

## Signless Laplacian Matrix

We discuss one more version of the Laplacian matrix of a graph  $G$ : the signless Laplacian. This matrix is defined as

$$Q(G) = D(G) + A(G) = L(G) - 2A(G).$$

**Exercise 1.** Show that if the diameter of a graph  $G$  is  $d$ , then  $Q(G)$  has at least  $d + 1$  eigenvalues. (As we already know about  $A(G)$  and  $L(G)$ .) 1 point

**Exercise 2.** We had that 1 point

$$\vec{x}^T L \vec{x} = \sum_{uv \in E(G)} (x_u - x_v)^2.$$

Write a similar expression for the signless Laplacian.

**Exercise 3.** What can you say about the multiplicity of the eigenvalue 0? 2 points

Let  $S(G)$  be the signless version of the edge incidence matrix: i.e. an  $n \times m$  matrix, which has a 1 in row  $v$  and column  $e$  if  $v \in e$ .

**Exercise 4.** Show that  $Q = SS^T$ . 1 point

**Exercise 5.** Show that for any  $n \times m$  matrix  $A$  and  $m \times n$  matrix  $B$ , we have 4 points

$$\lambda^n \det(\lambda I_n - AB) = \lambda^m \det(\lambda I_m - BA),$$

and conclude that  $AB$  and  $BA$  have the same spectrum (including multiplicities), except for the 0 eigenvalue.

**Exercise 6.** Let  $\text{Line}(G)$  be the line graph of  $G$ . Show that all eigenvalues of  $A(\text{Line}(G))$  are bounded from below by  $-2$ . 3 points

**Exercise 7.** Use the facts from the previous questions to explain the relationship between the spectra of  $A(\text{Line}(G))$  and  $Q(G)$ . 3 points

## Transition matrices

A (linear) discrete dynamical system takes the form

$$\vec{x}(t) = P\vec{x}(t-1), \text{ with some initial condition } \vec{x}(0) = \vec{x}_0.$$

We can write this as a direct formula

$$\vec{x}(t) = P^t \vec{x}_0.$$

We define a *Markov chain* on (finitely many) states  $S = \{1, 2, \dots, n\}$  as a process that starts in some state and moves to another state (or stays put) at each discrete time step. So, at each time step  $t$ , we have a random variable  $X_t$  which represents the state of the process at time  $t$ . A *Markov process* is time-homogeneous and memoryless. This means that the random variables  $X_1, X_2, \dots$  are identically distributed, and that at each time step, the probability distribution of the next step of the system depends only on the current state, i.e.

$$\mathbb{P}(X_{t+1} = k | X_1 = x_1, \dots, X_t = x_t) = \mathbb{P}(X_{t+1} = k | X_t = x_t).$$

We call these the transition probabilities:

$$p_{ji} = \mathbb{P}(X_{t+1} = j | X_t = i),$$

which we can represent in a  $n \times n$  transition matrix  $P$ .

We call  $\vec{x}$  a *distribution vector* if it has nonnegative elements that add up to 1. We then have the following result.

**Exercise 8.** Show if  $P$  is a transition matrix and  $\vec{x}$  is a distribution vector, then  $P\vec{x}$  is a distribution vector. In fact, the transformation  $P$  always preserves the sum of elements of a vector. 0 points

**Exercise 9.** Show that if  $\vec{x}_t$  represents the distribution of probabilities of  $X_t$  taking values in  $\{1, 2, \dots, n\}$ , then  $\vec{x}_{t+1} = P\vec{x}_t$  represents the distribution of probabilities of  $X_{t+1}$  taking values in  $\{1, 2, \dots, n\}$ . 1 point

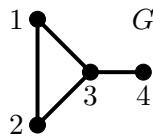
**Exercise 10.** Show that if  $P$  is a primitive  $n \times n$  transition matrix, then  $P$  has exactly one distribution eigenvector  $\vec{x}$  with eigenvalue 1 (where 1 is the largest eigenvalue), meaning that  $P\vec{x} = \vec{x}$ . This is called the equilibrium distribution of  $P$ , and denoted by  $\vec{x}_{equ}$ . For any starting distribution  $\vec{x}_0$ , we have 3 points

$$\lim_{t \rightarrow \infty} P^t \vec{x}_0 = \vec{x}_{equ}.$$

**Exercise 11.** Show that if  $P$  has a unique equilibrium, this does not imply that  $P$  is primitive. 1 point

**Number of returns in a random walk on a finite graph**

The following example and proof are taken from Bollobás’ Modern Graph Theory. We’ve spent some time thinking about Markov chains on a finite set of states, which can be thought of as random walks on a finite graph. Now we’ll look in more detail at the very basic case where a walker is on a finite, simple, undirected graph  $G(V, E)$ . The walker starts at a starting vertex  $v_0 \in V(G)$ , and at each time step, they move from their current vertex  $v$  to a neighboring vertex of  $v$ , choosing one uniformly from the set  $\Gamma(v)$  (the neighborhood of  $v$ ). For example, the following graph  $G$  has the transition matrix  $M$ :



$$M = \begin{pmatrix} 0 & \frac{1}{2} & \frac{1}{3} & 0 \\ \frac{1}{2} & 0 & \frac{1}{3} & 0 \\ \frac{1}{2} & \frac{1}{2} & 0 & 1 \\ 0 & 0 & \frac{1}{3} & 0 \end{pmatrix}$$

**Exercise 12.** Write  $P$  of this random walk in terms of  $A(G)$  and  $D(G)$ . 0 points

**Exercise 13.** Show that when  $G$  is a connected and non-bipartite graph, then 2 points

$$\vec{x} = \frac{1}{2m} \begin{pmatrix} d(1) \\ d(2) \\ \vdots \\ d(n) \end{pmatrix},$$

where  $m = |E(G)|$  is the equilibrium vector of the random walk on  $G$ .