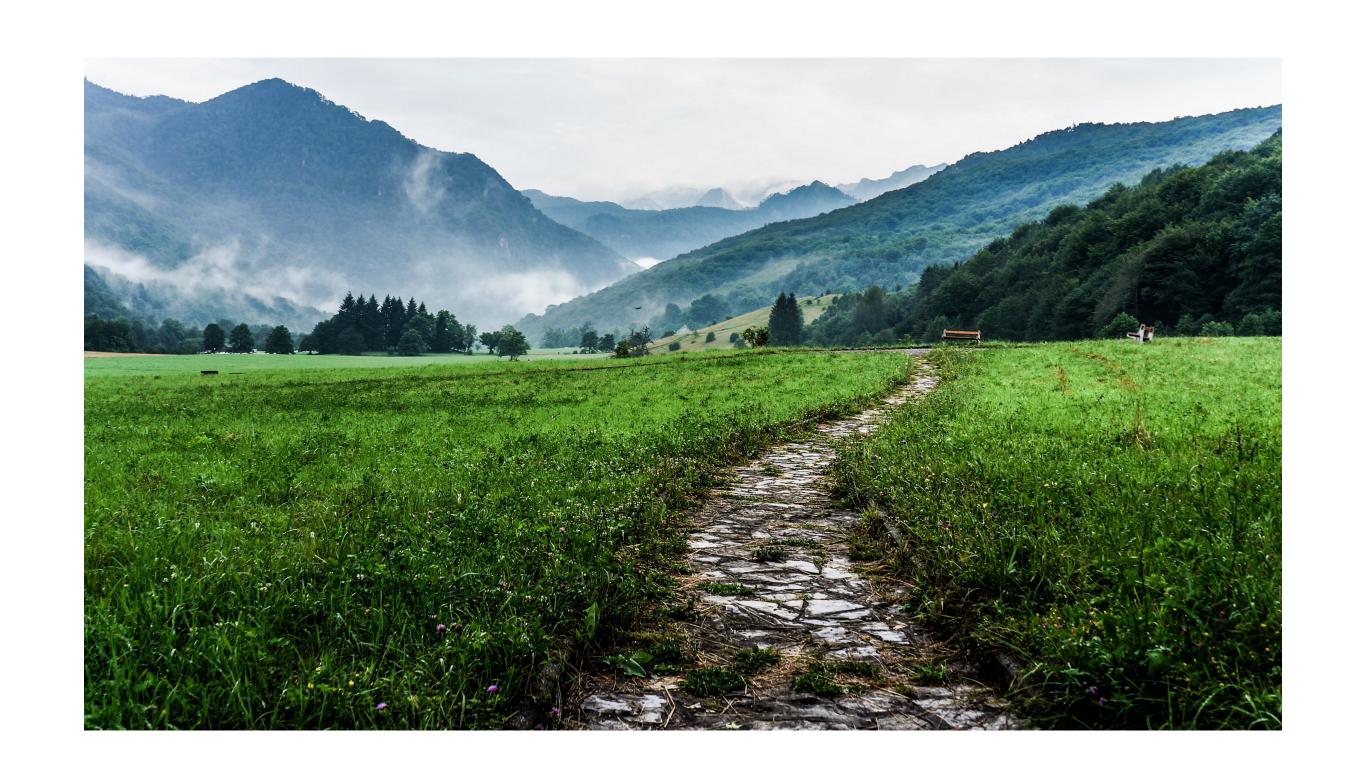


# Shortest Path

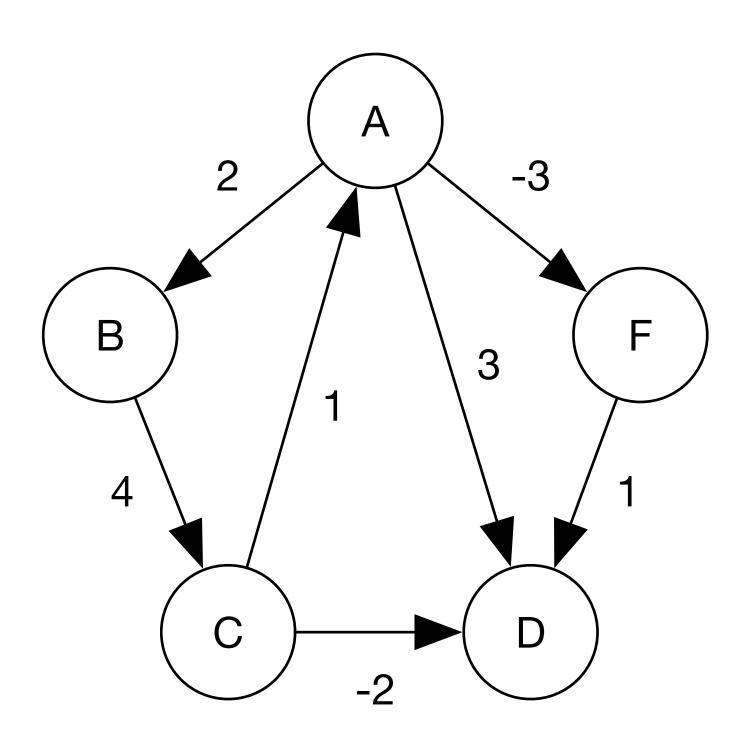
**Bellman-Ford Algorithm** 

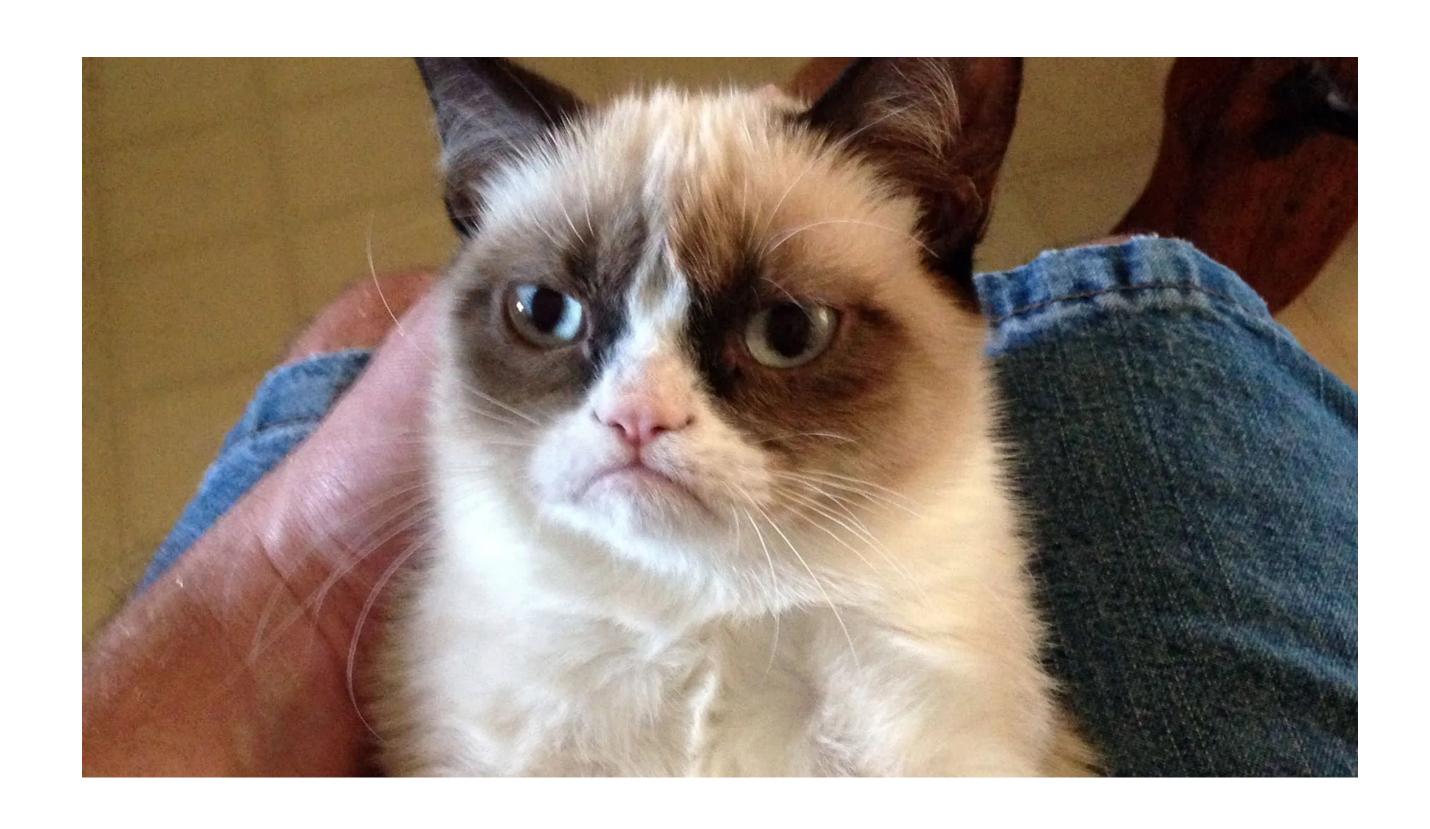


**CS 124 / Department of Computer Science** 

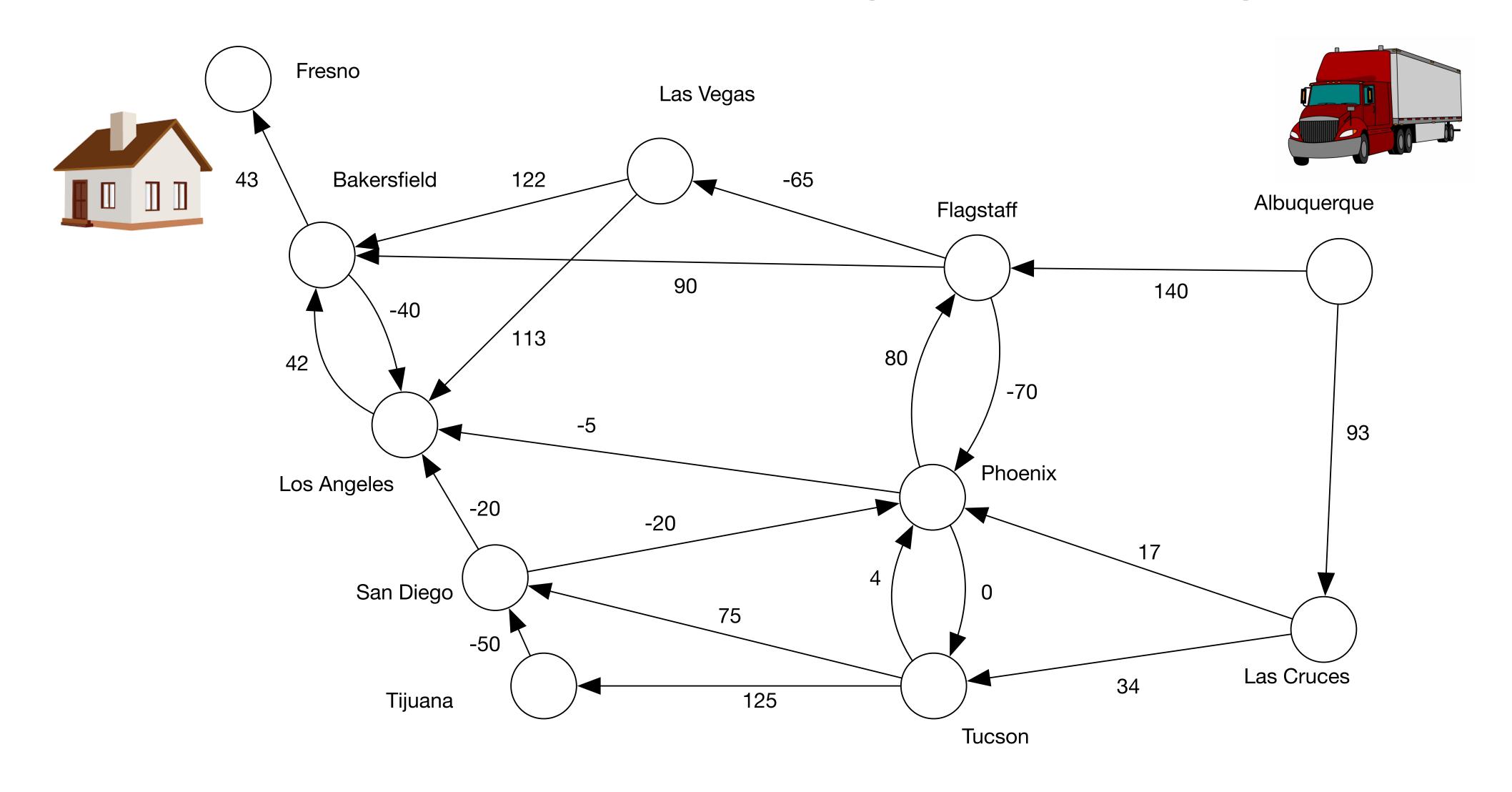
# Shortest path

Dijkstra's algorithm doesn't work if there's an edge in the graph with negative weight.





# Lowest-cost path with negative weights



# What can be done?

# What can be done? Bellman-Ford algorithm

Given some graph, G = (V, E), and some starting node  $S \in V$ , the Bellman-Ford algorithm will find the shortest paths (or paths with minimum weight) from S to all other nodes in V.

Note that G must not contain any negative weight cycles.

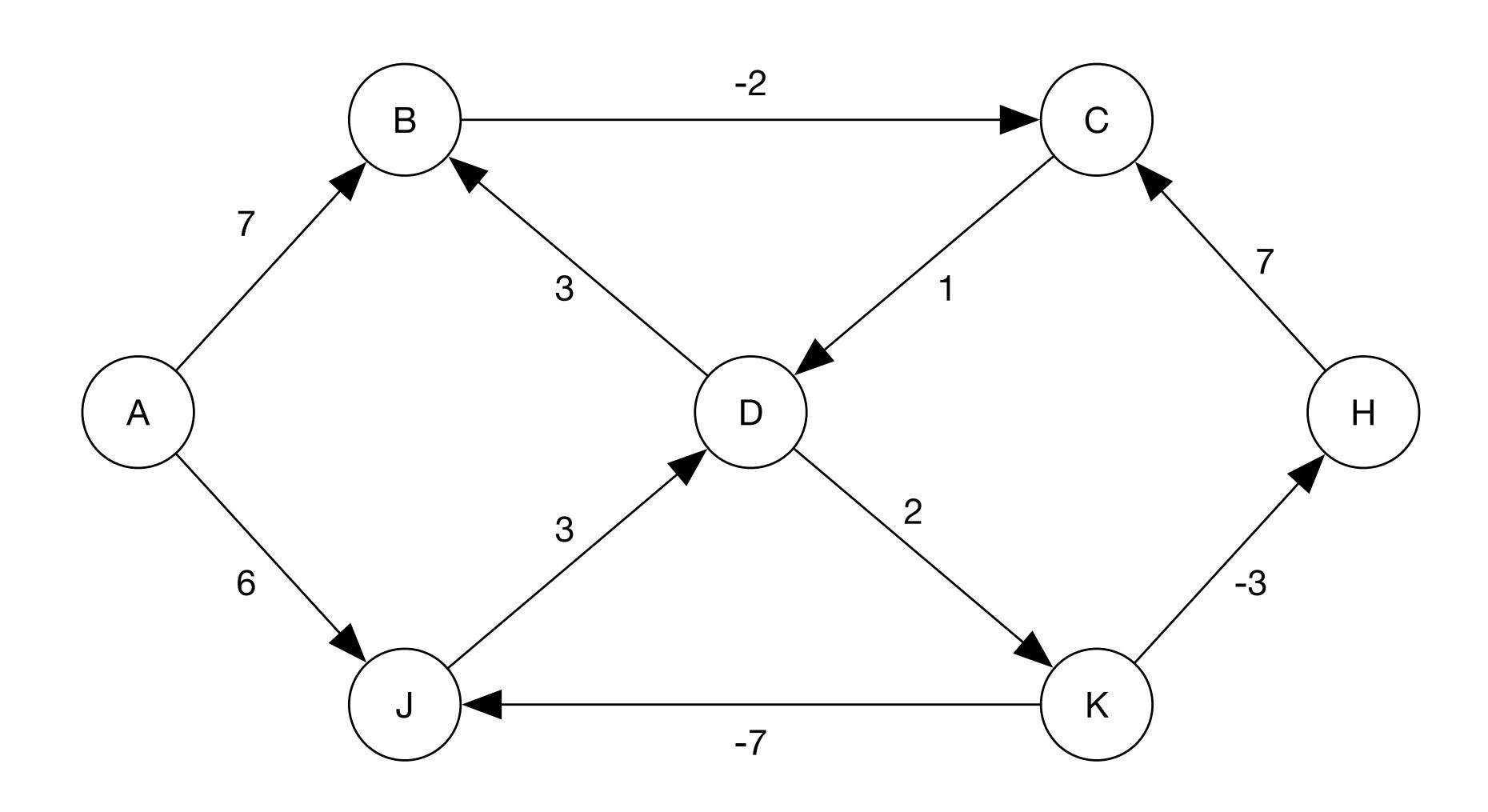
## **Shortest Path / Lowest Cost Path**

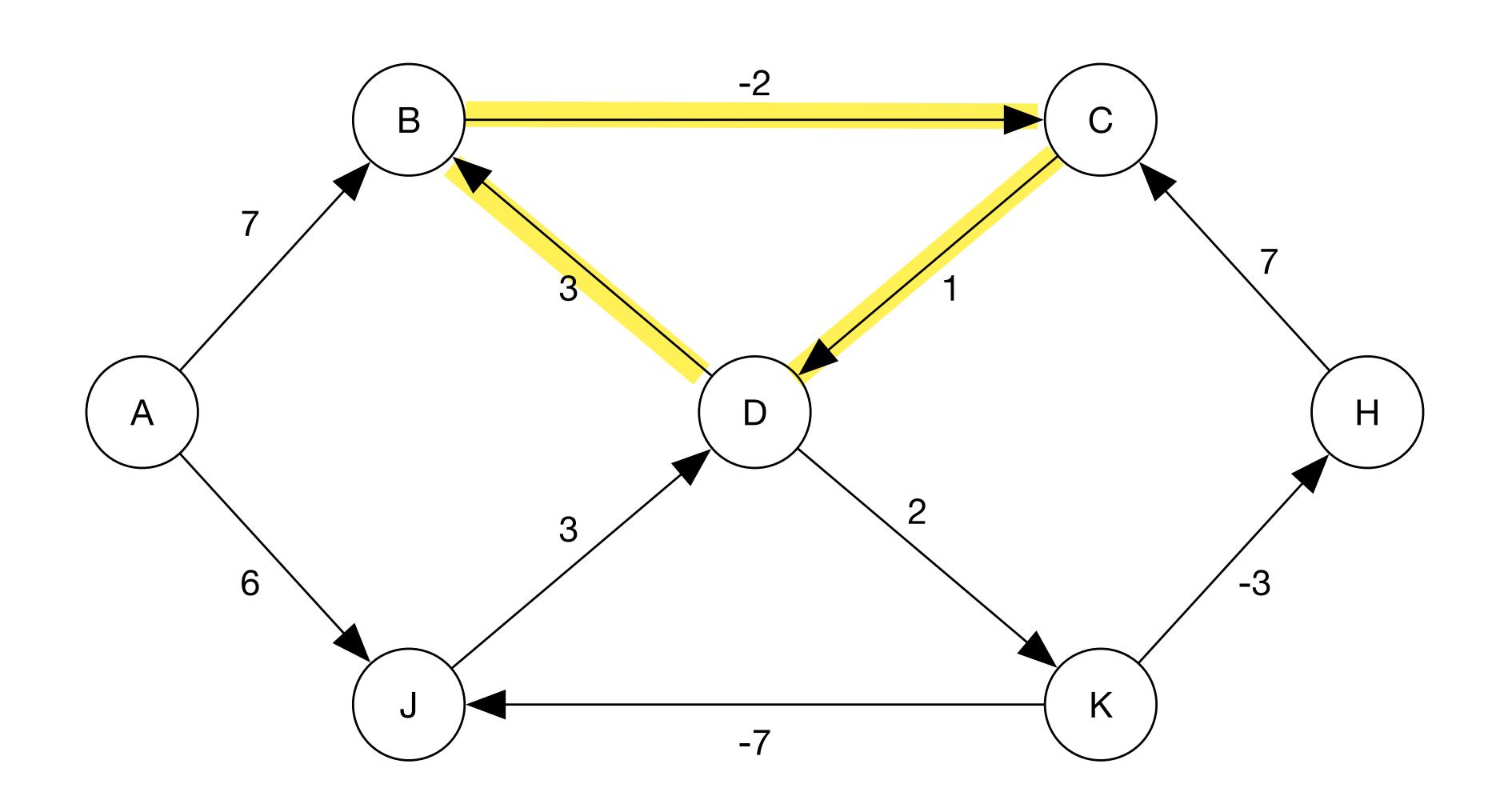
Algorithm	Dijkstra	Bellman - Ford
Worst-case complexity	O(( V  +  E ) log  V )	O( V  x  E )

