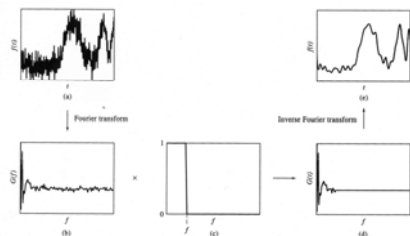
- A *weighted moving average* applied to a series of data. **EXAMPLE: 3-point smooth**



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## Fourier Filter/Smooth

- We would have greater control if we were to do this in the *frequency domain*:



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## Beware!

- It is easy to *smooth/filter* signal as well as noise
  - overlay original and processed waveforms
  - make sure that result is not *distorted*
- Need high point density
  - trade-off between *resolution* and noise  
(high point density = greater  $\Delta f$ )
  - trade-off between *resolution* and **time**  
(lotsa data points = incr. storage and processing time)