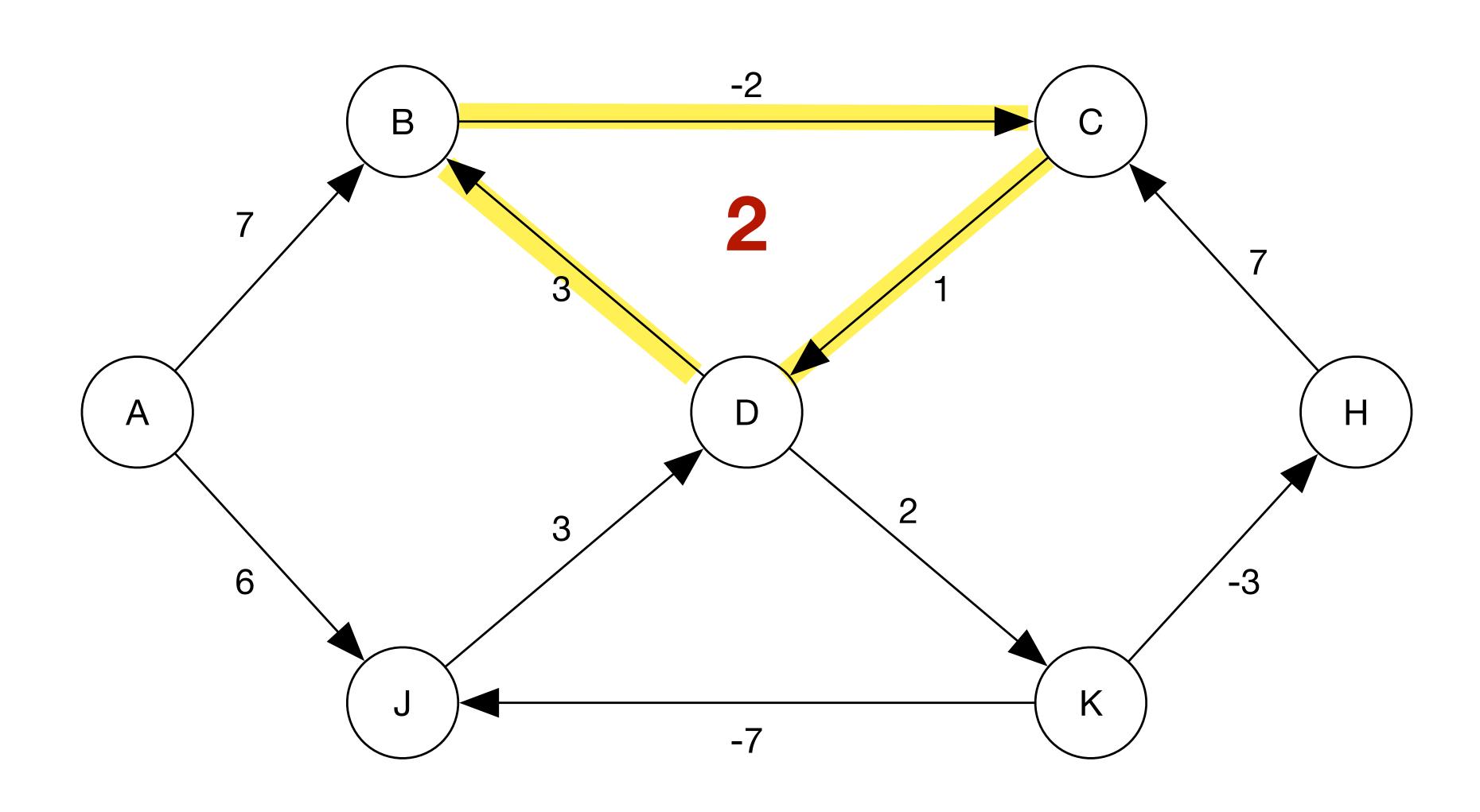
Restrictions

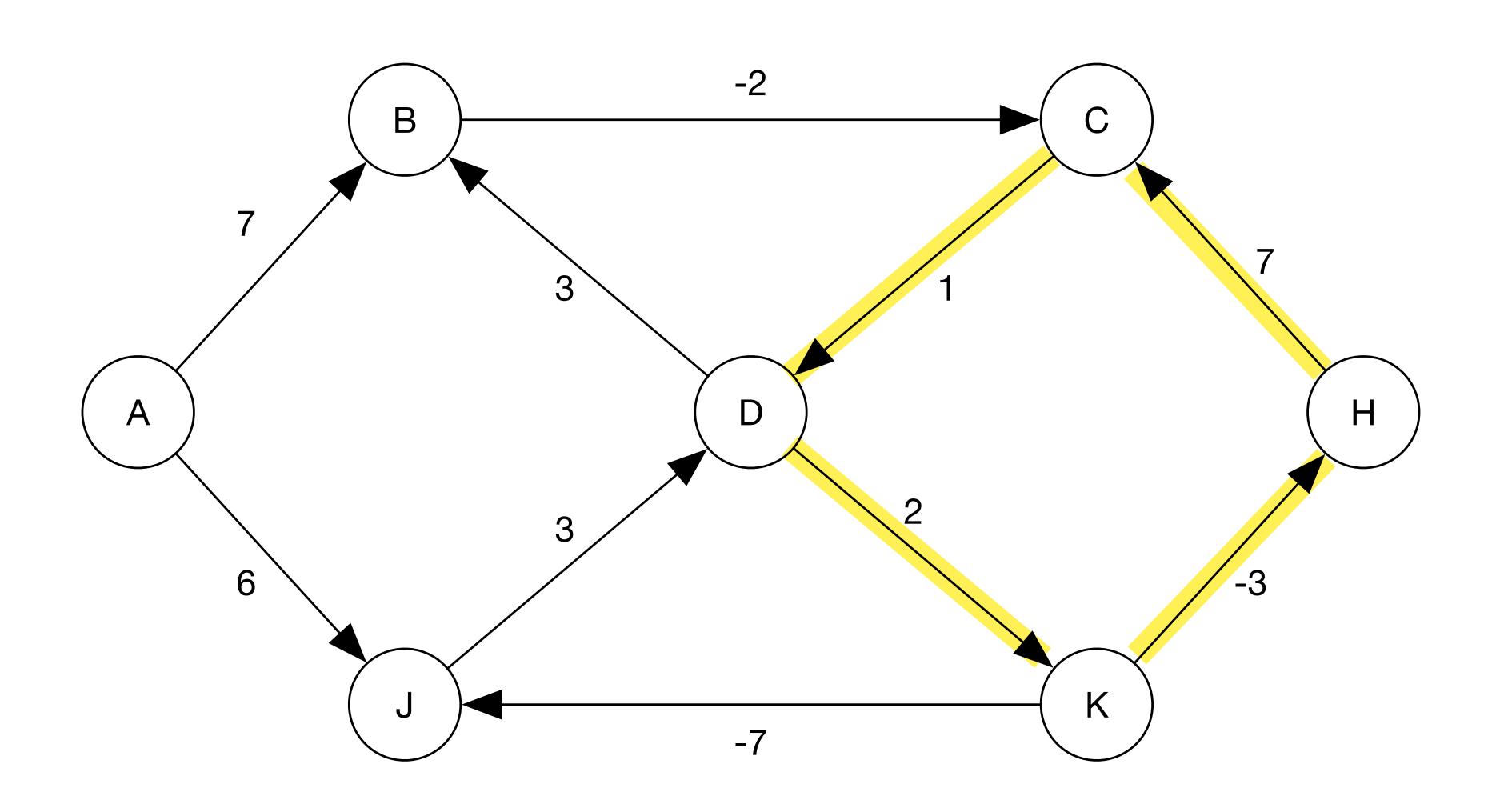
Edge weights must be non-negative

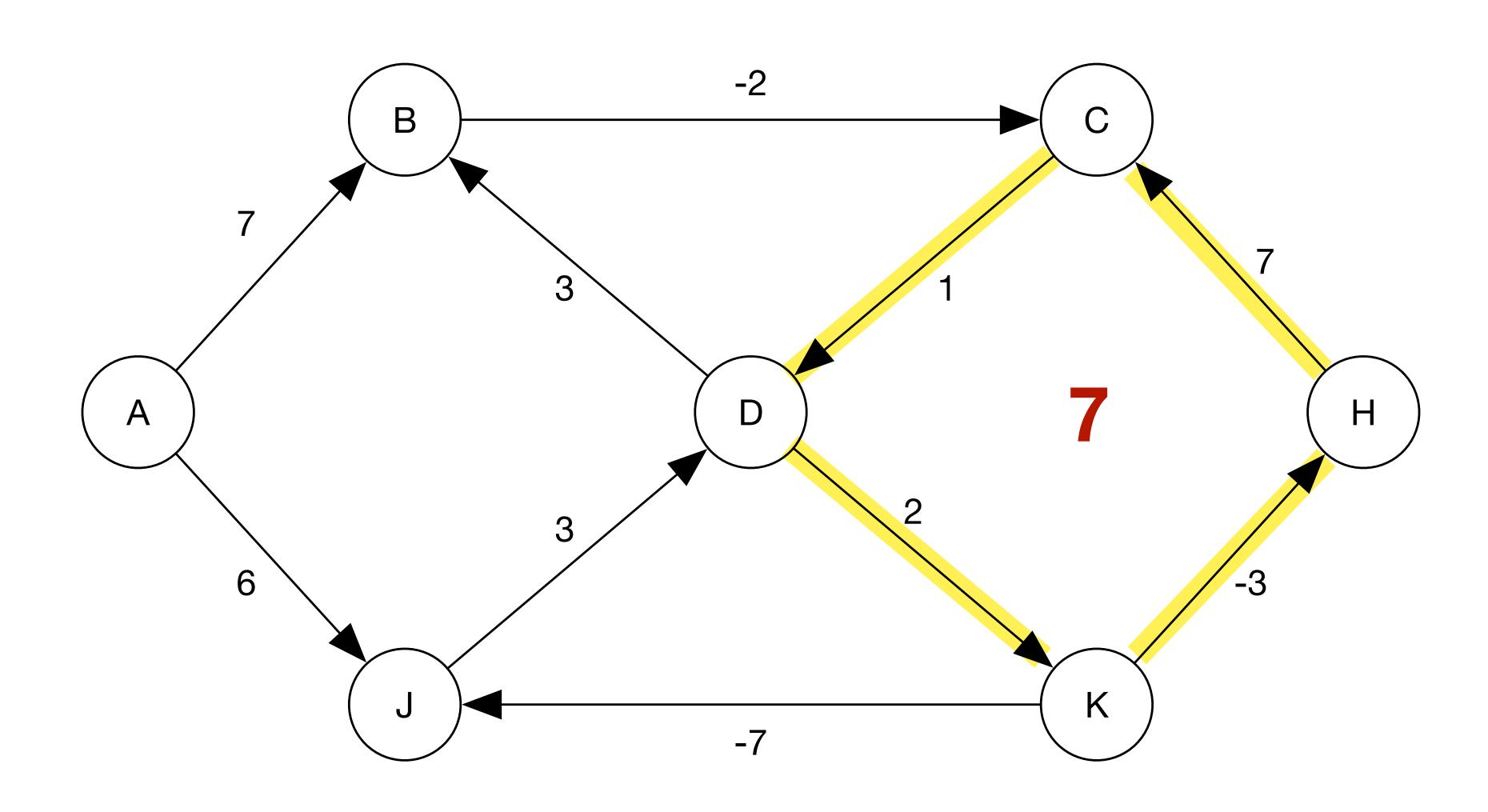
No negative cycles

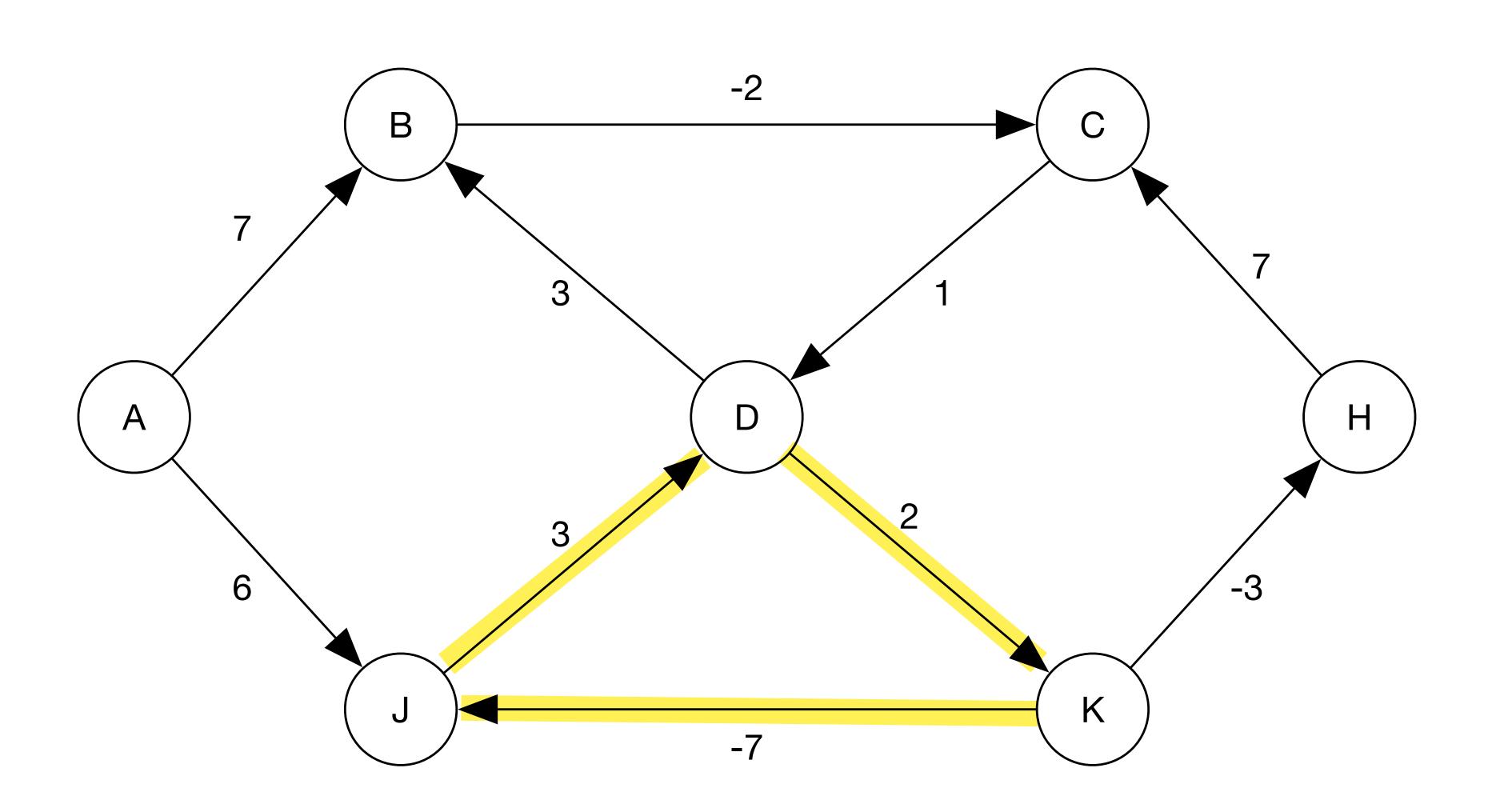


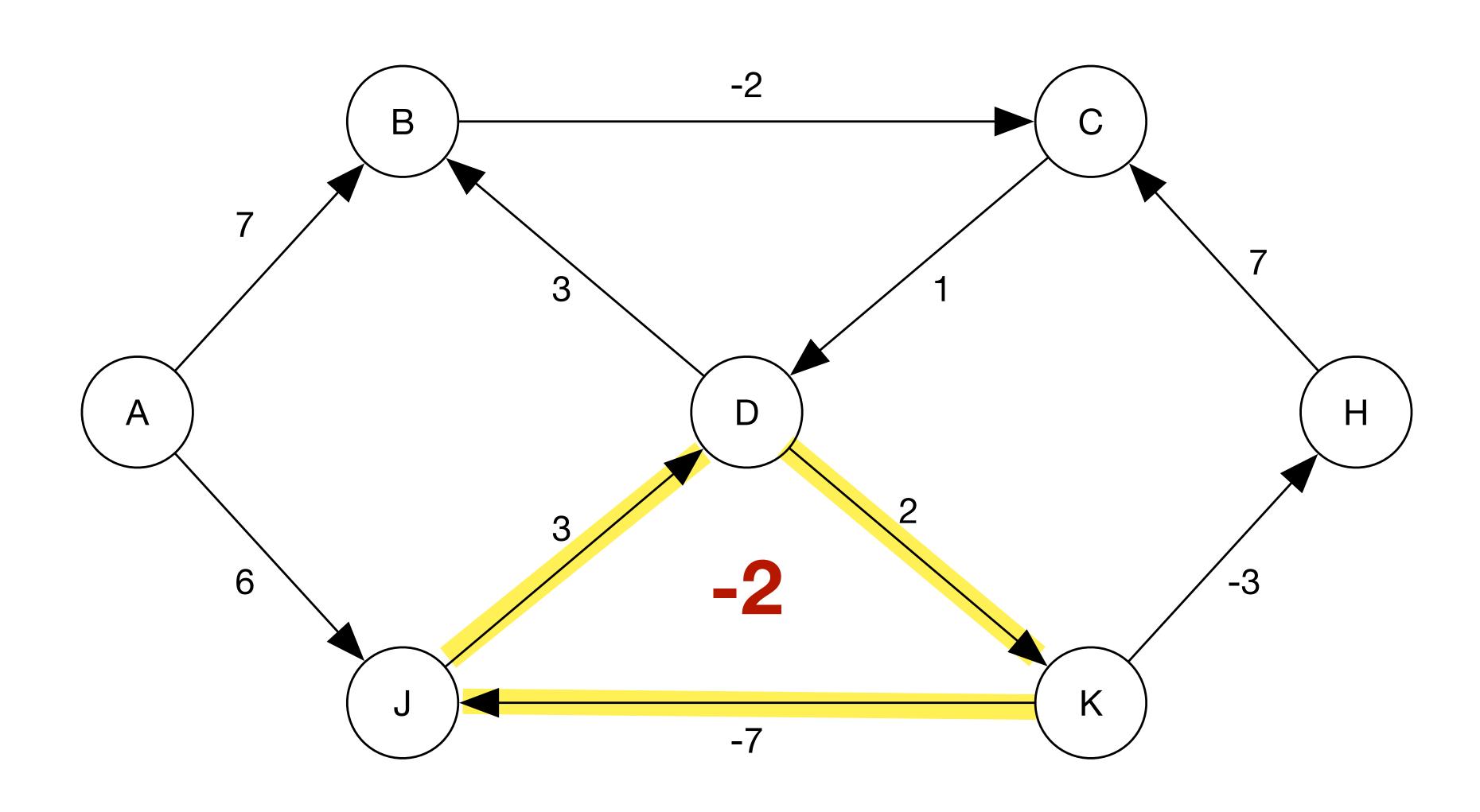












# Bellman-Ford: pseudocode

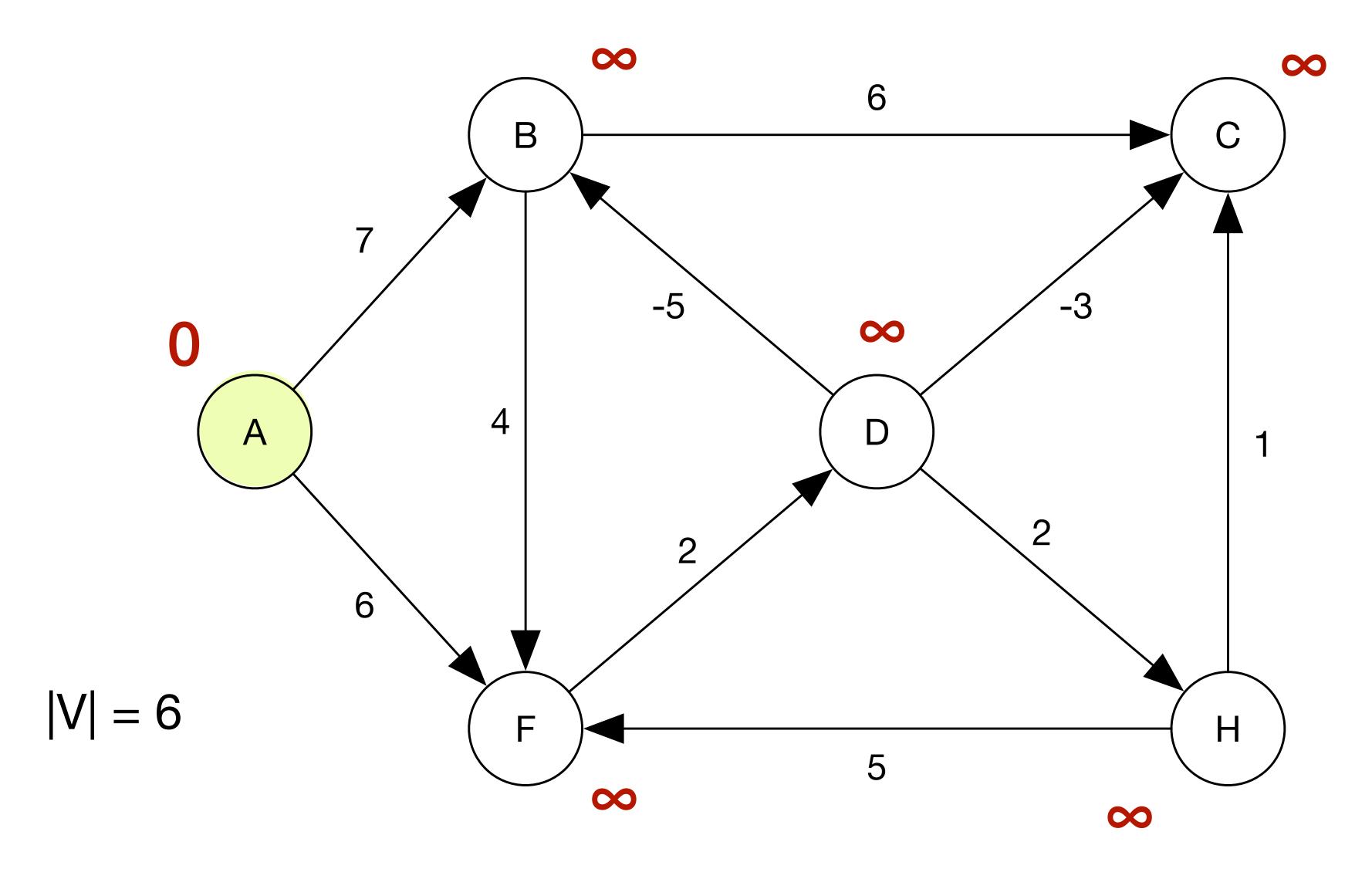
```
function bellman_ford(G, S) // G is the graph; S is the starting node
    for each node V in G
        arrived_from[V] = null
        if V = S
            distance[V] = 0
        else
            distance[V] = infinite
   repeat |V| - 1 times or until no distances are updated
        for each edge (U, V) in E
            distance = distance[U] + weight of edge
            if distance < distance[V] // We've found a shorter distance</pre>
                distance[V] = distance
                arrived_from[V] = U
   for each edge (U, V) in E
       if distance[V] > distance[U] + weight of edge
           return "ERROR: negative weight cycle"
```

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AB

AF

BF

BC

DB

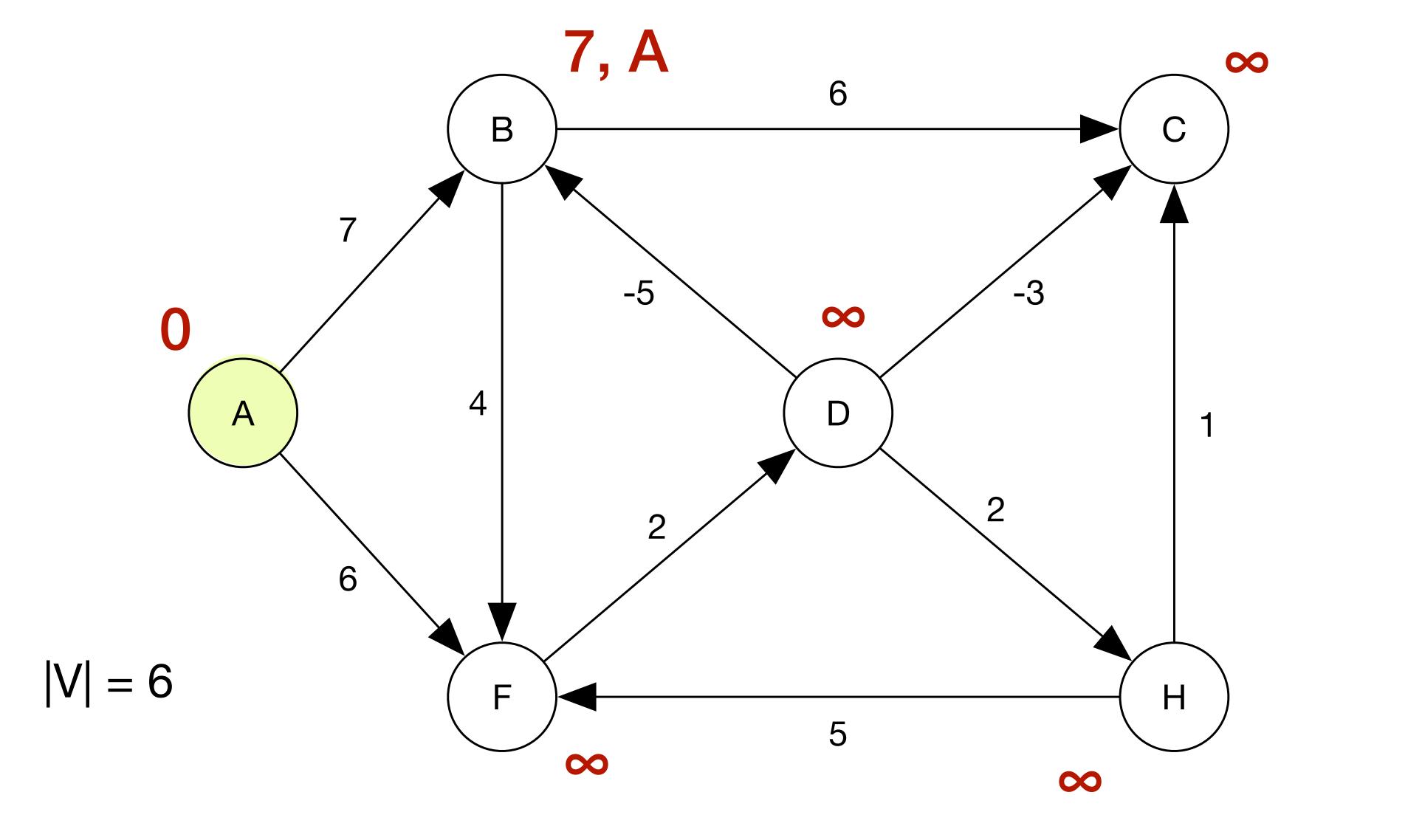
DC

DH

FD

HC

#### First iteration



AB

AF

BF

BC

DB

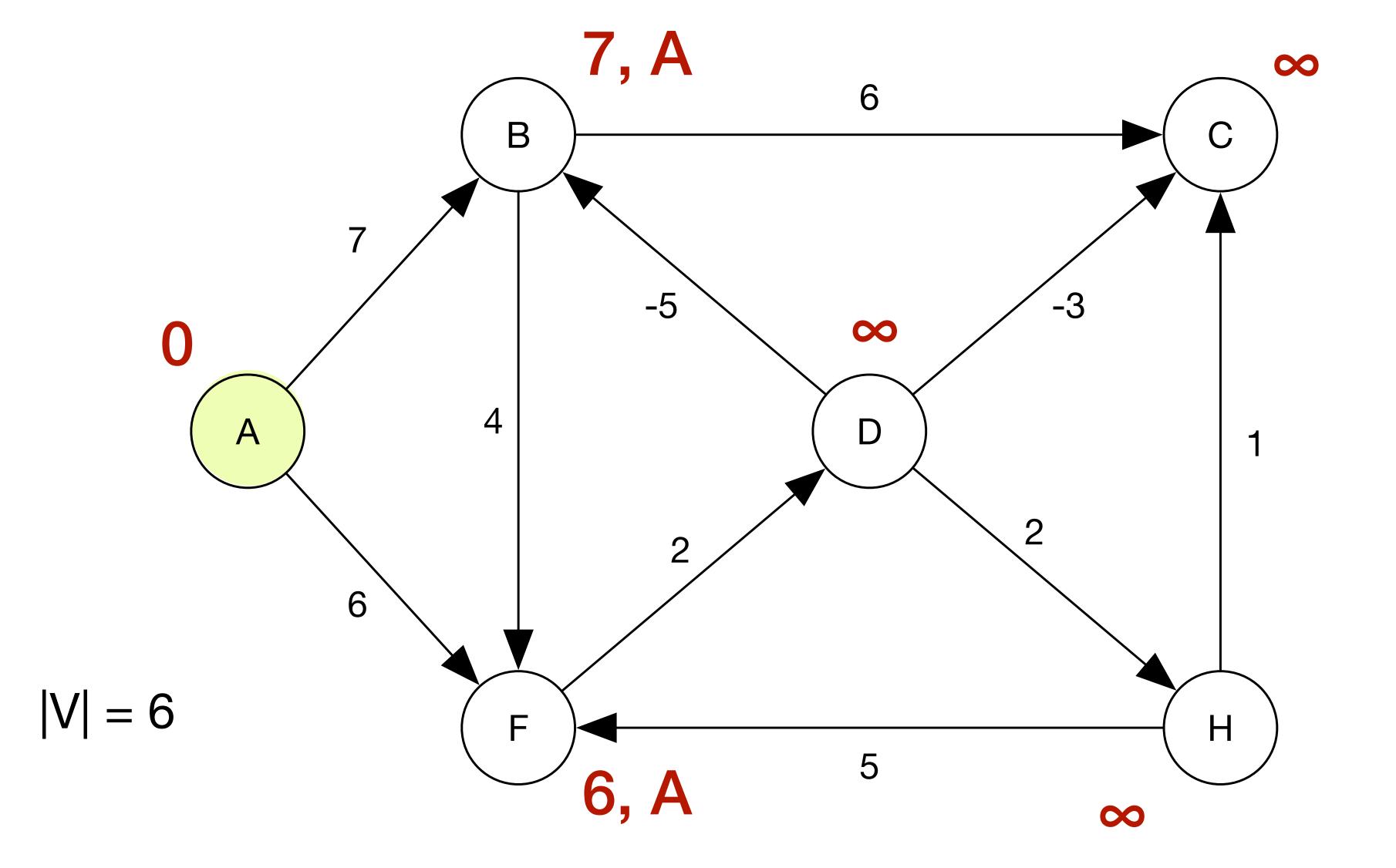
DC

DH

FD

HC

#### First iteration



AB

AF

BF

BC

DB

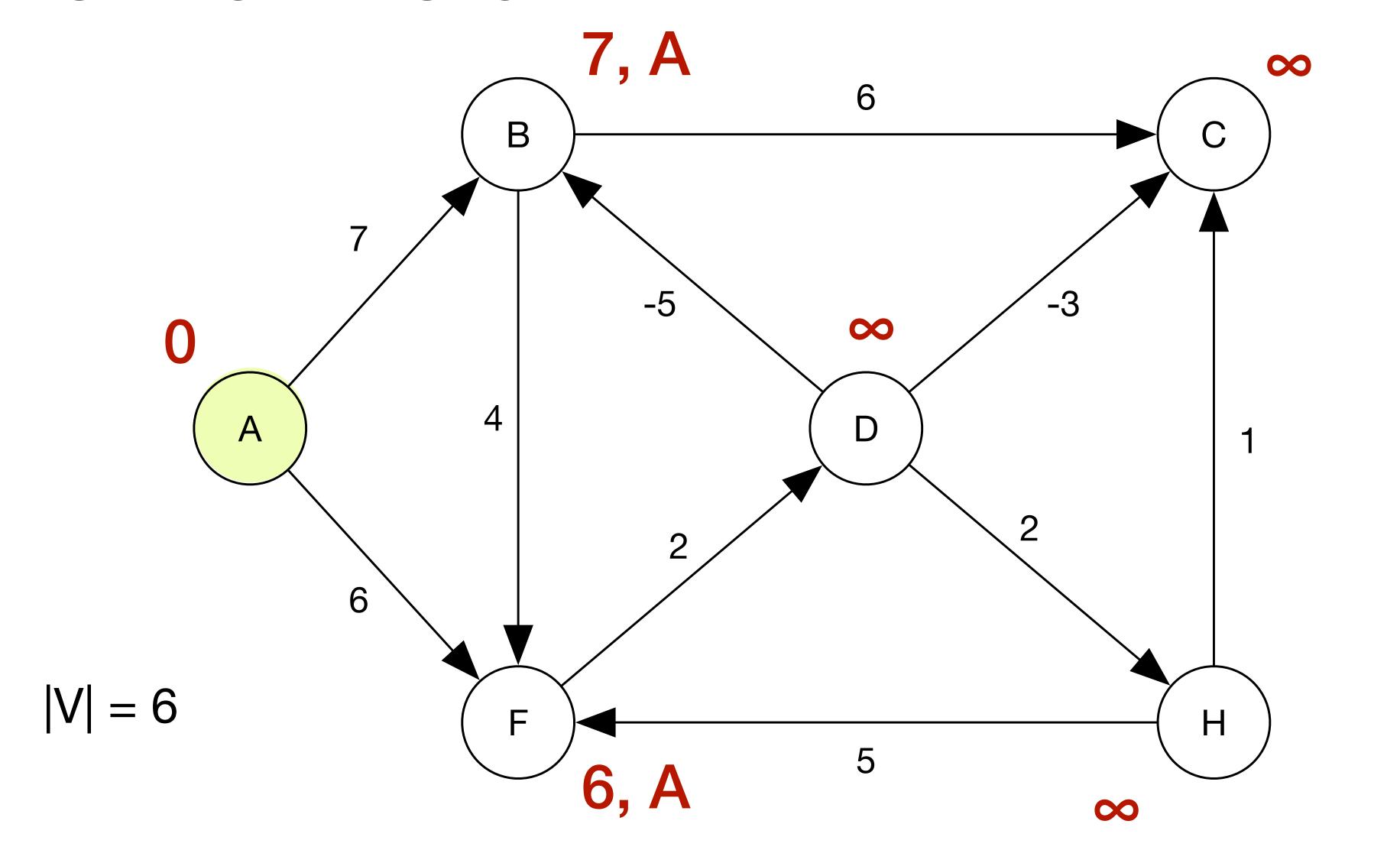
DC

DH

FD

HC

#### First iteration



AB

AF

BF

BC

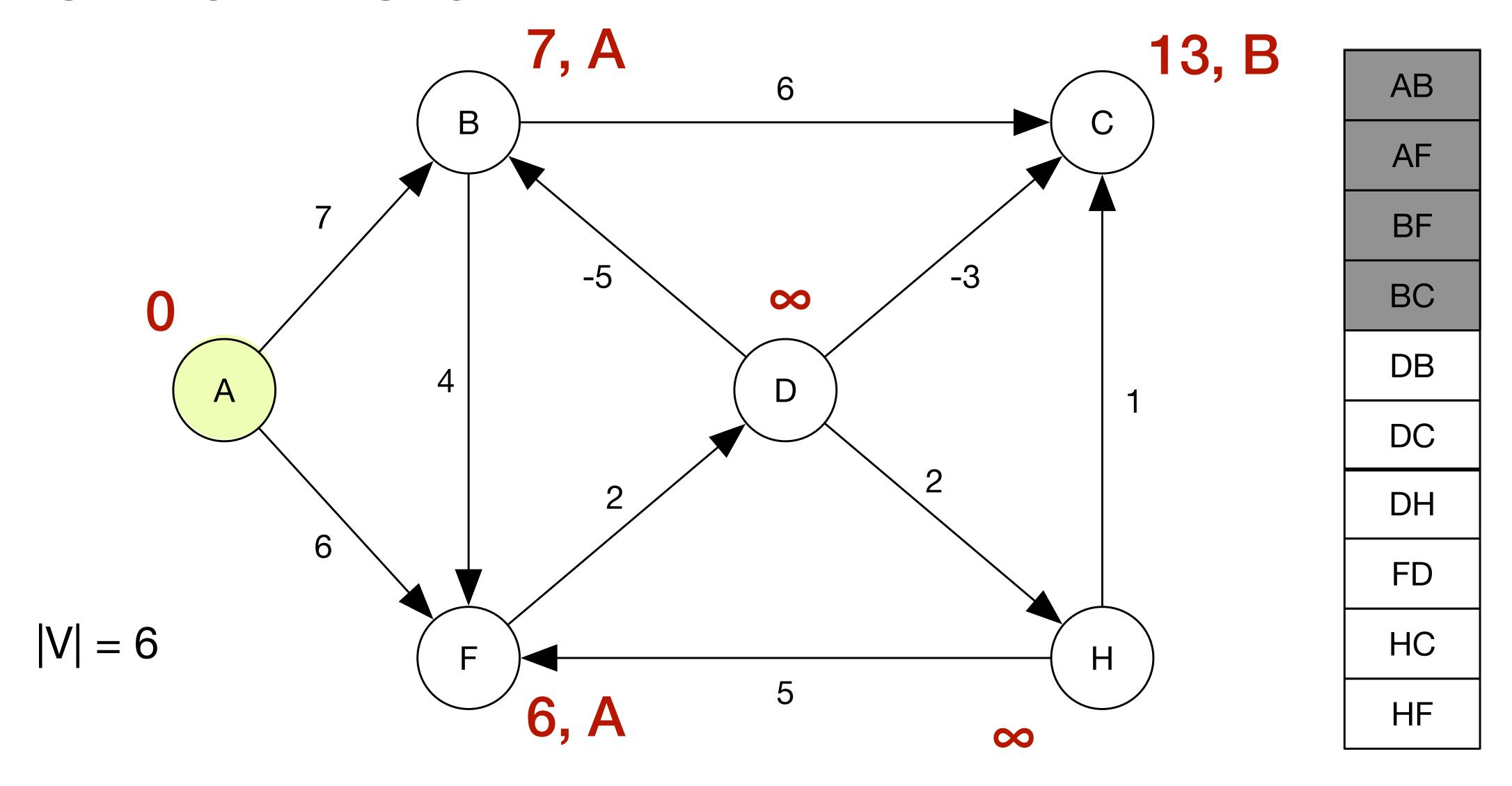
DB

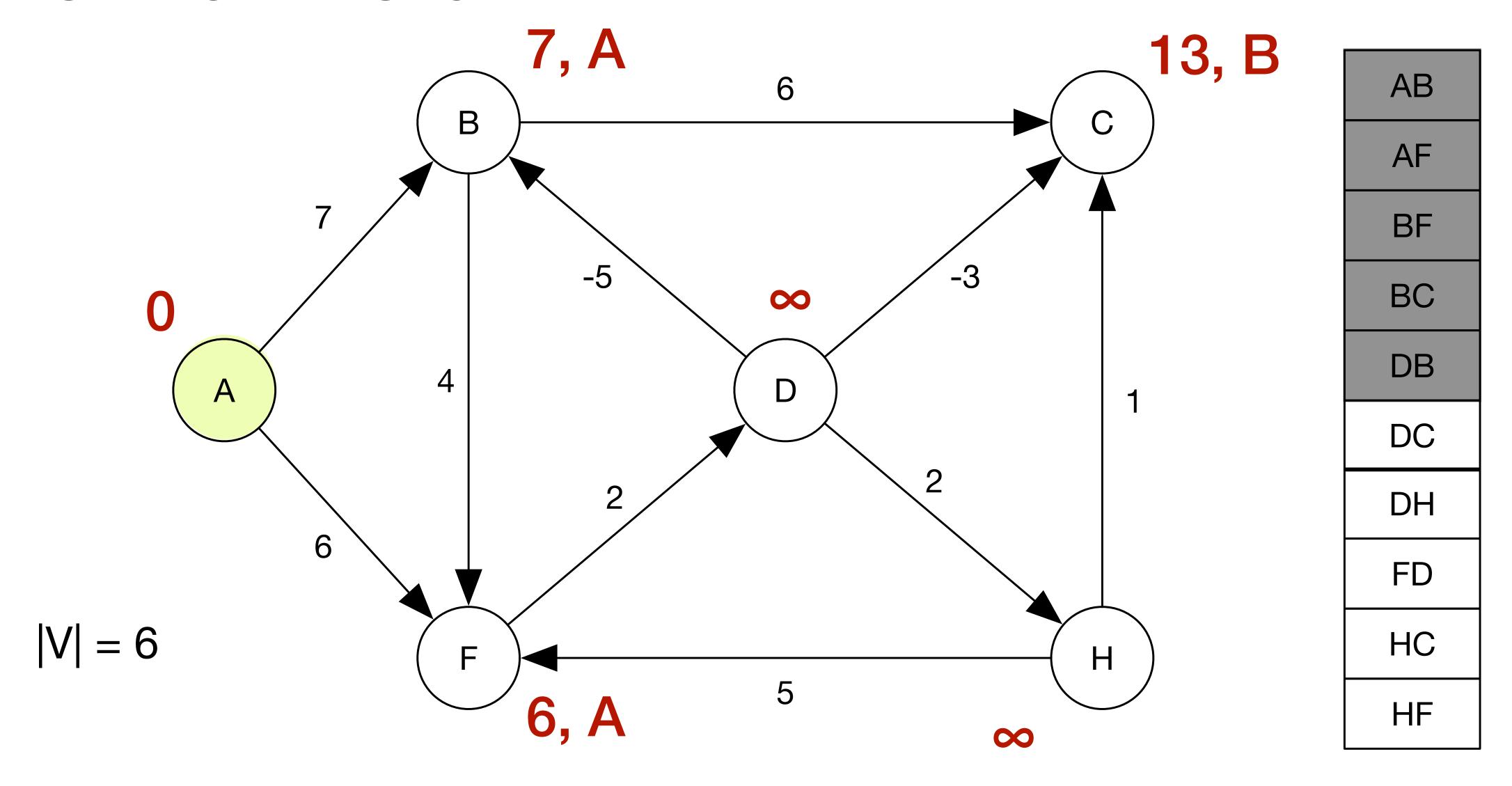
DC

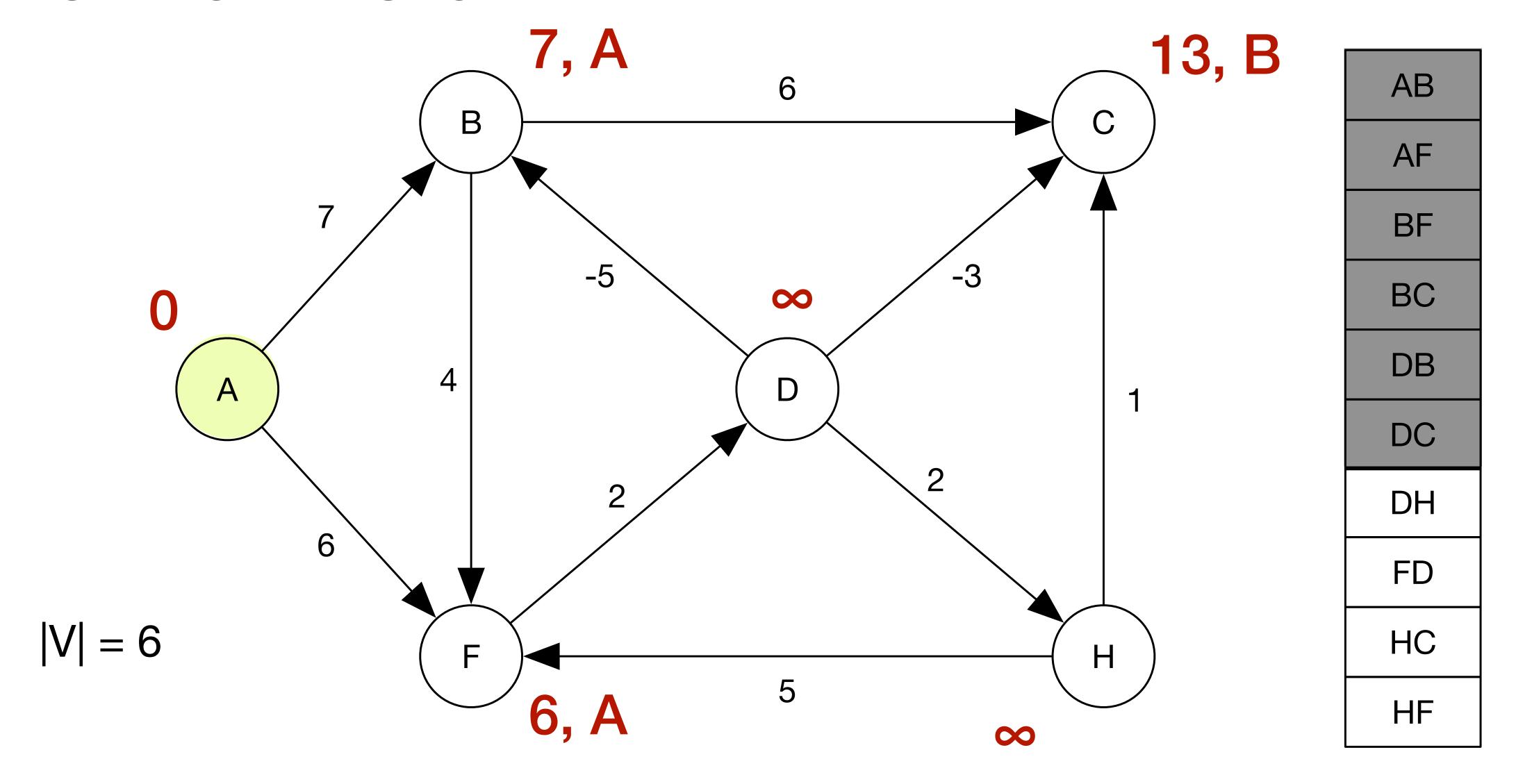
DH

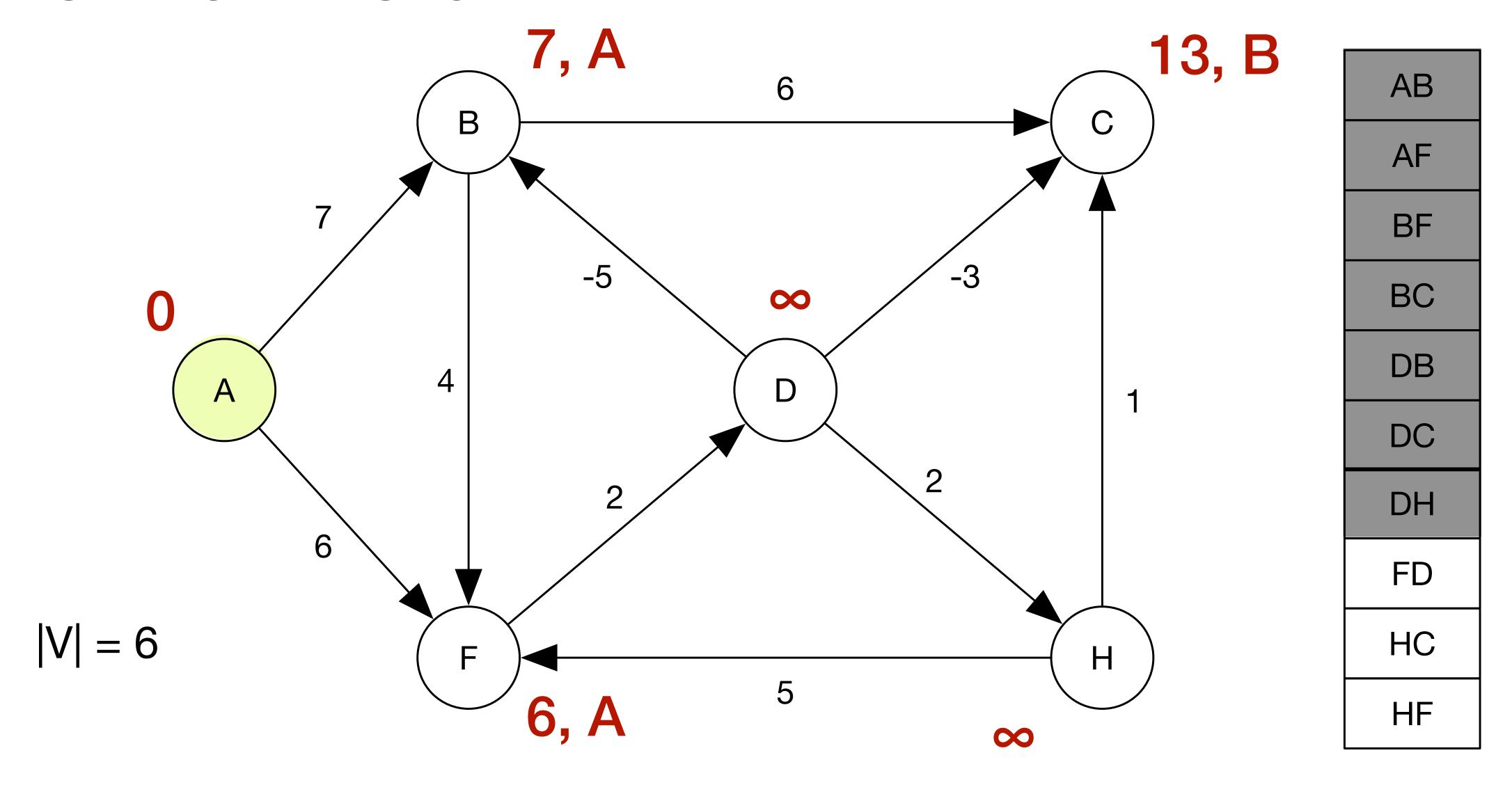
FD

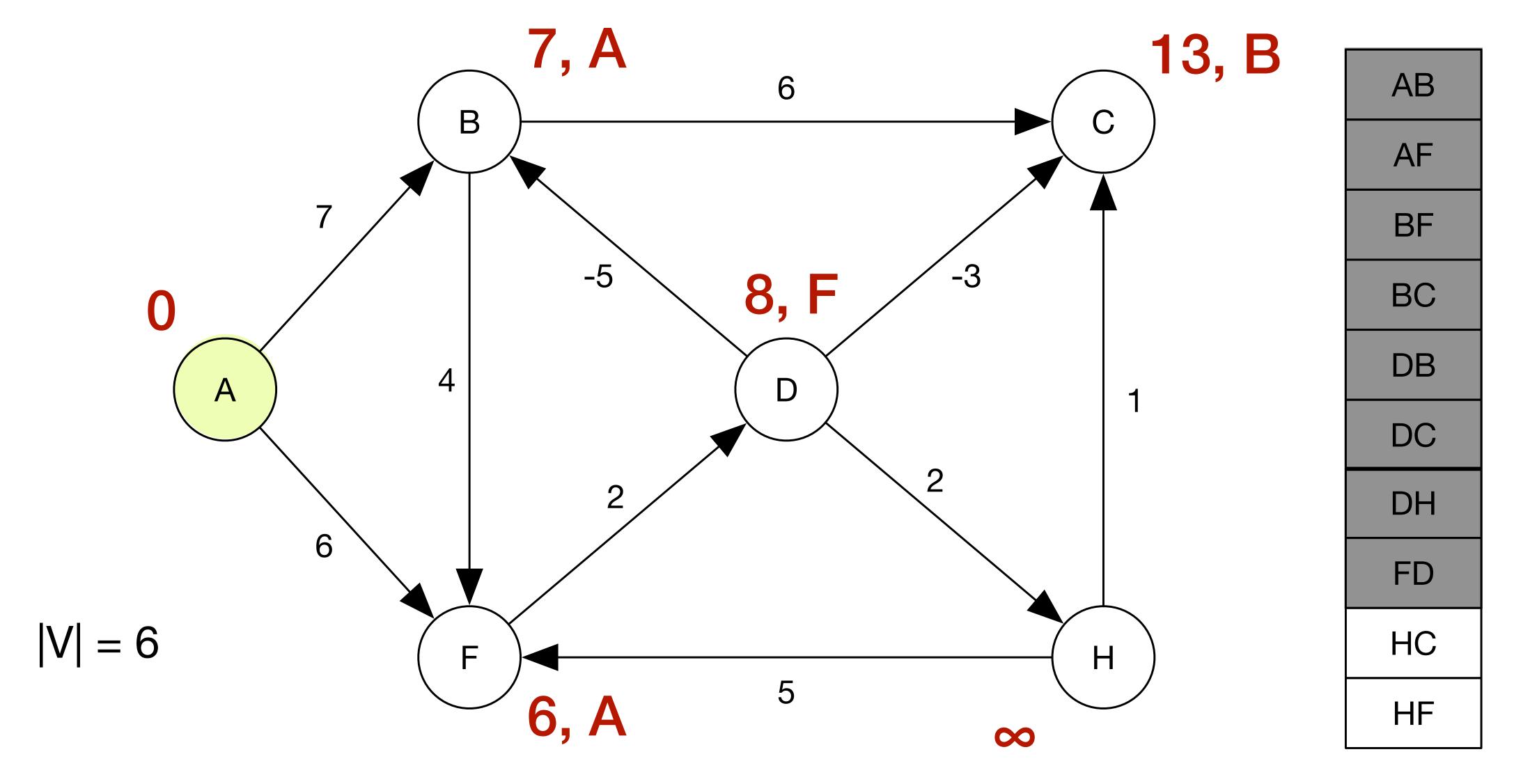
HC

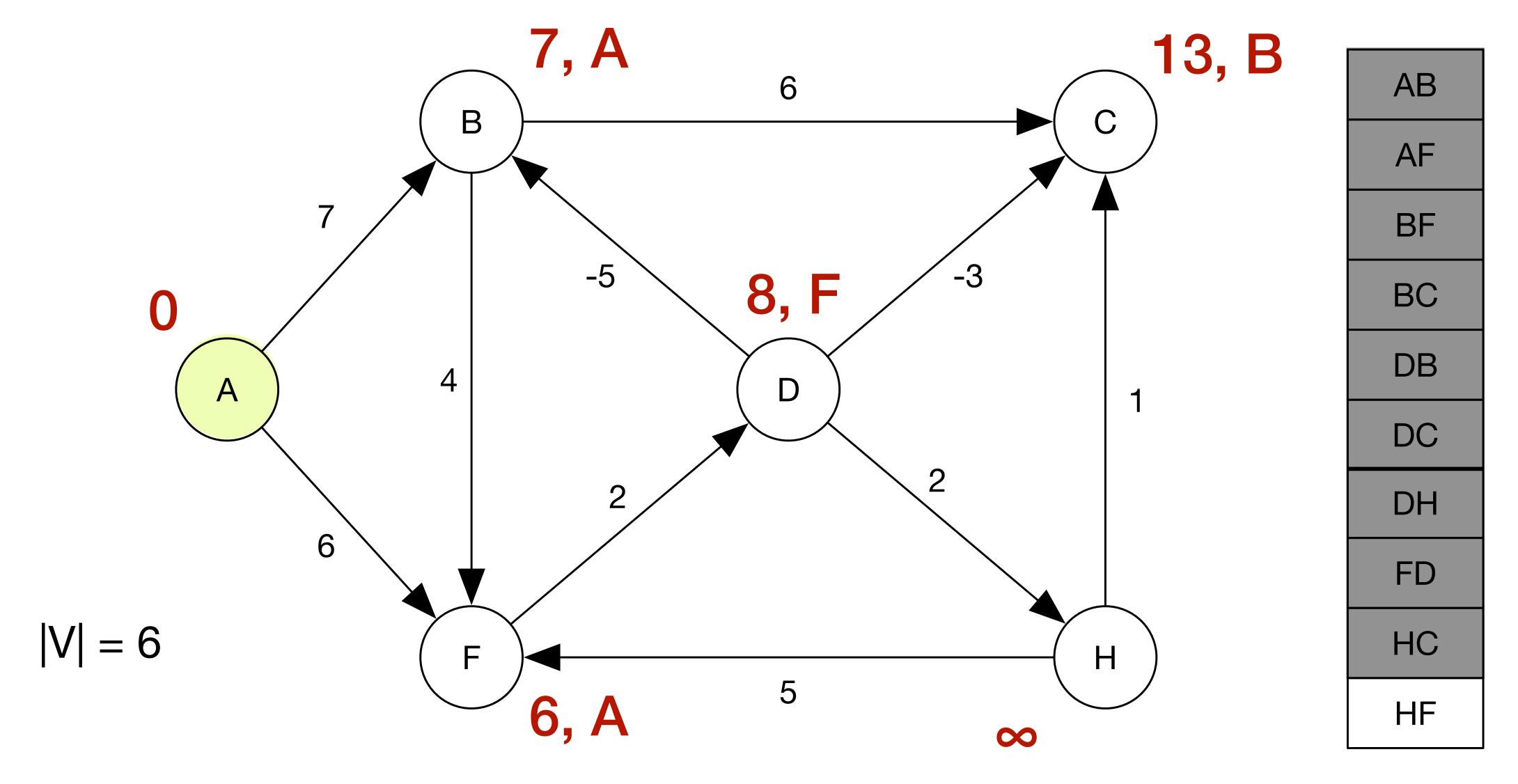


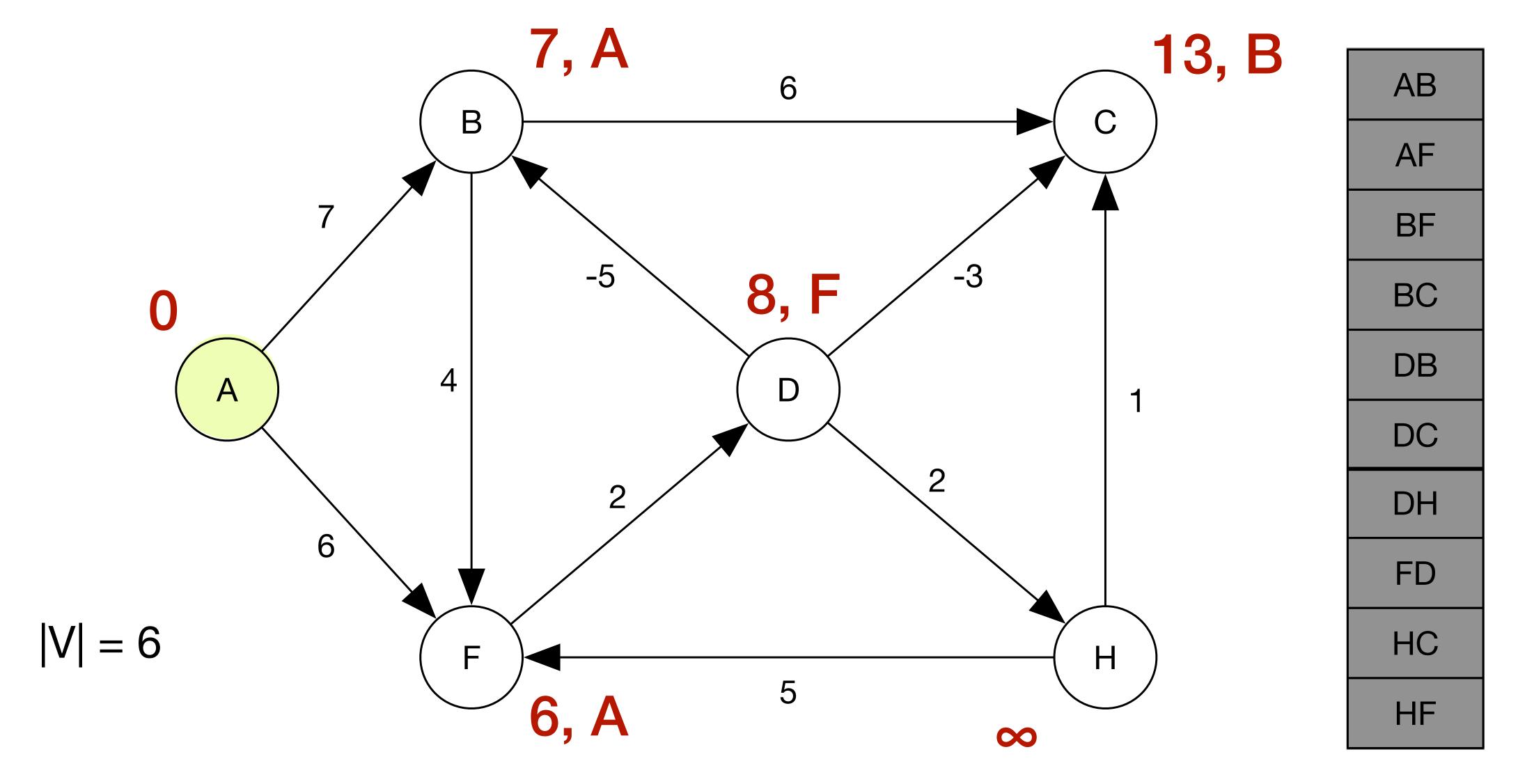


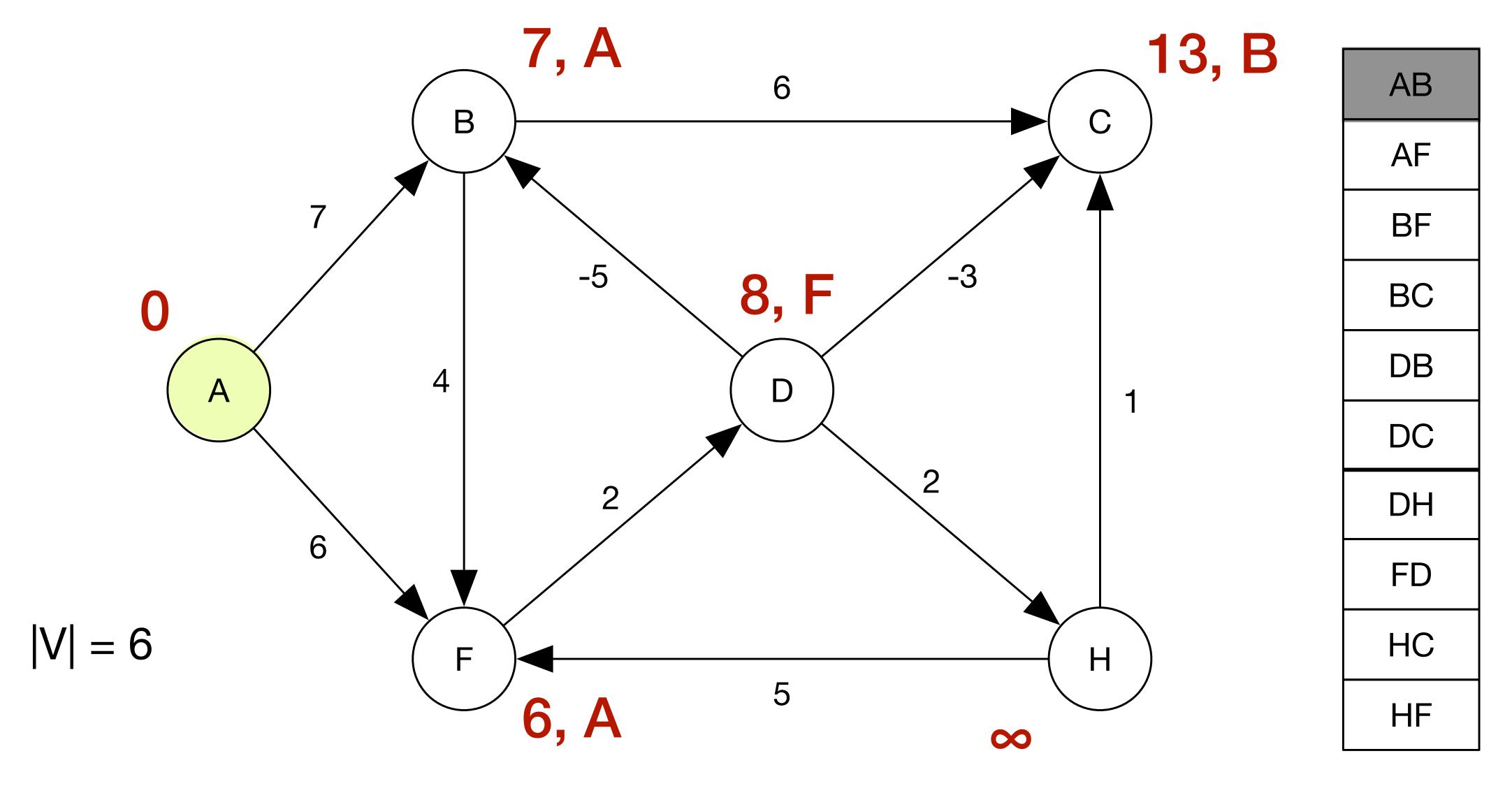


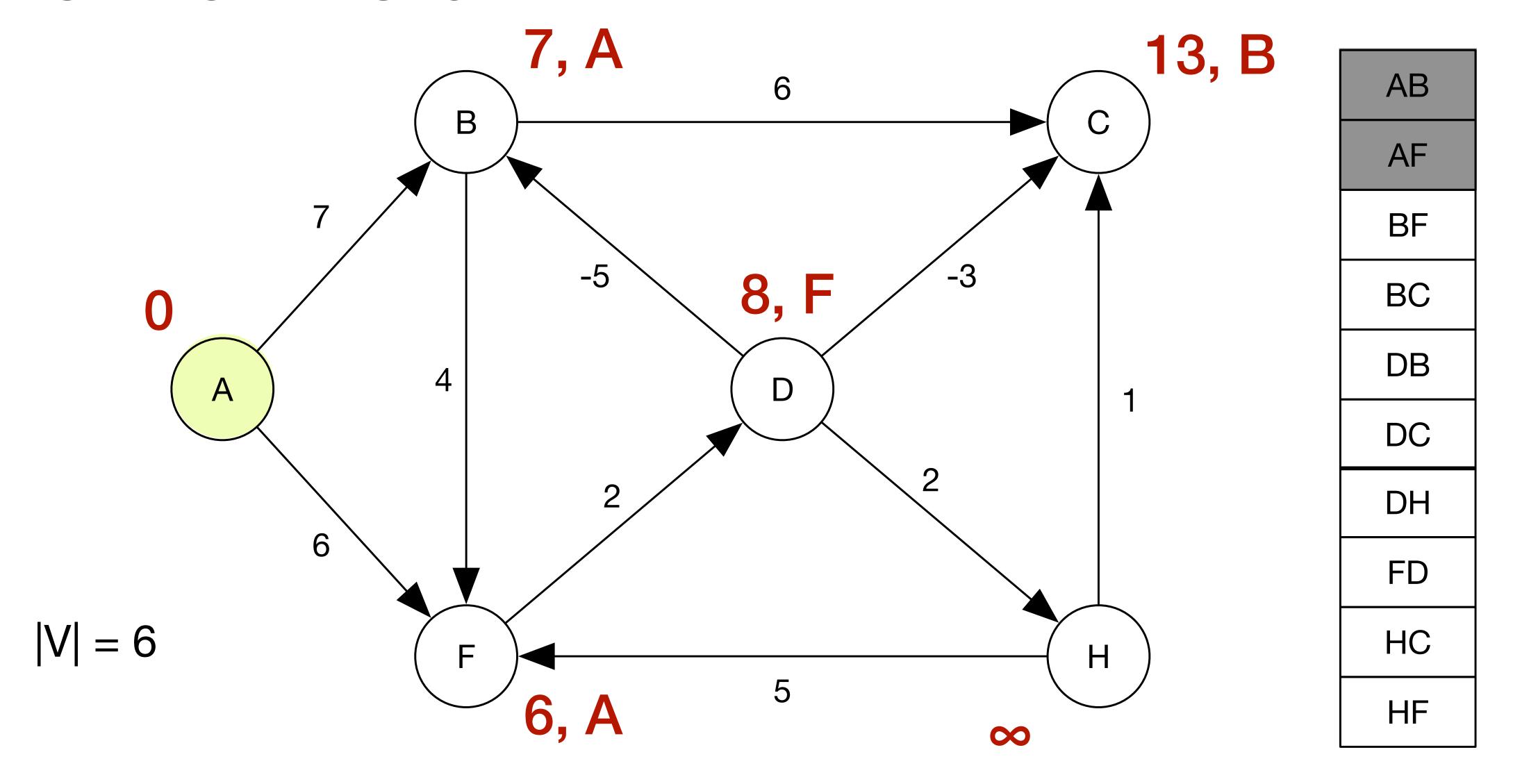


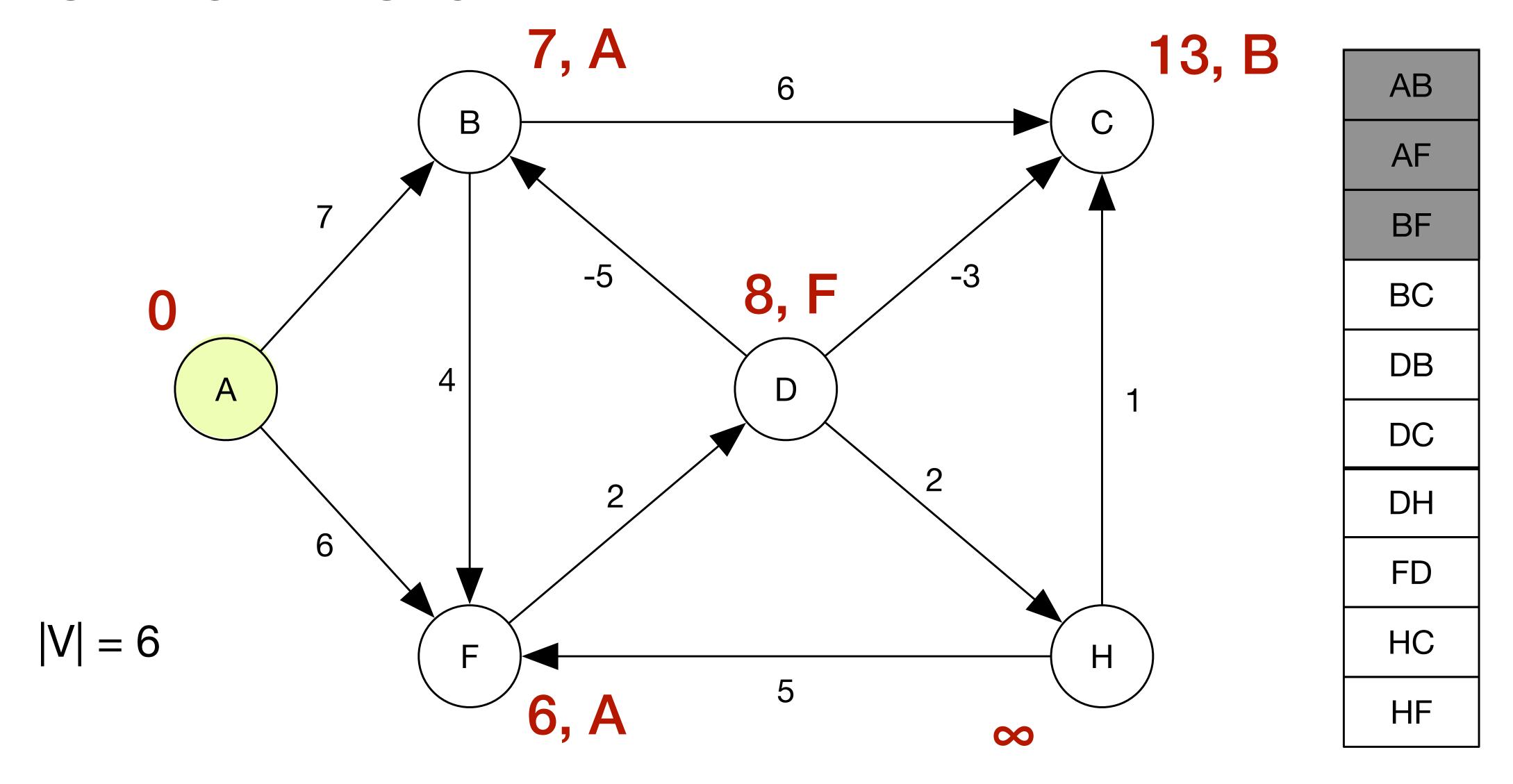


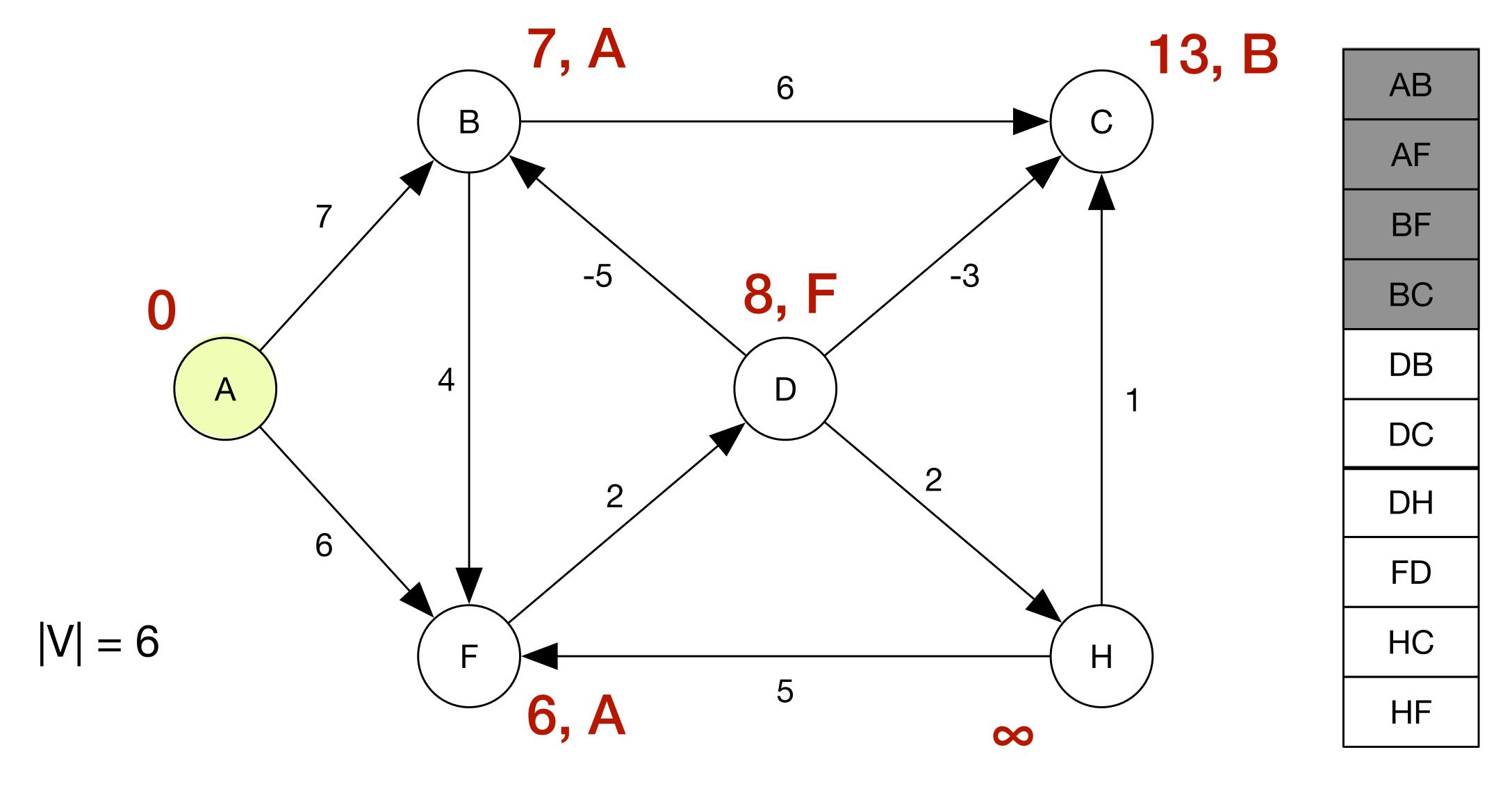


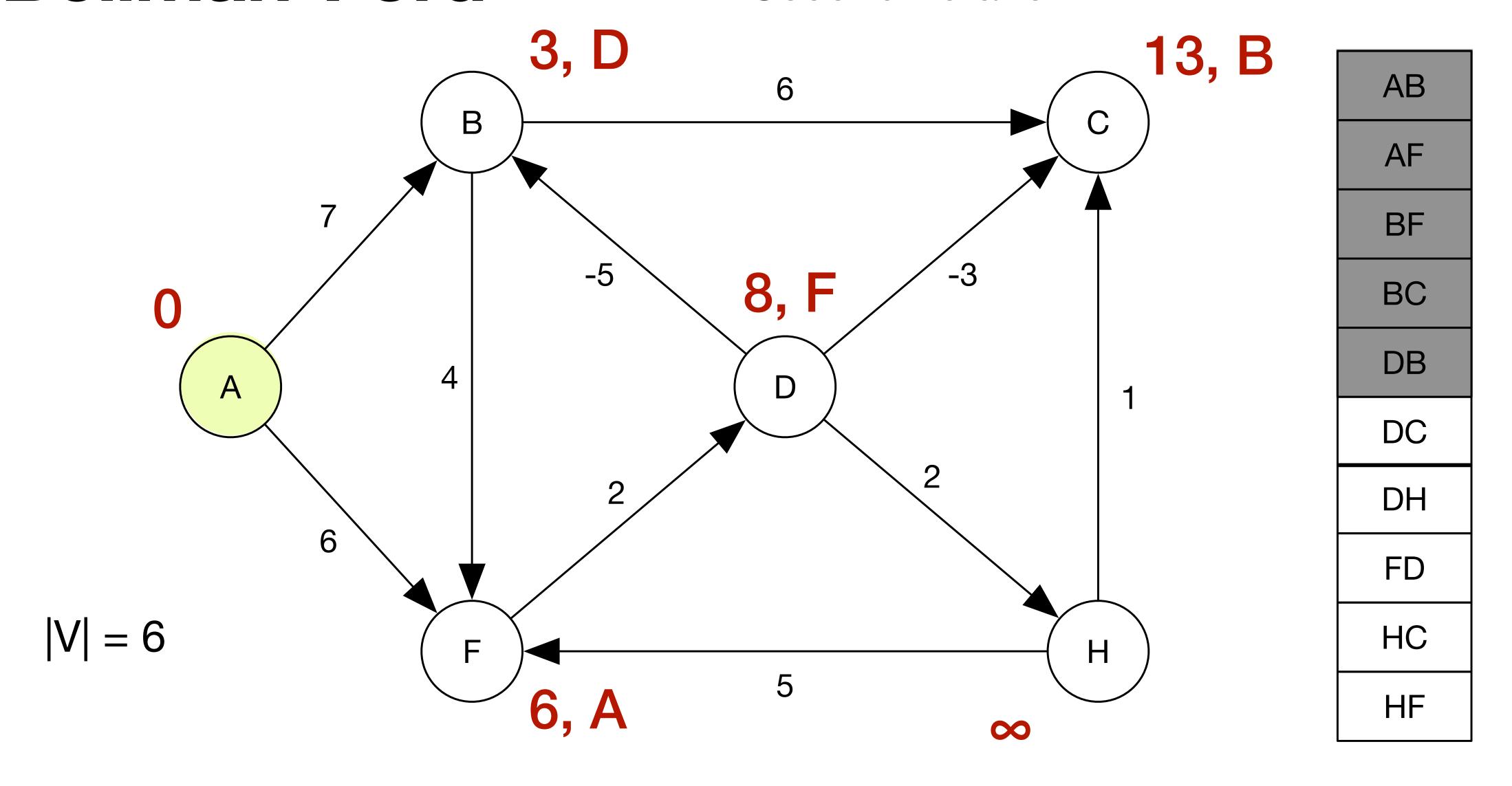


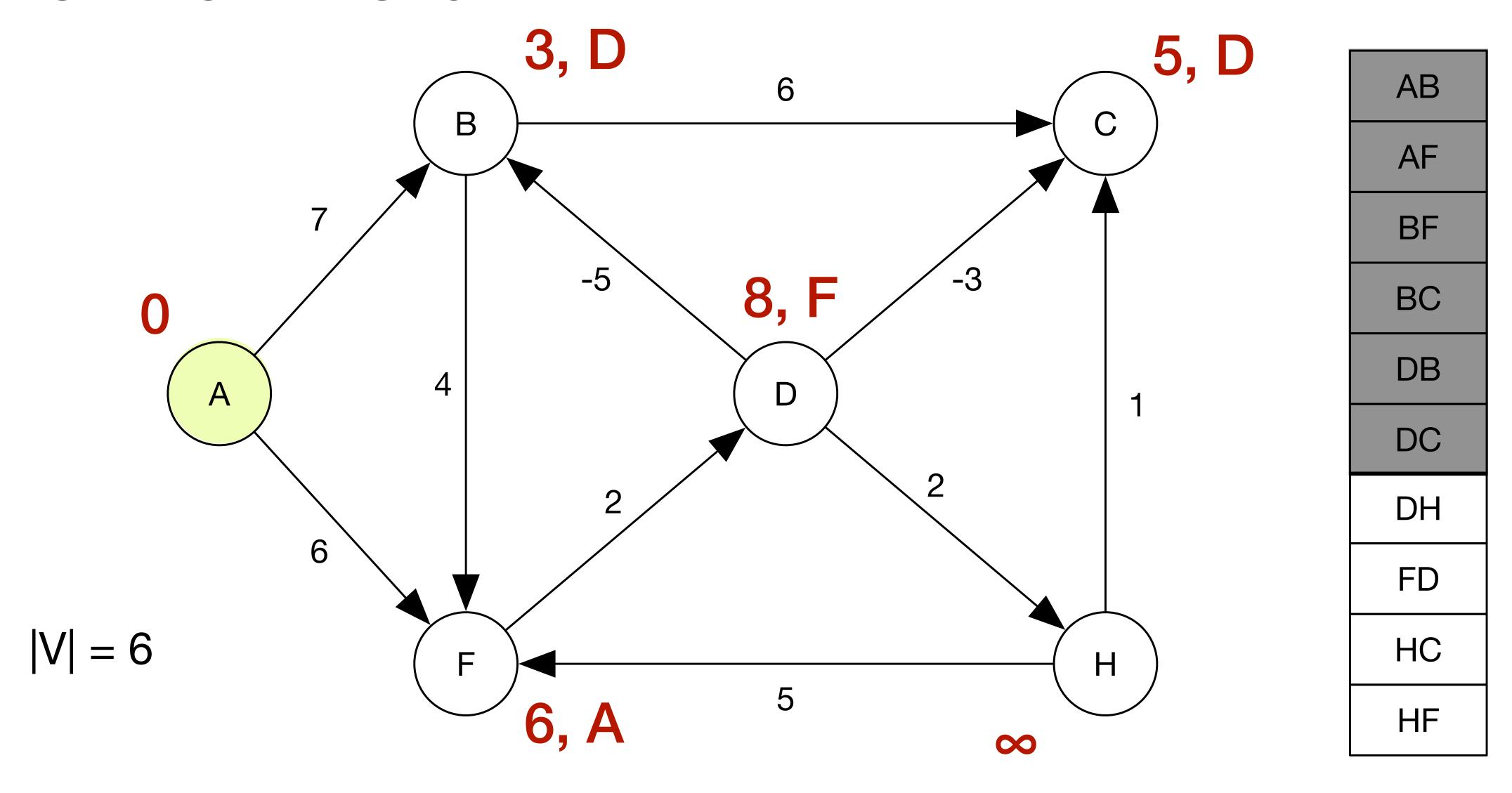


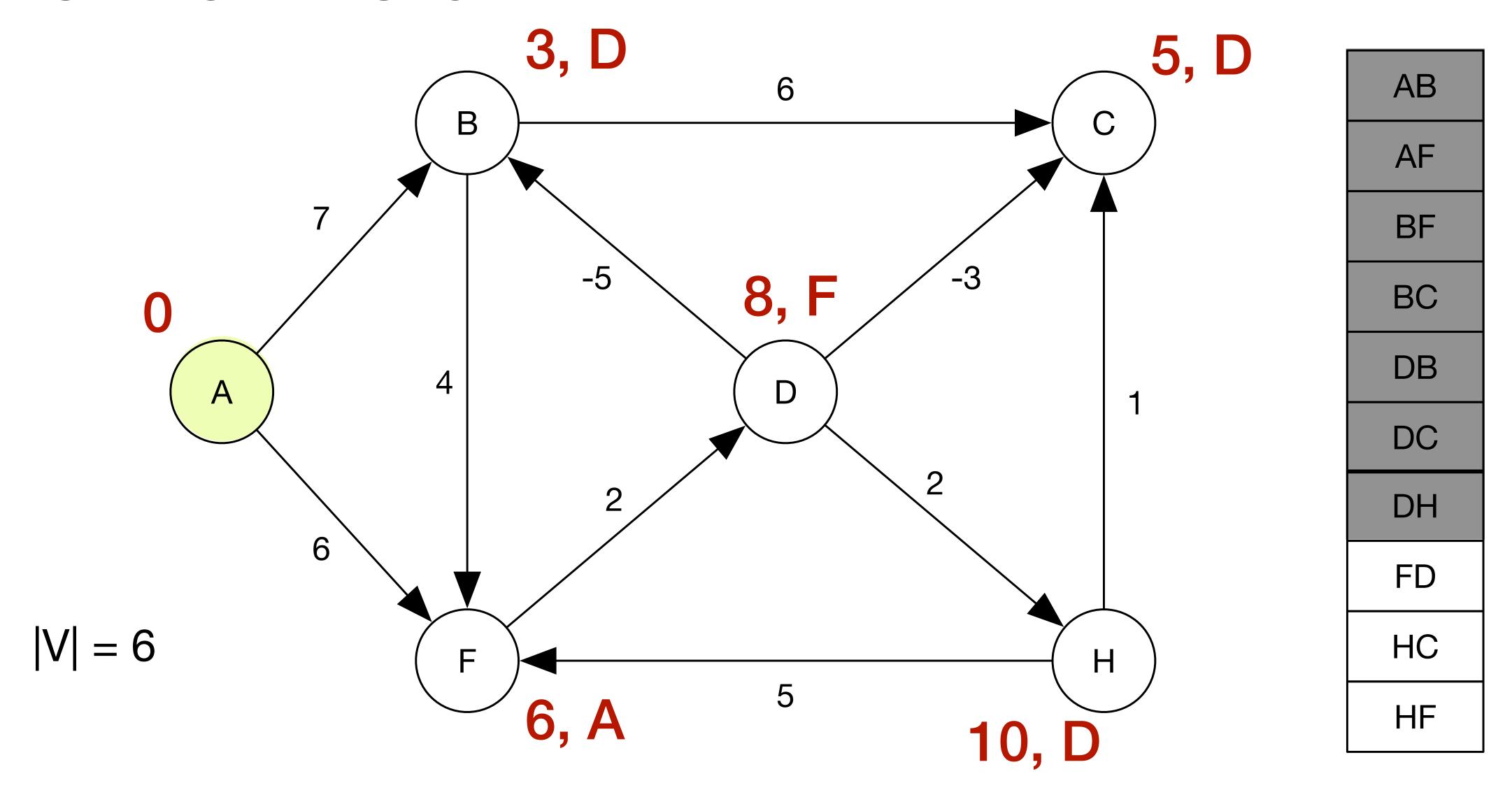


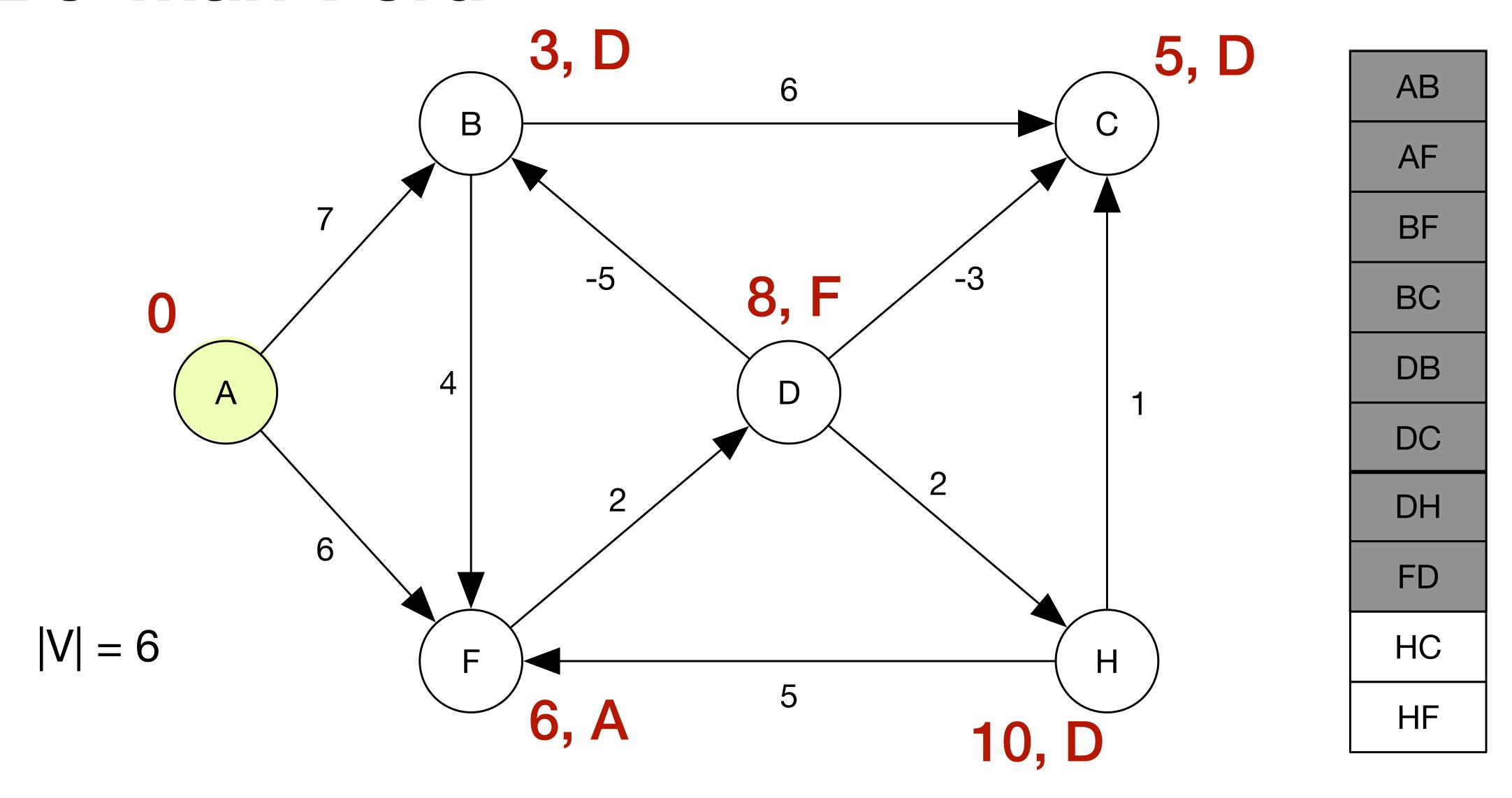




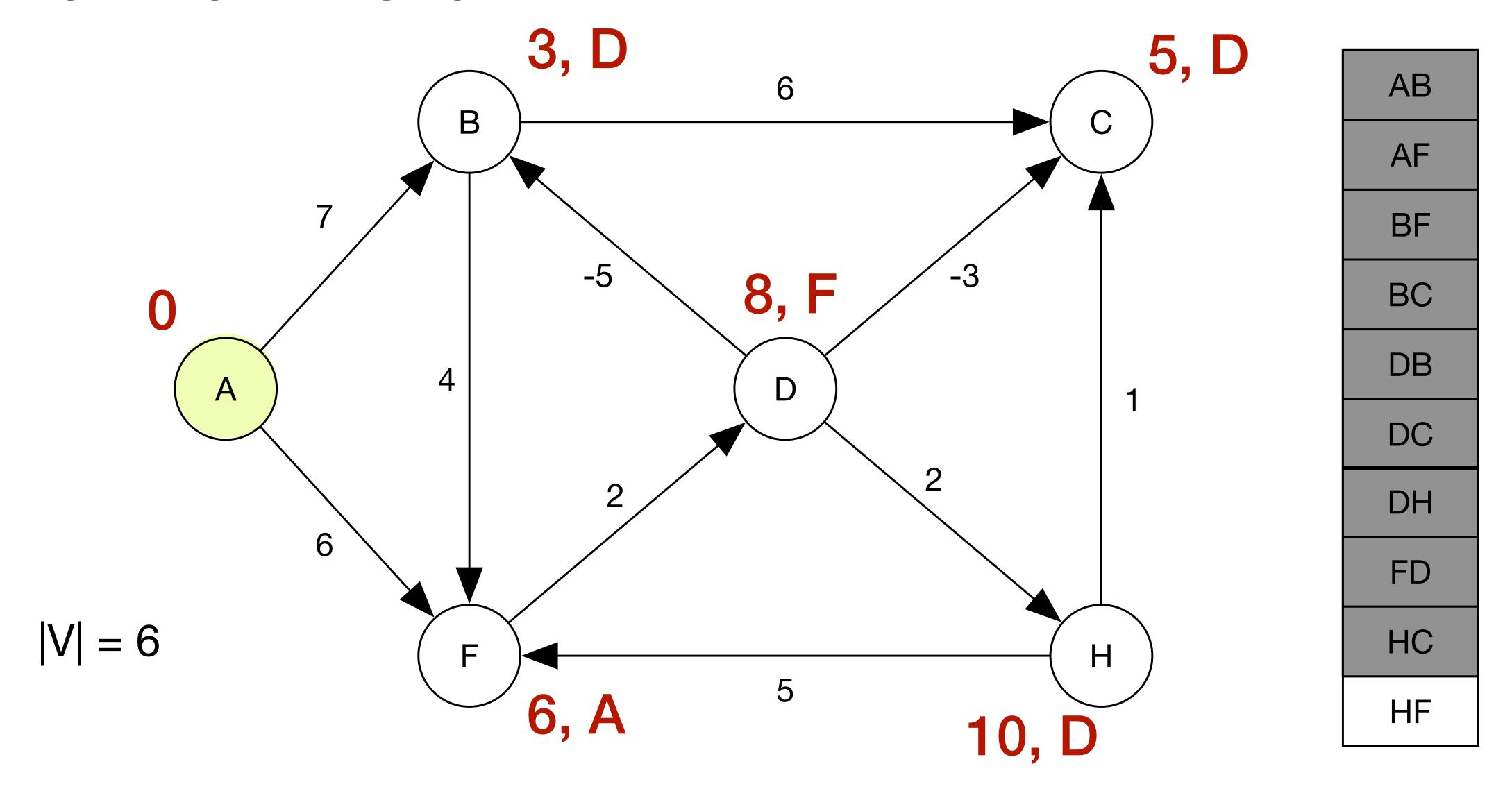




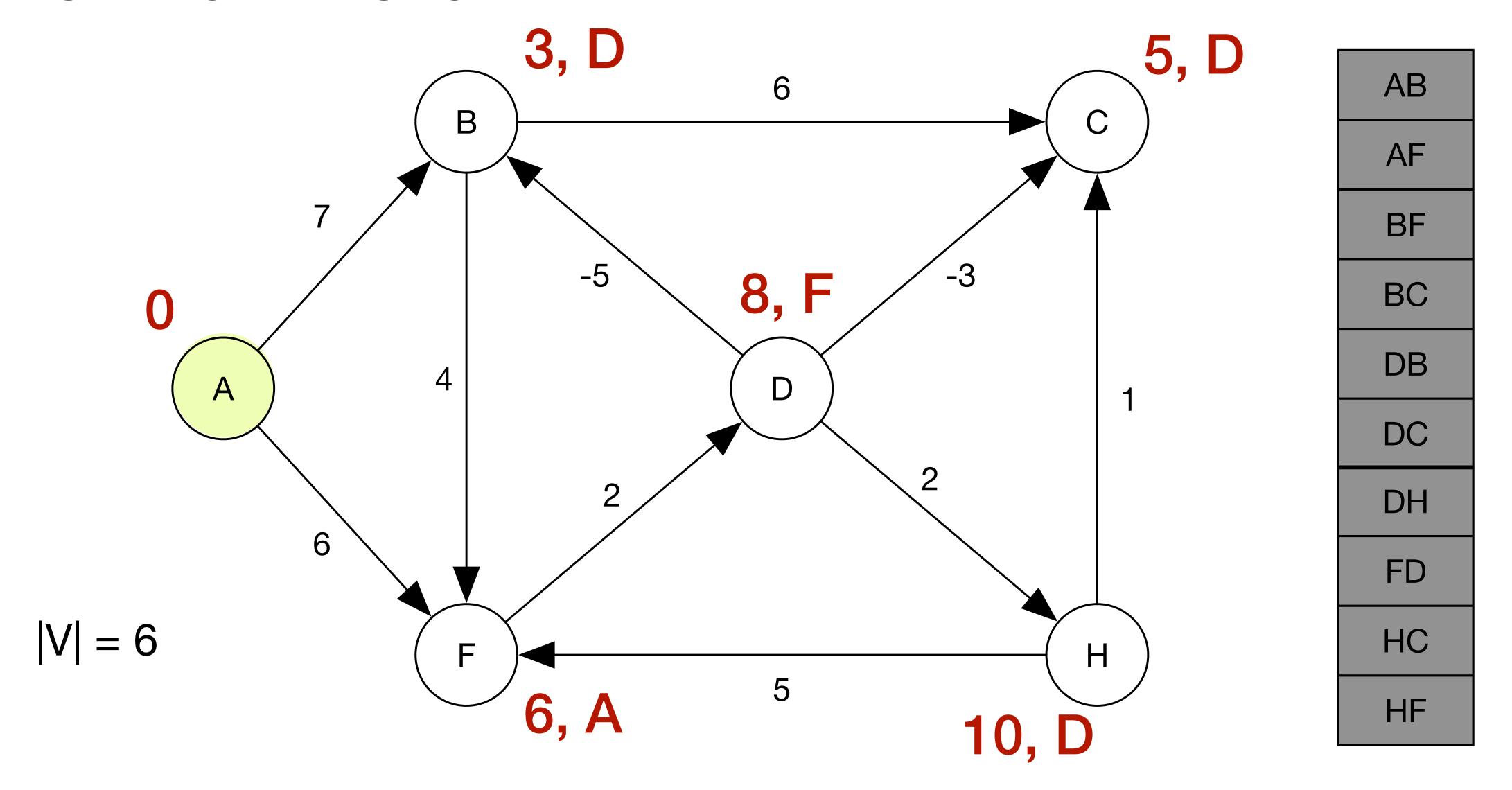


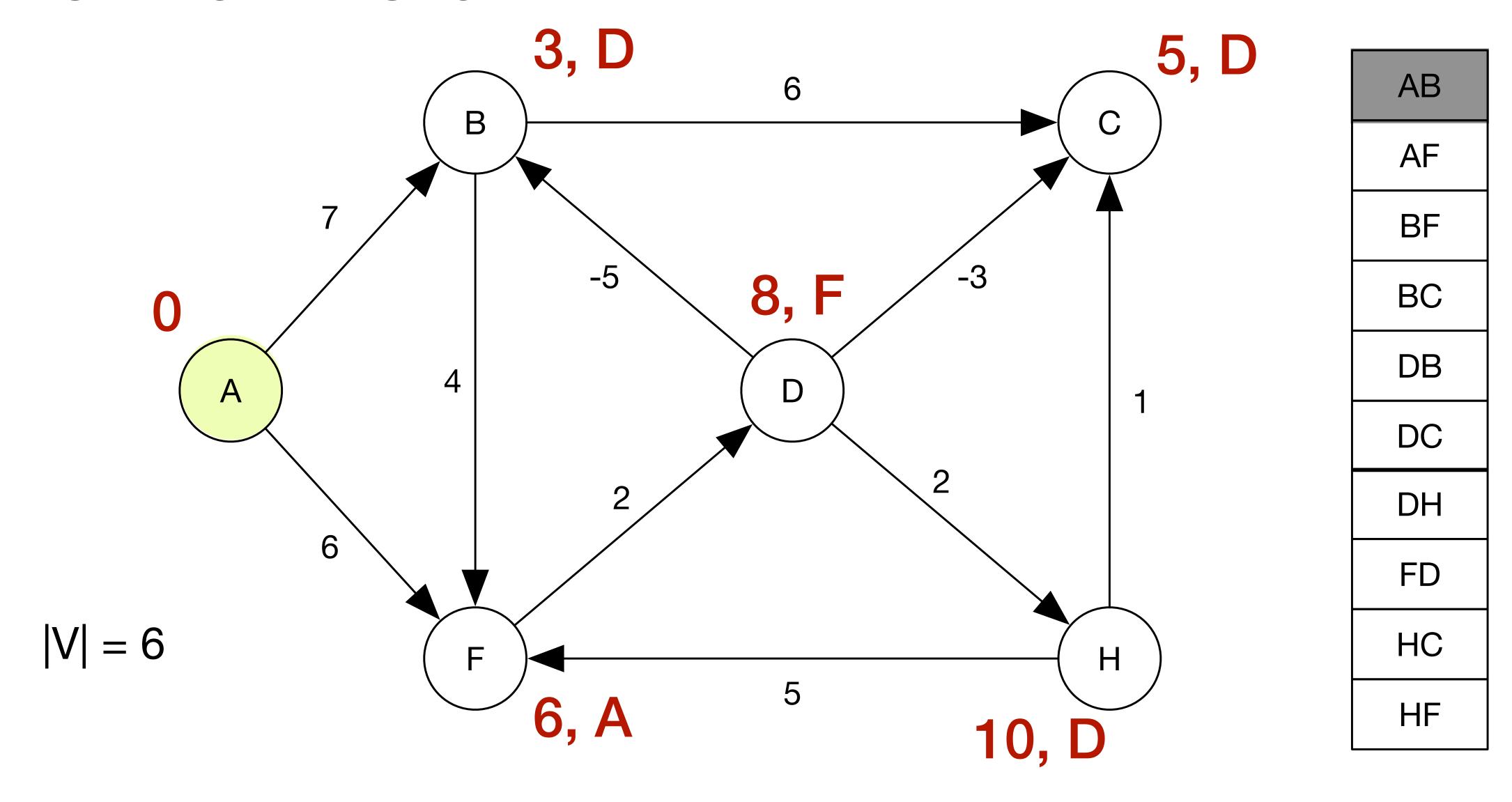


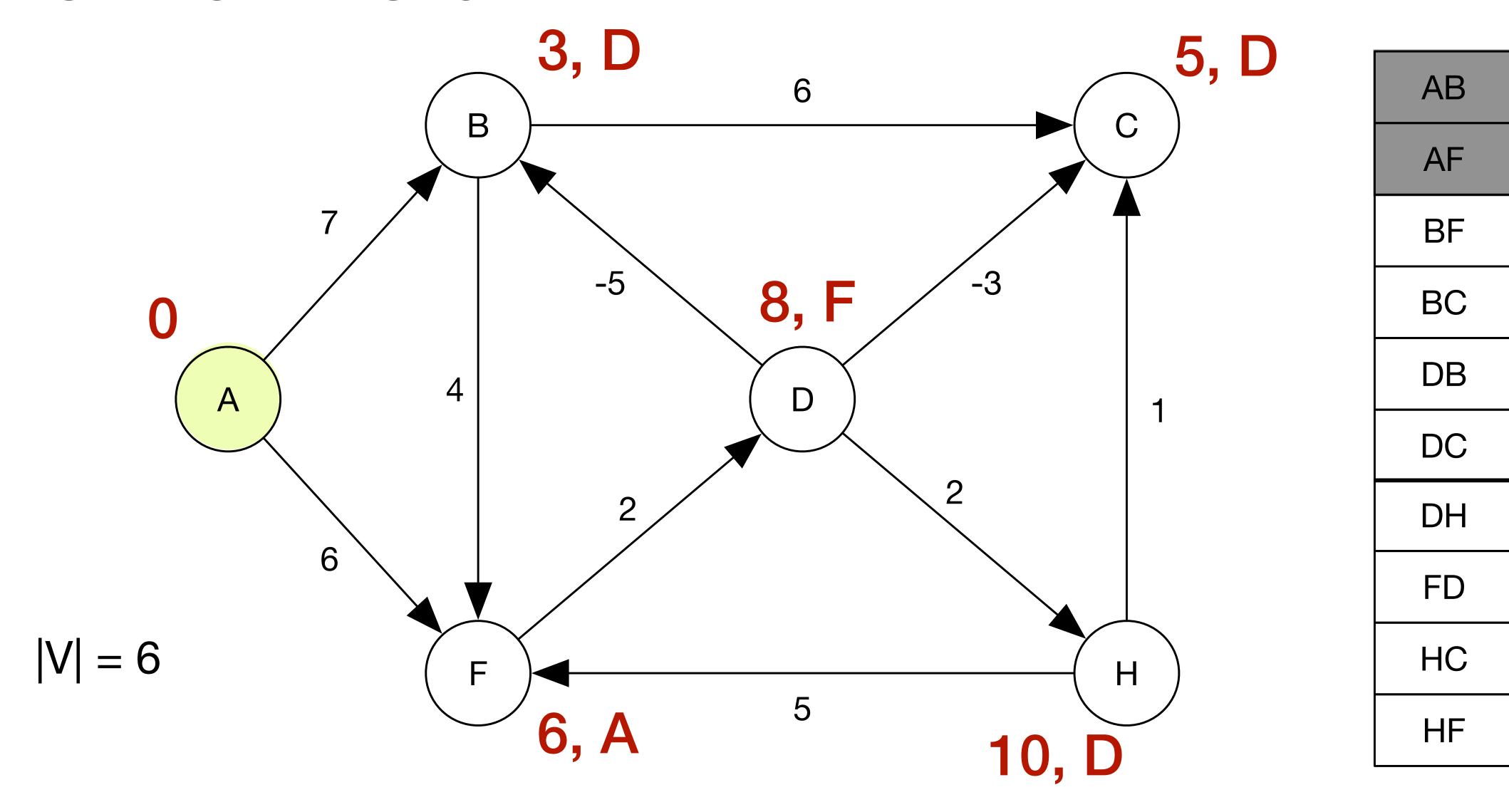
#### Second iteration

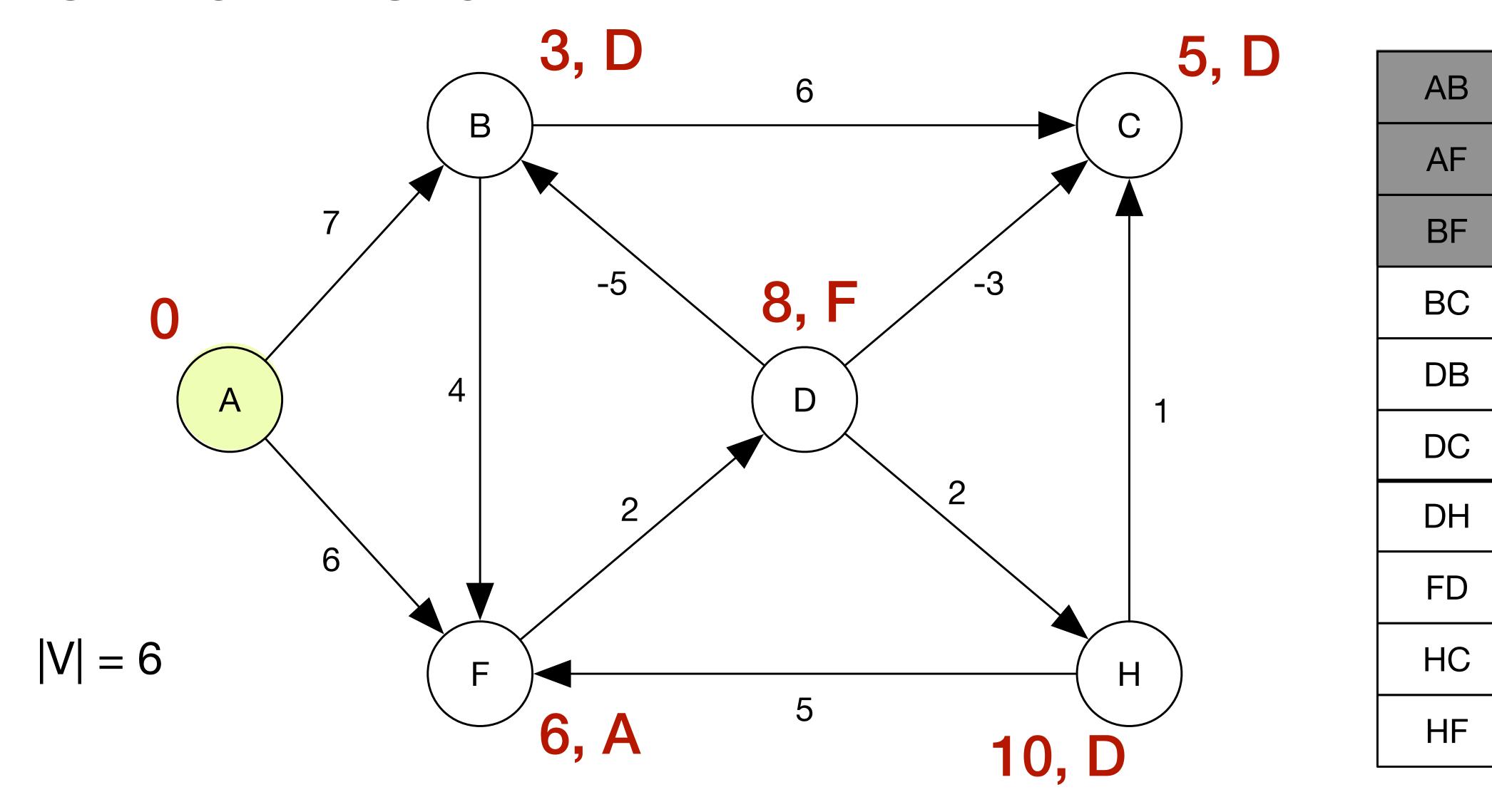


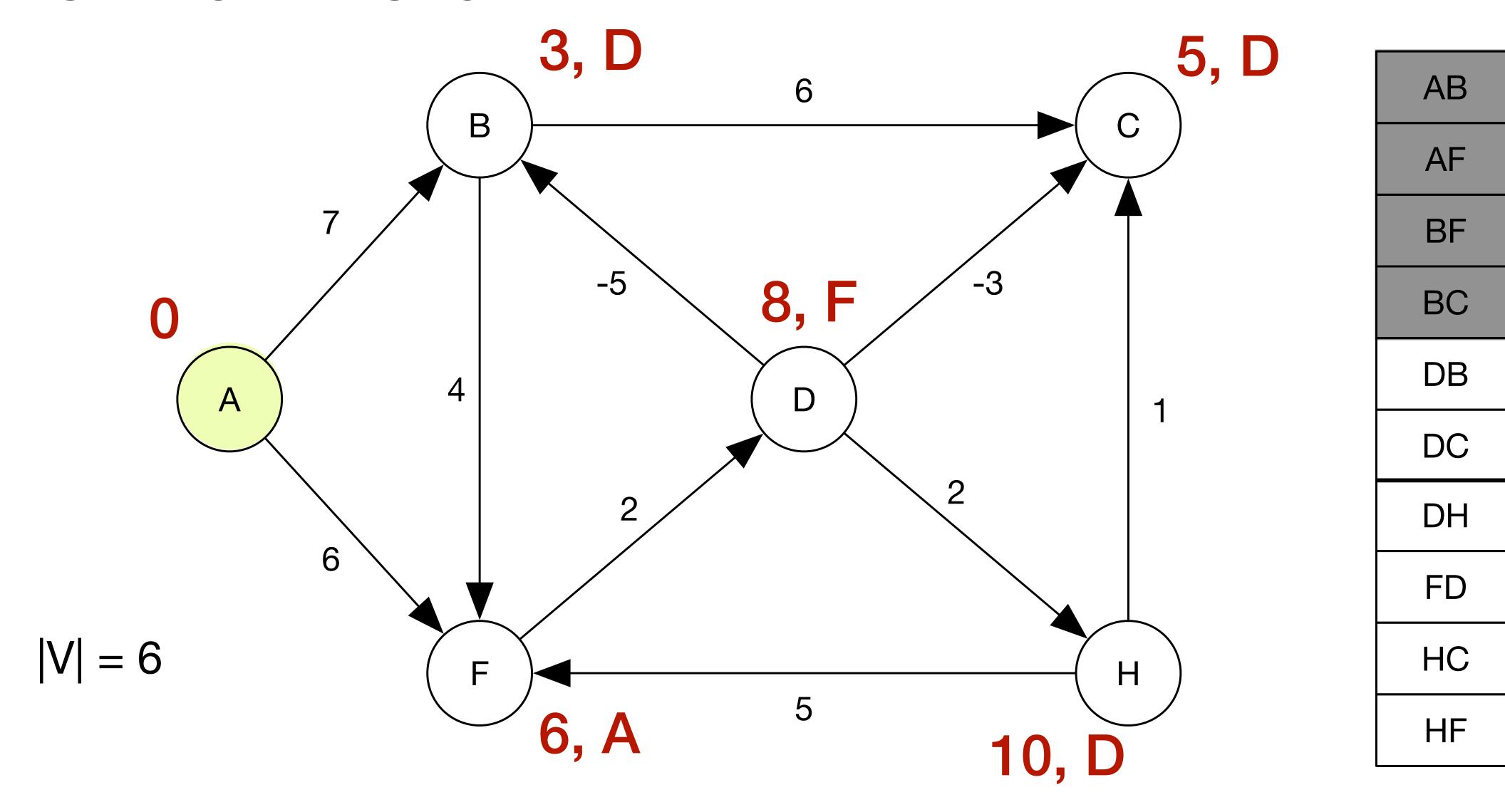
#### Second iteration

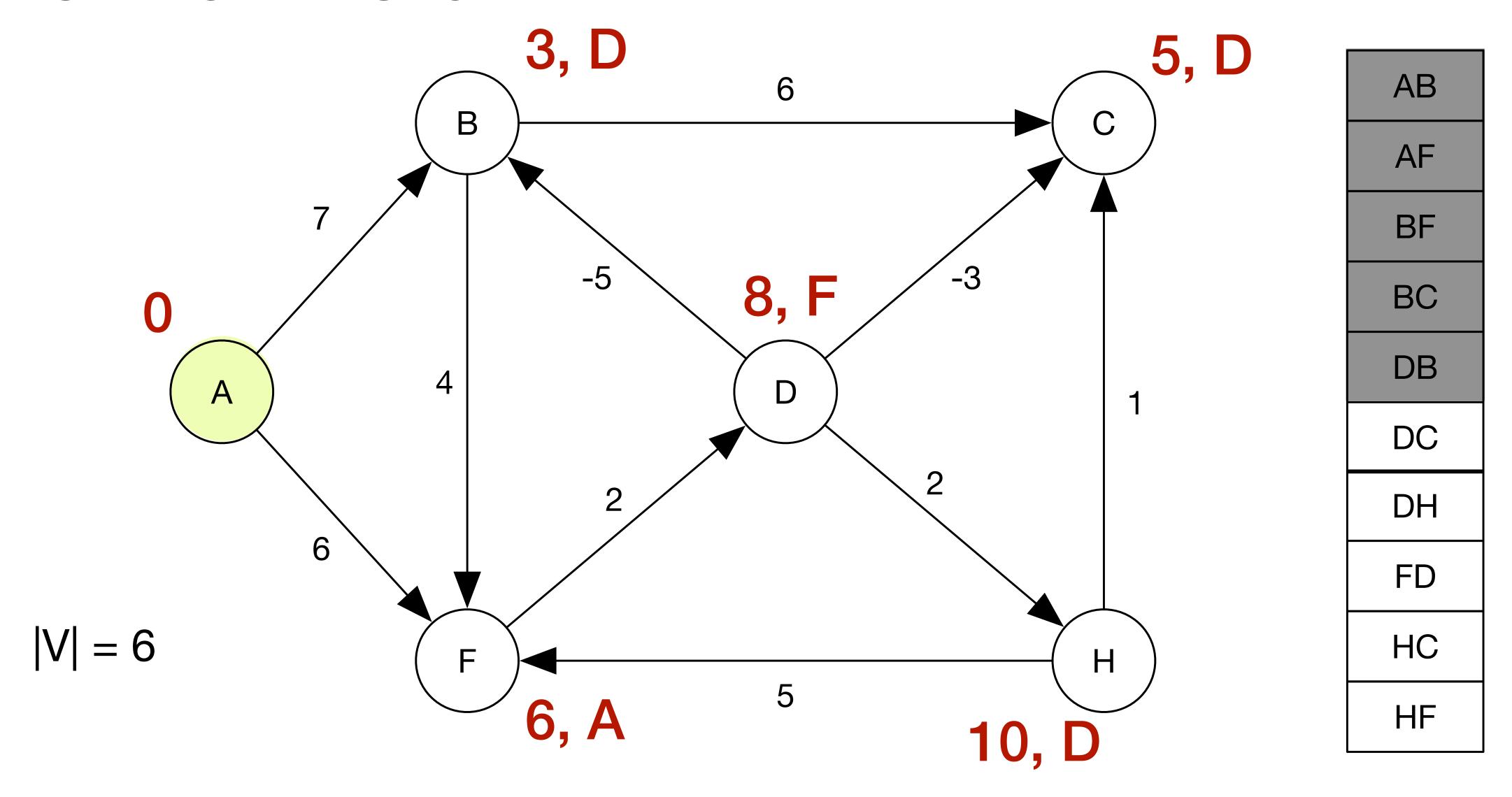


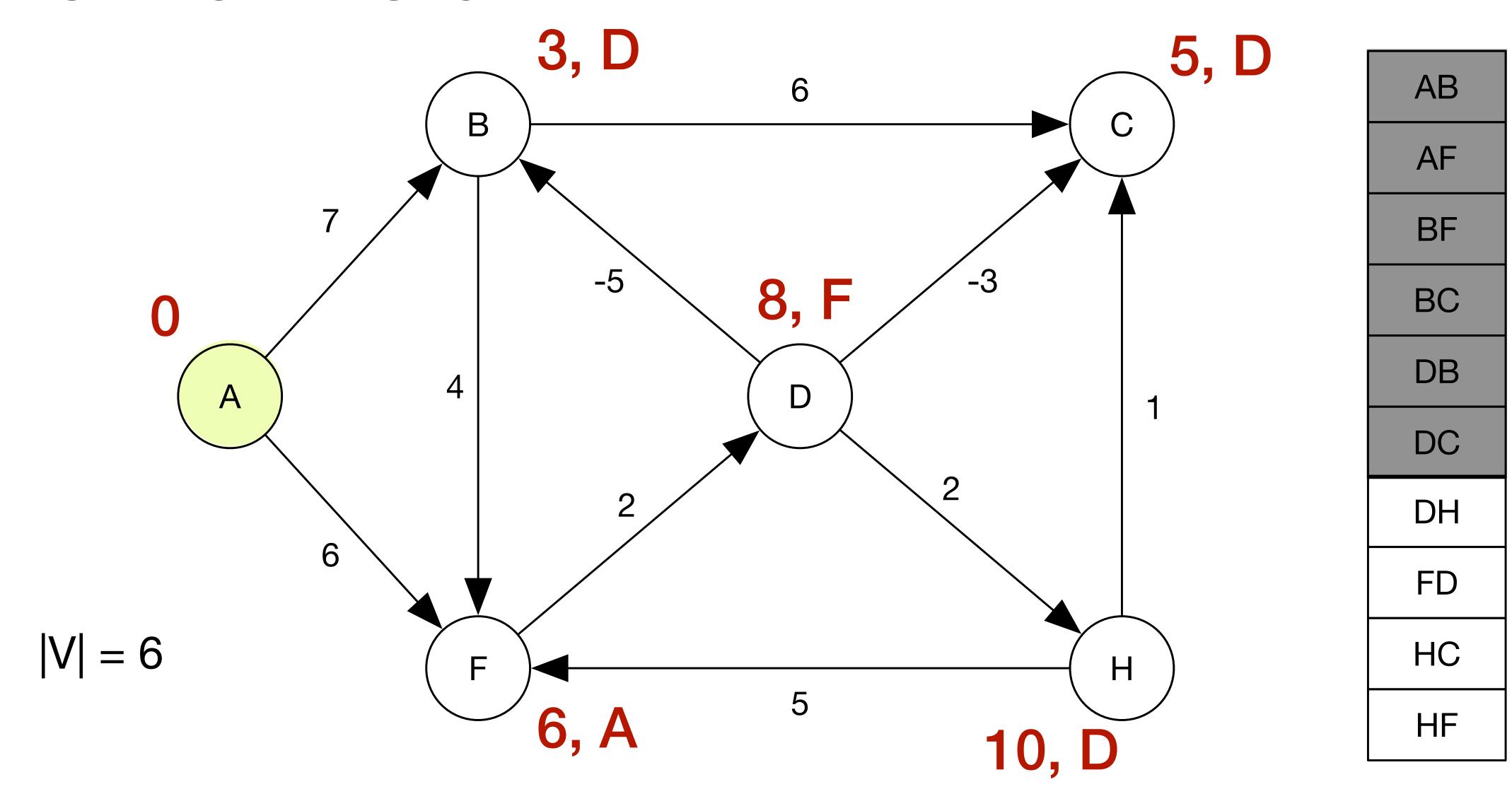




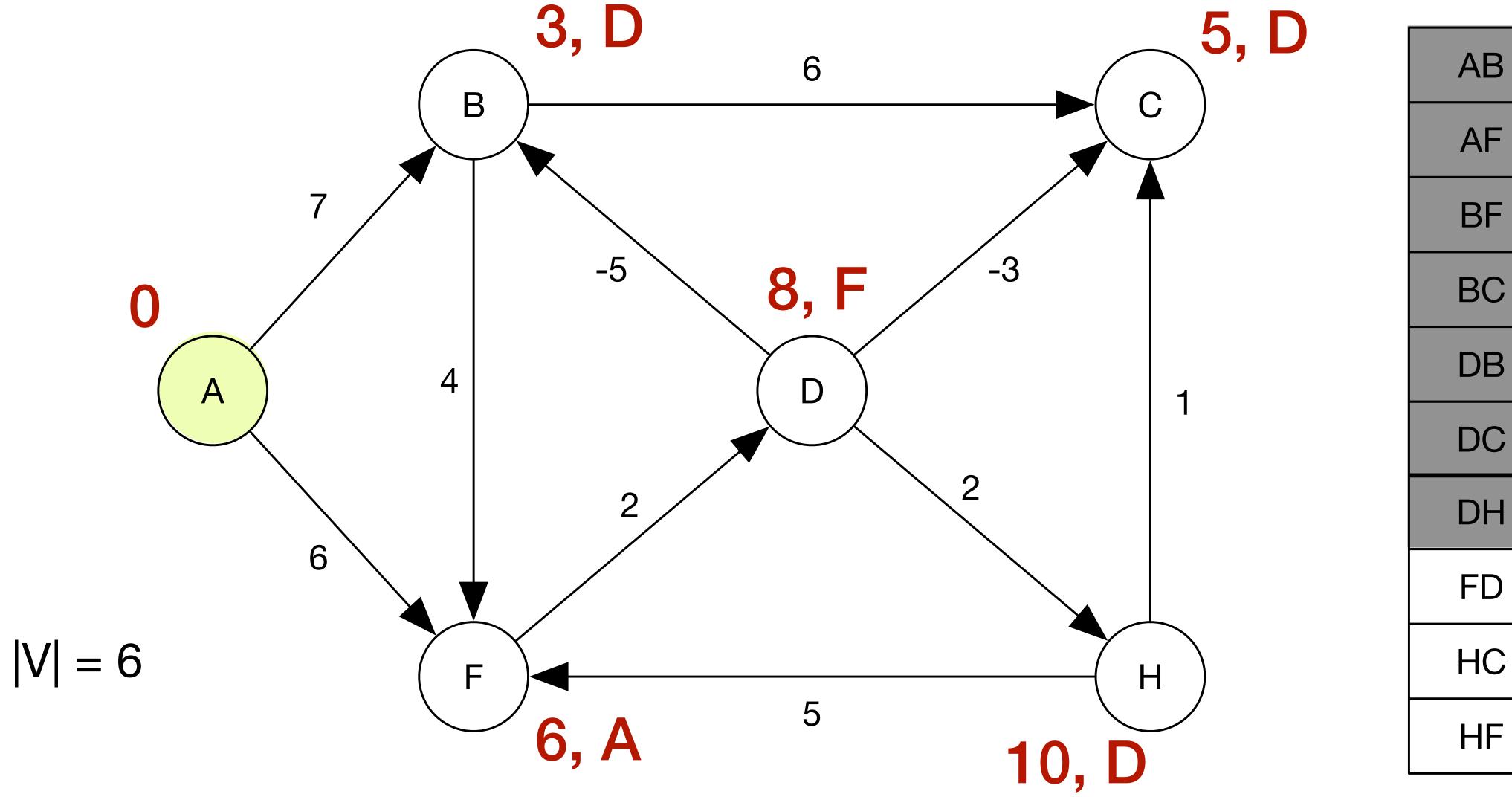






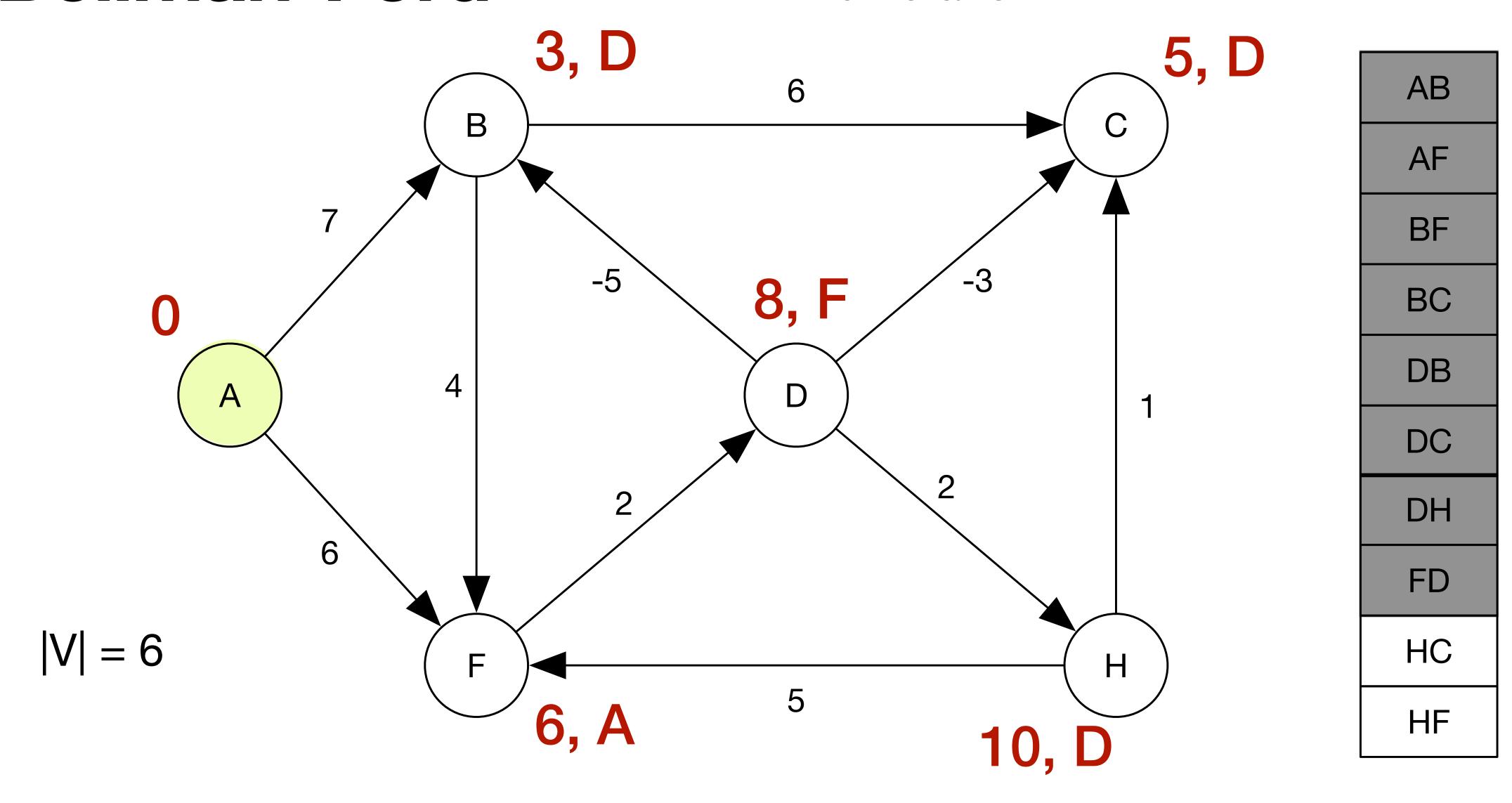


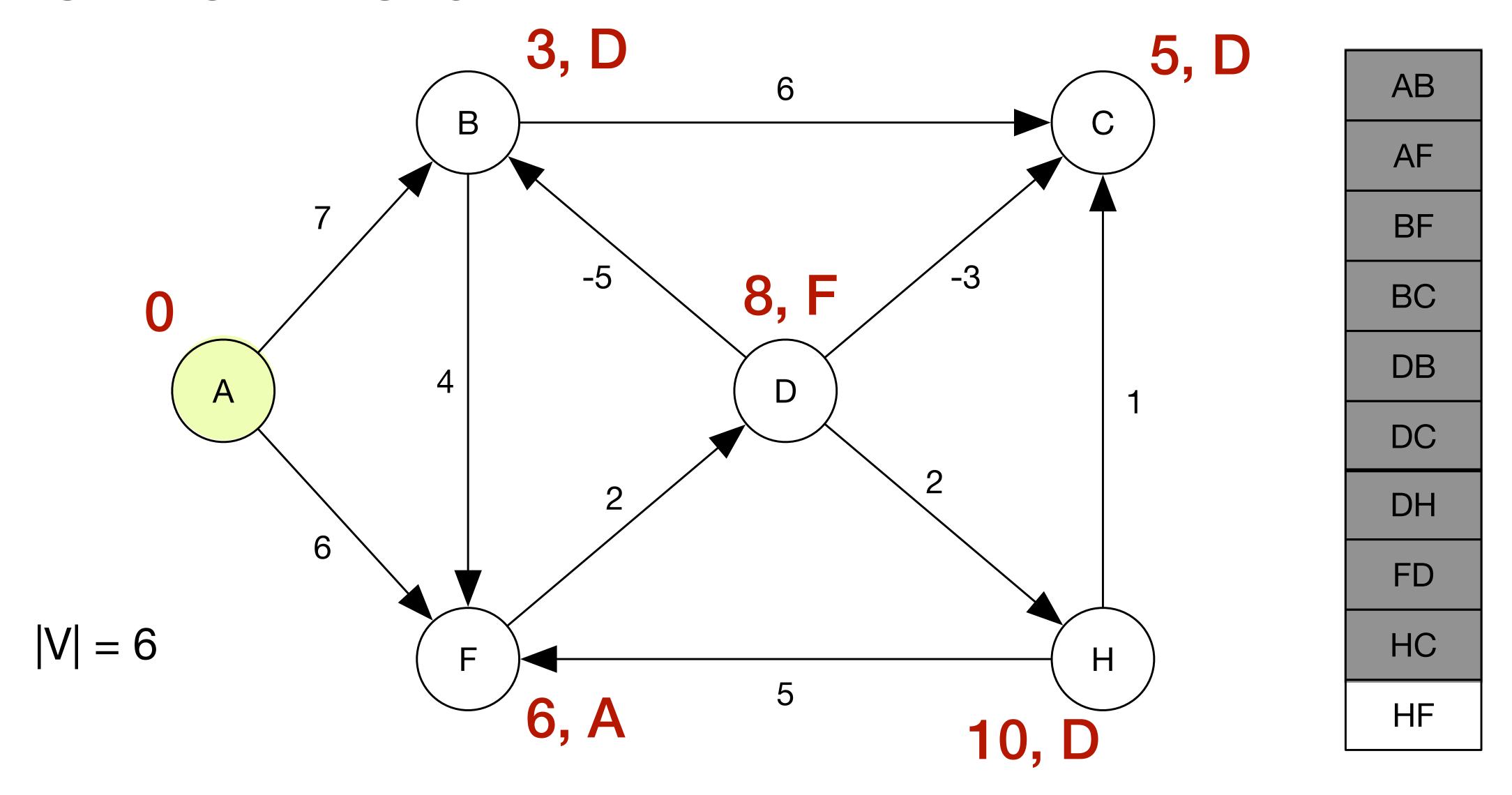
#### Third iteration

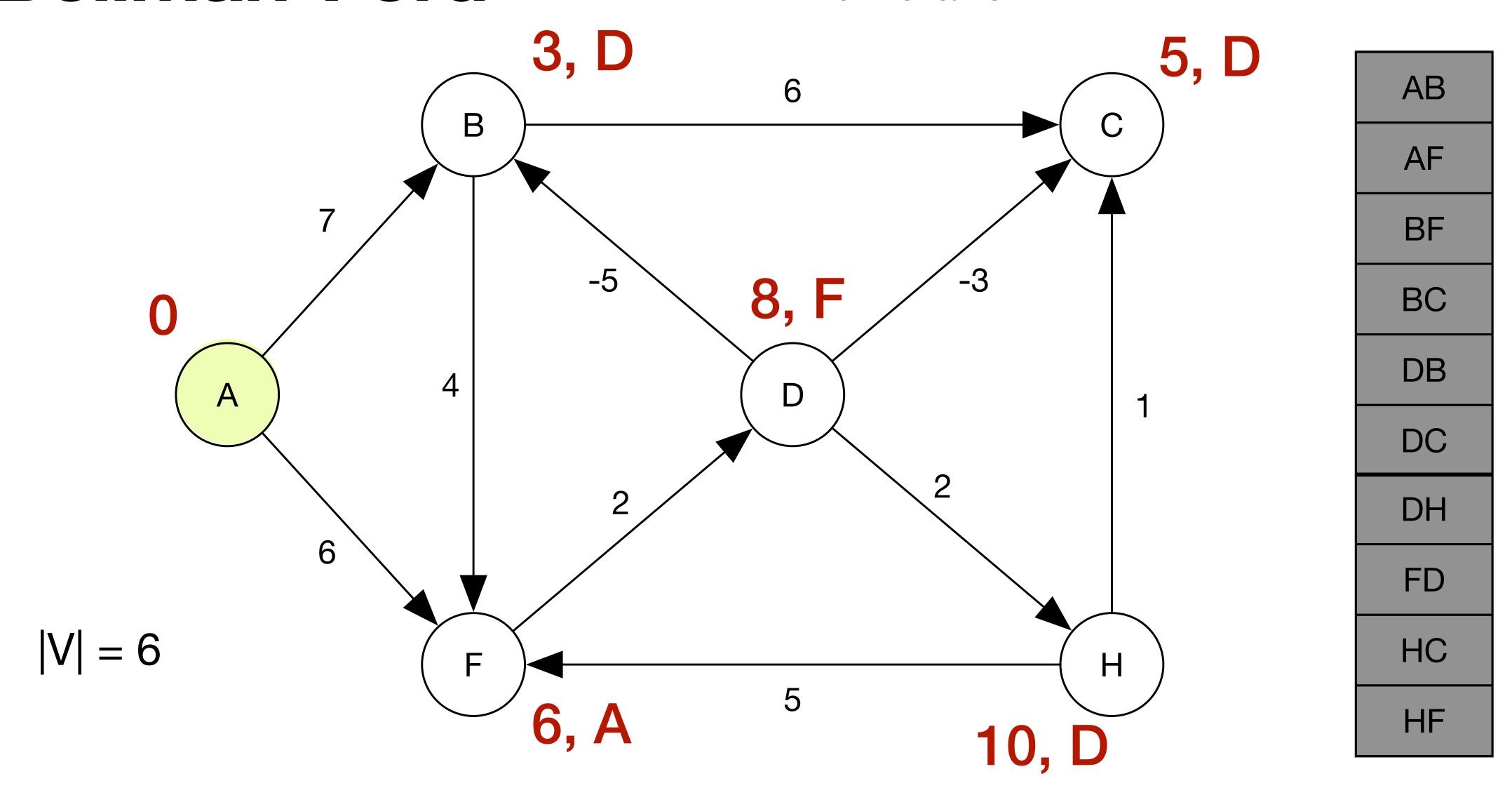


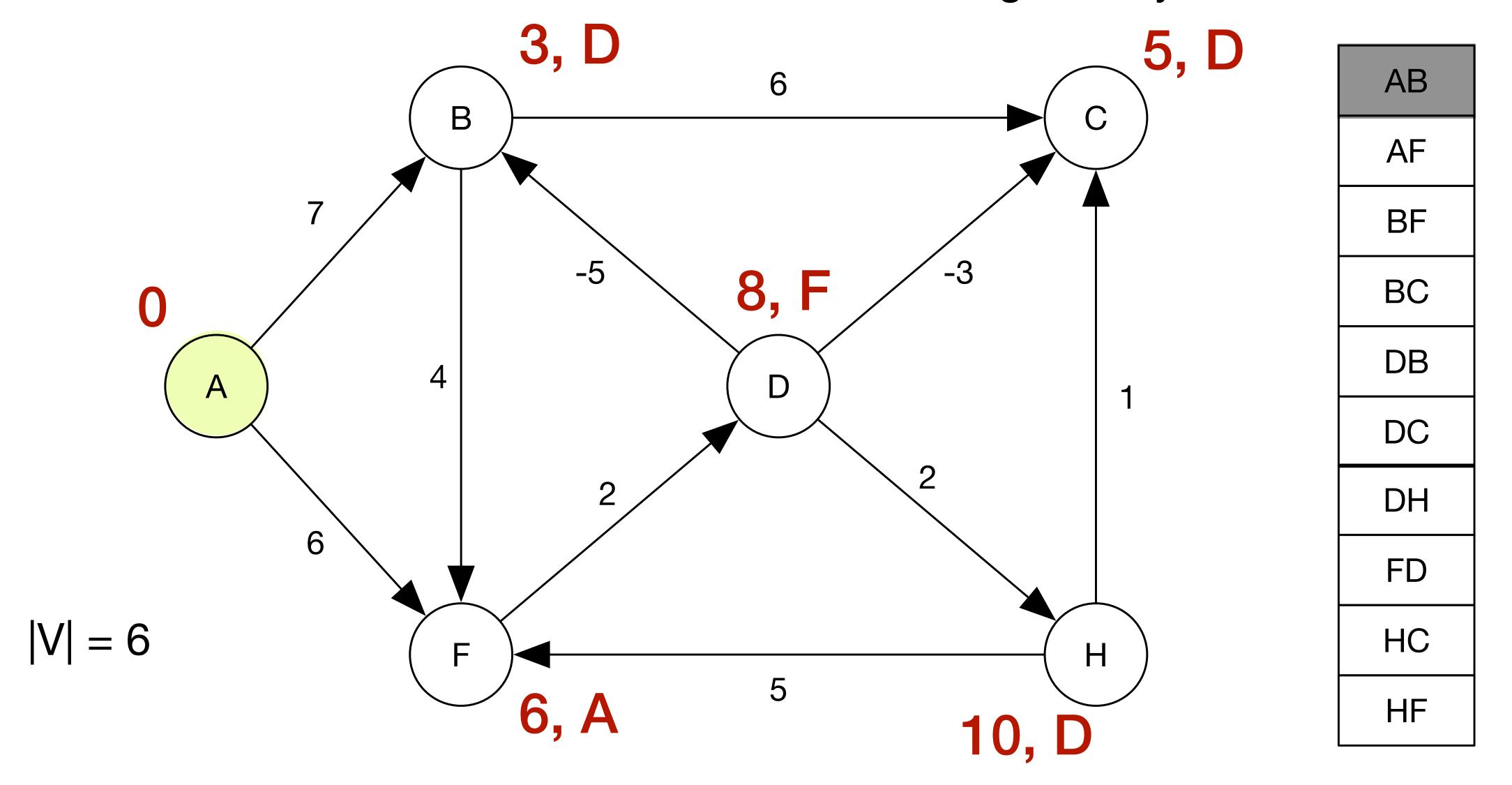
AB

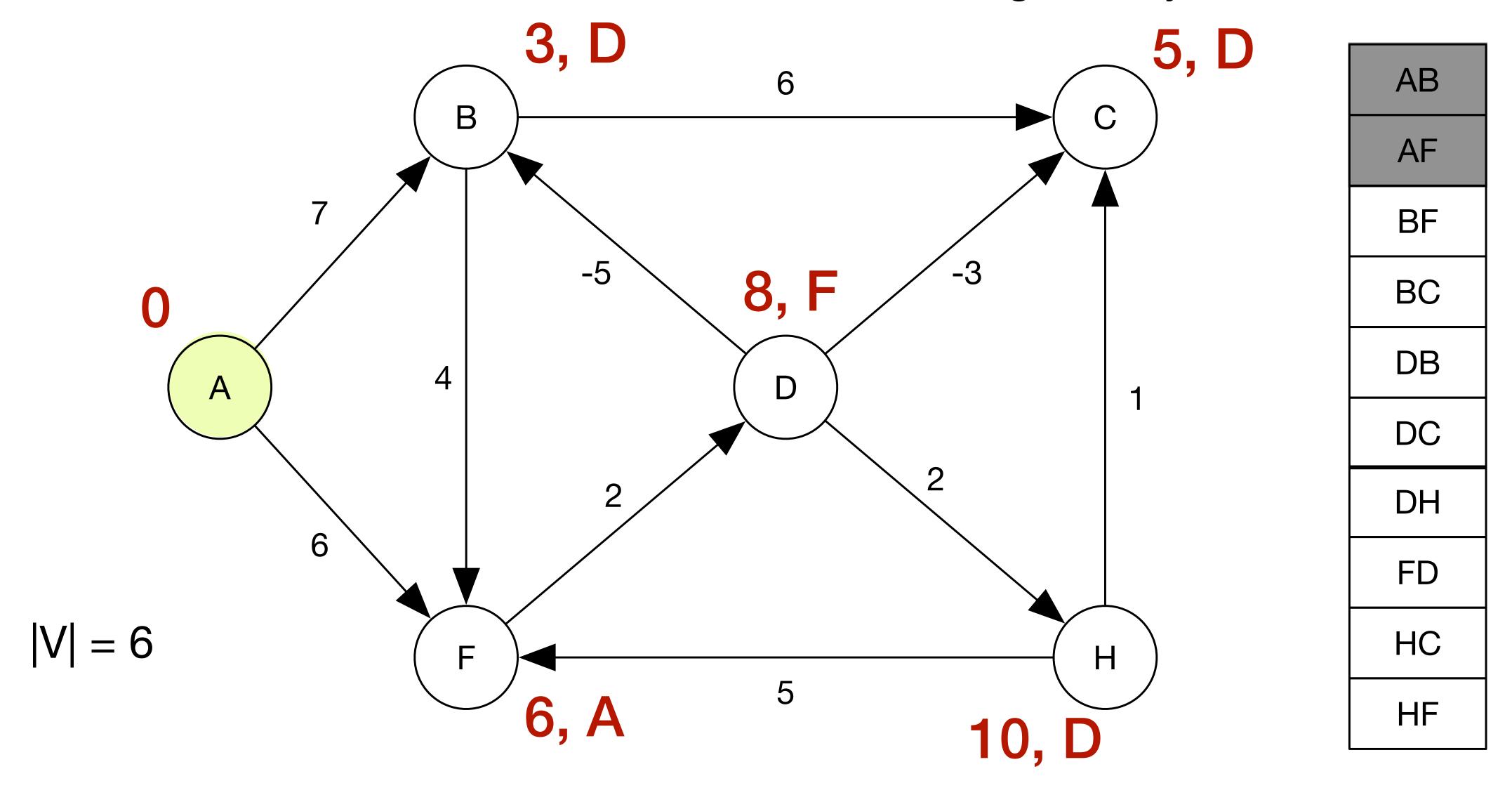
HC

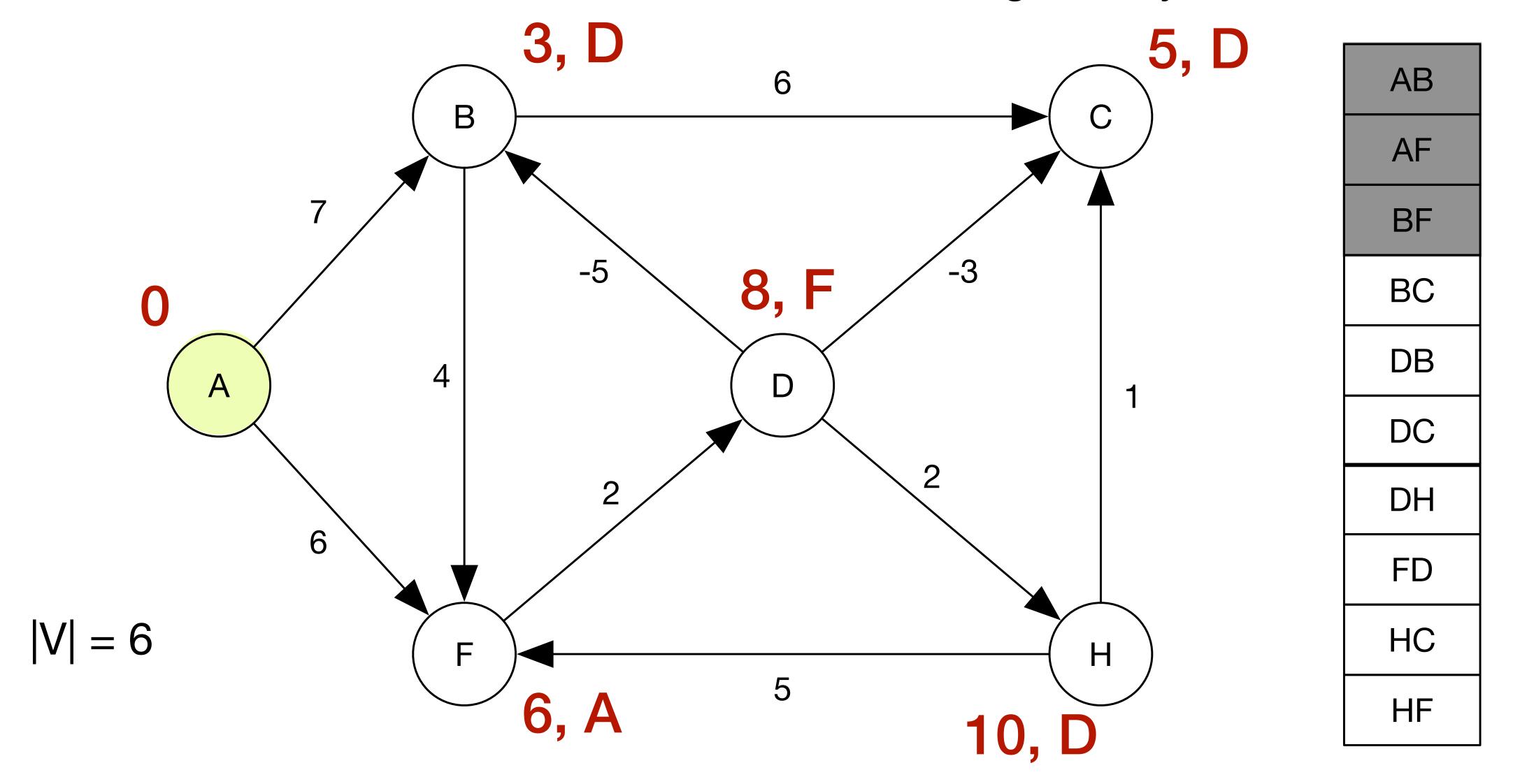


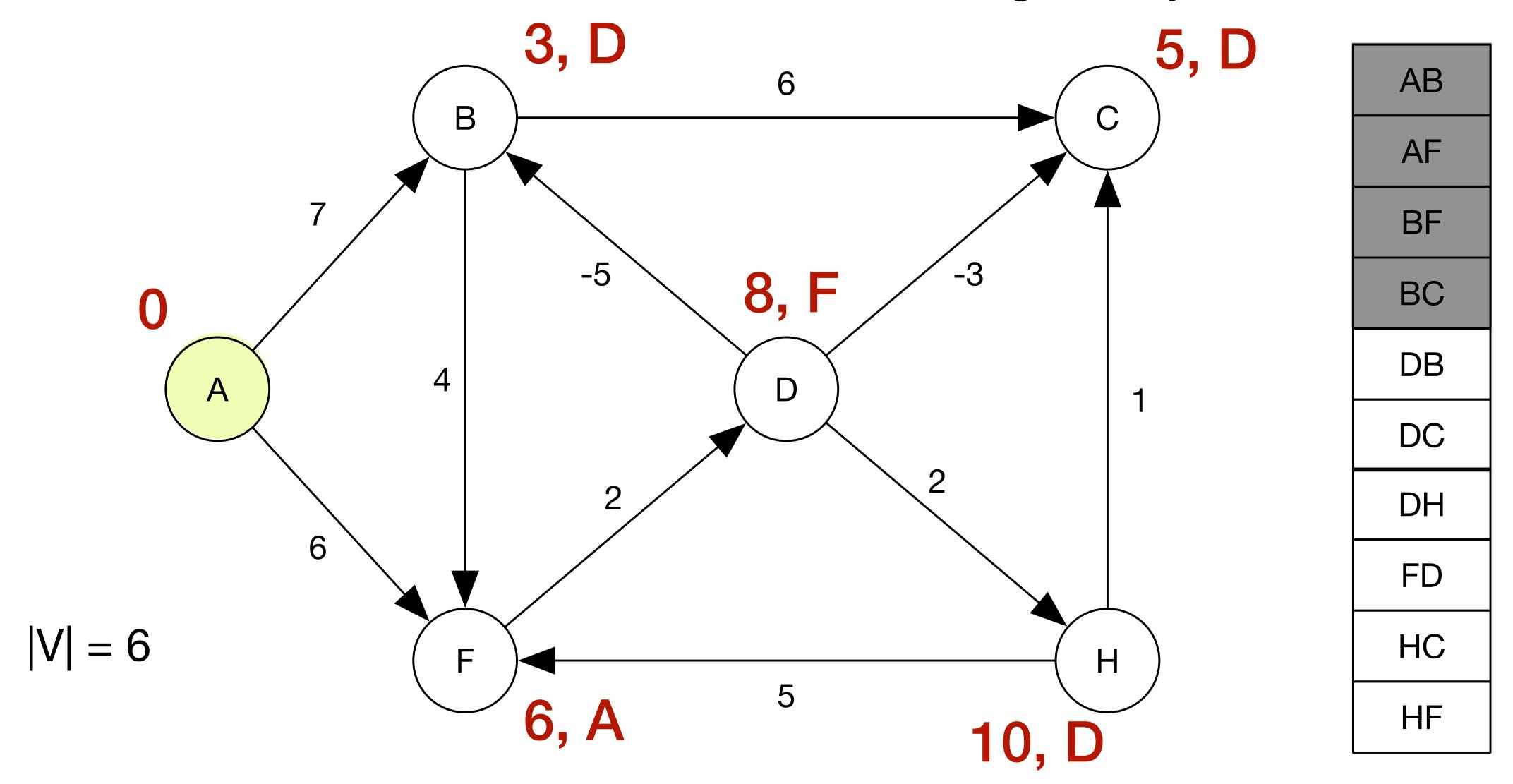


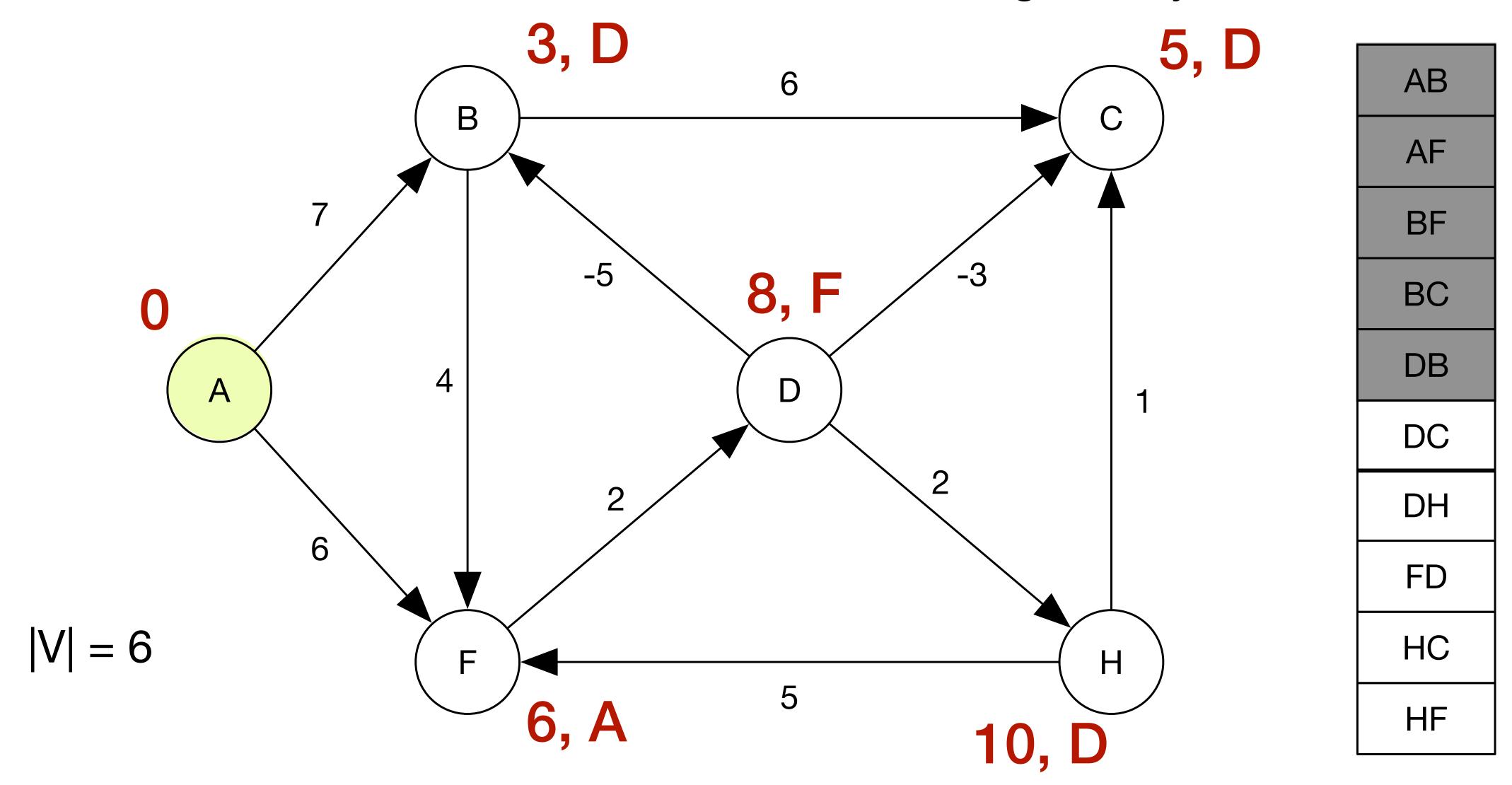


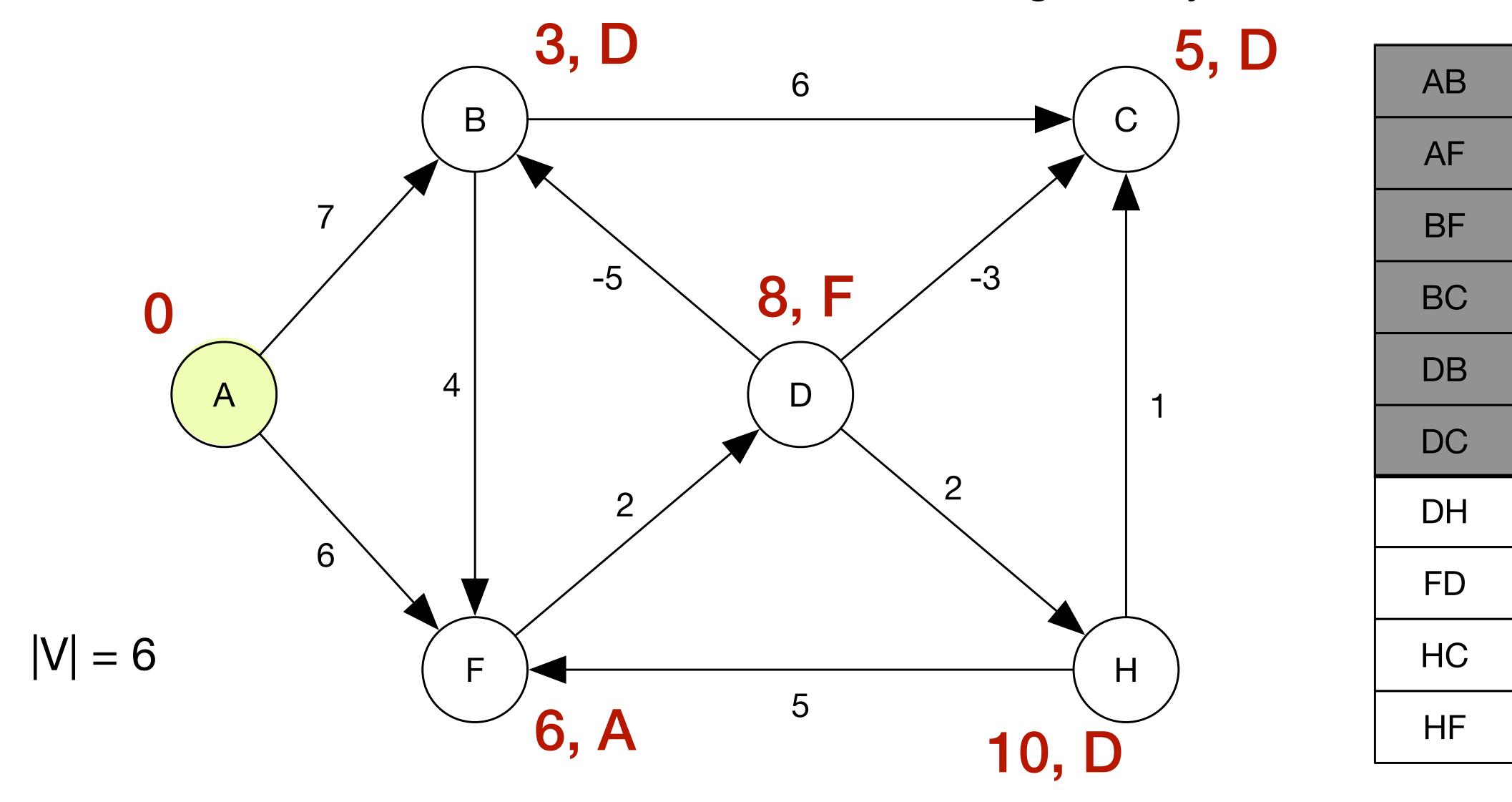


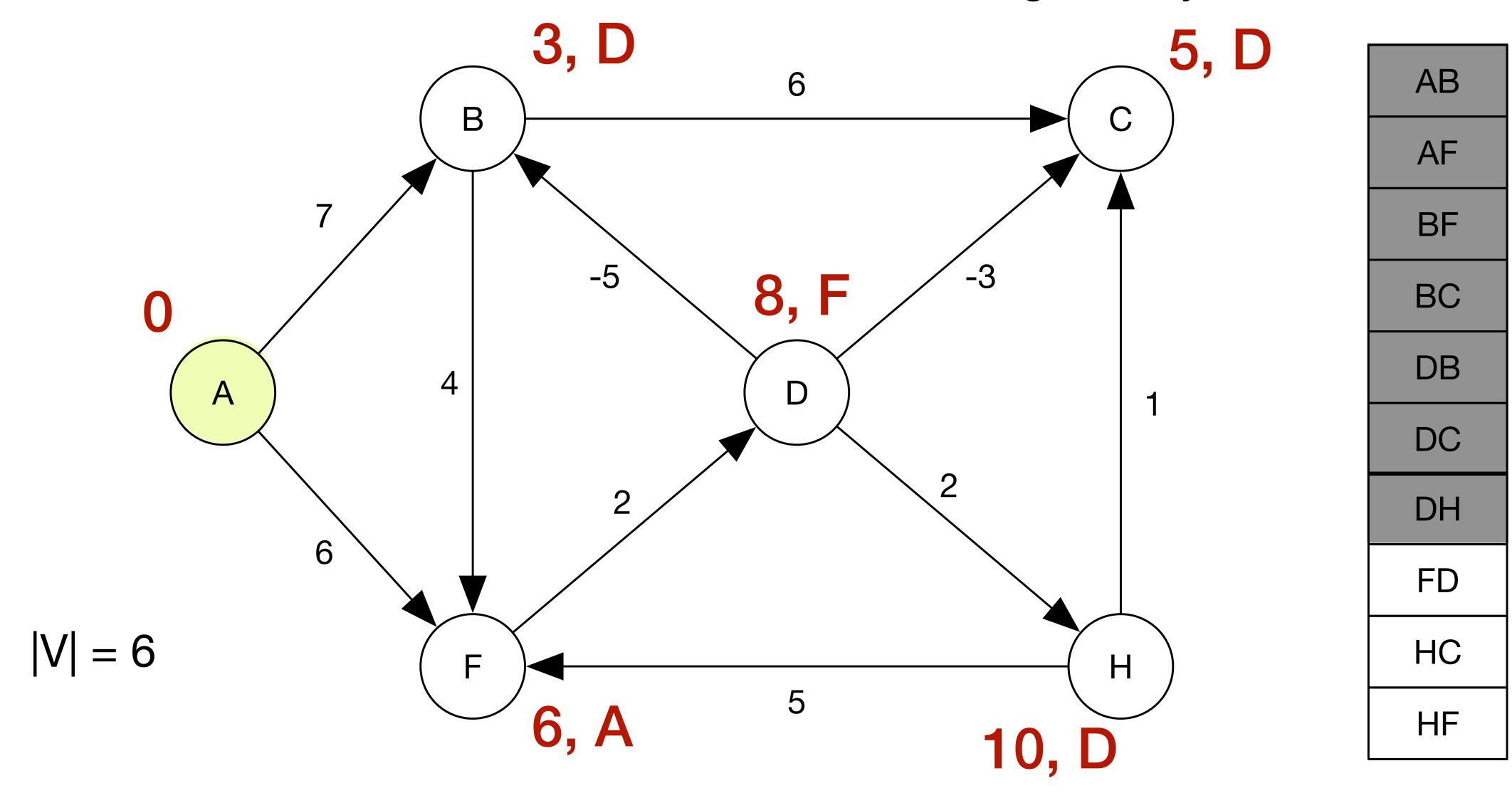


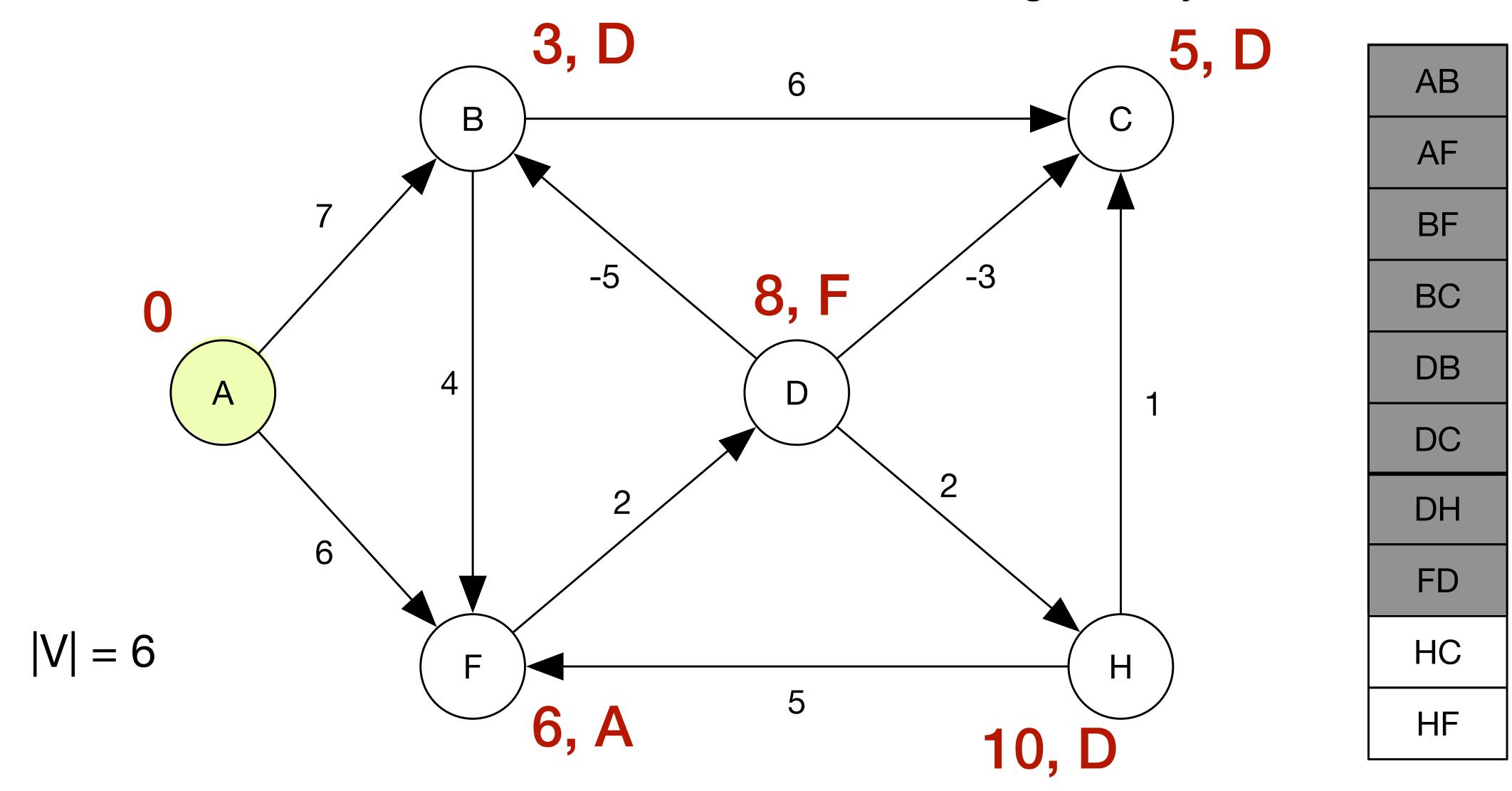


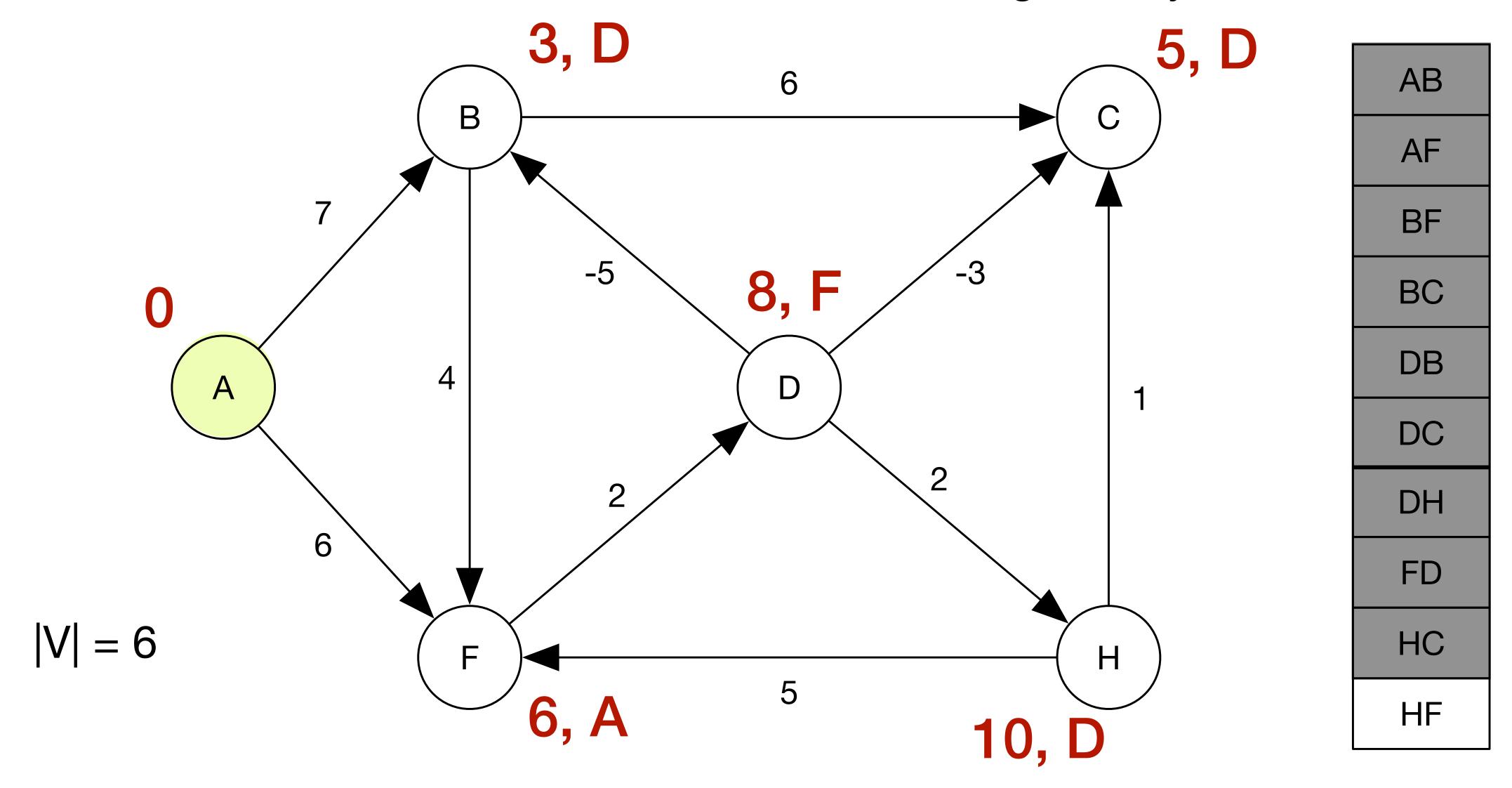


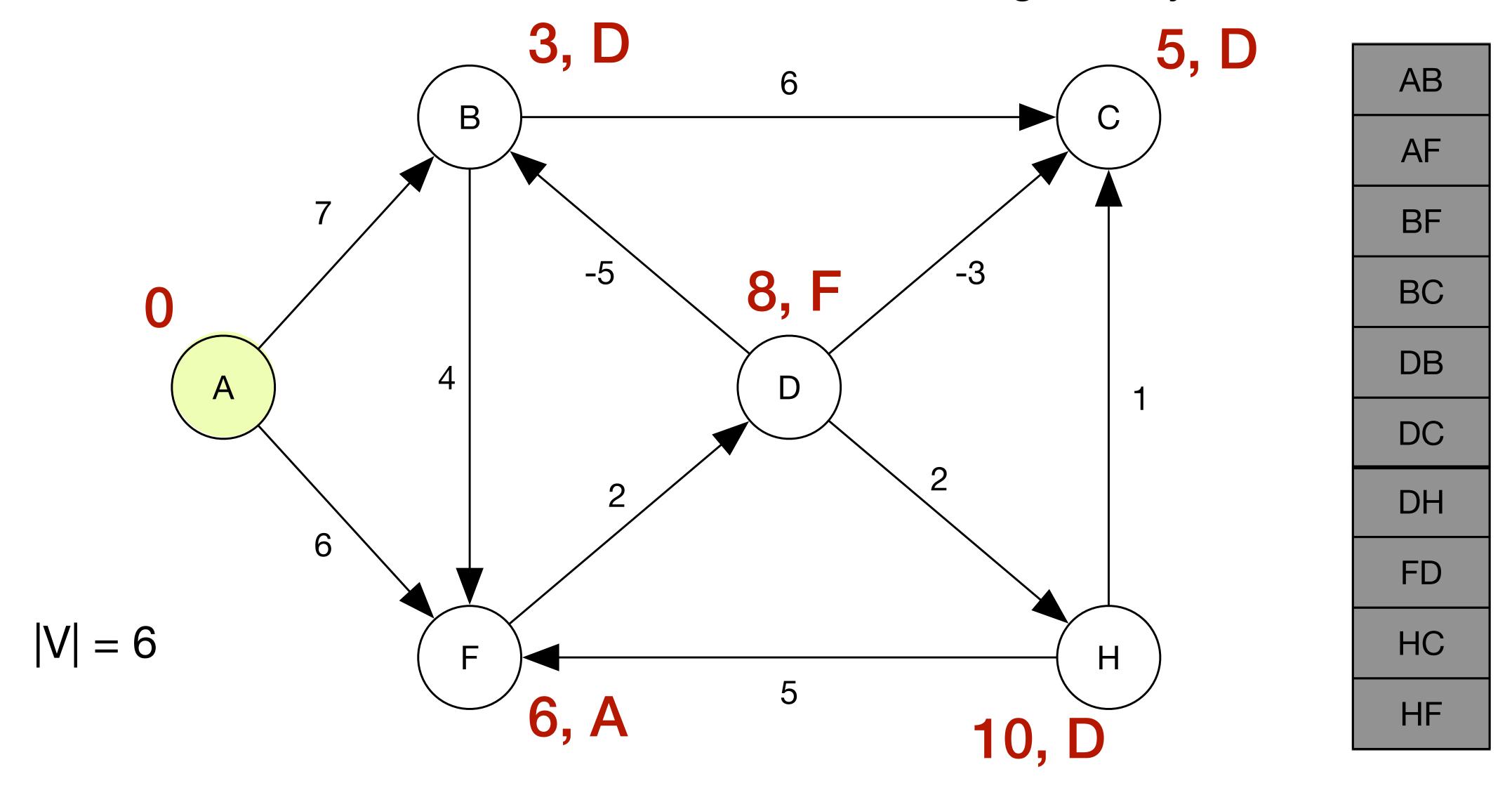




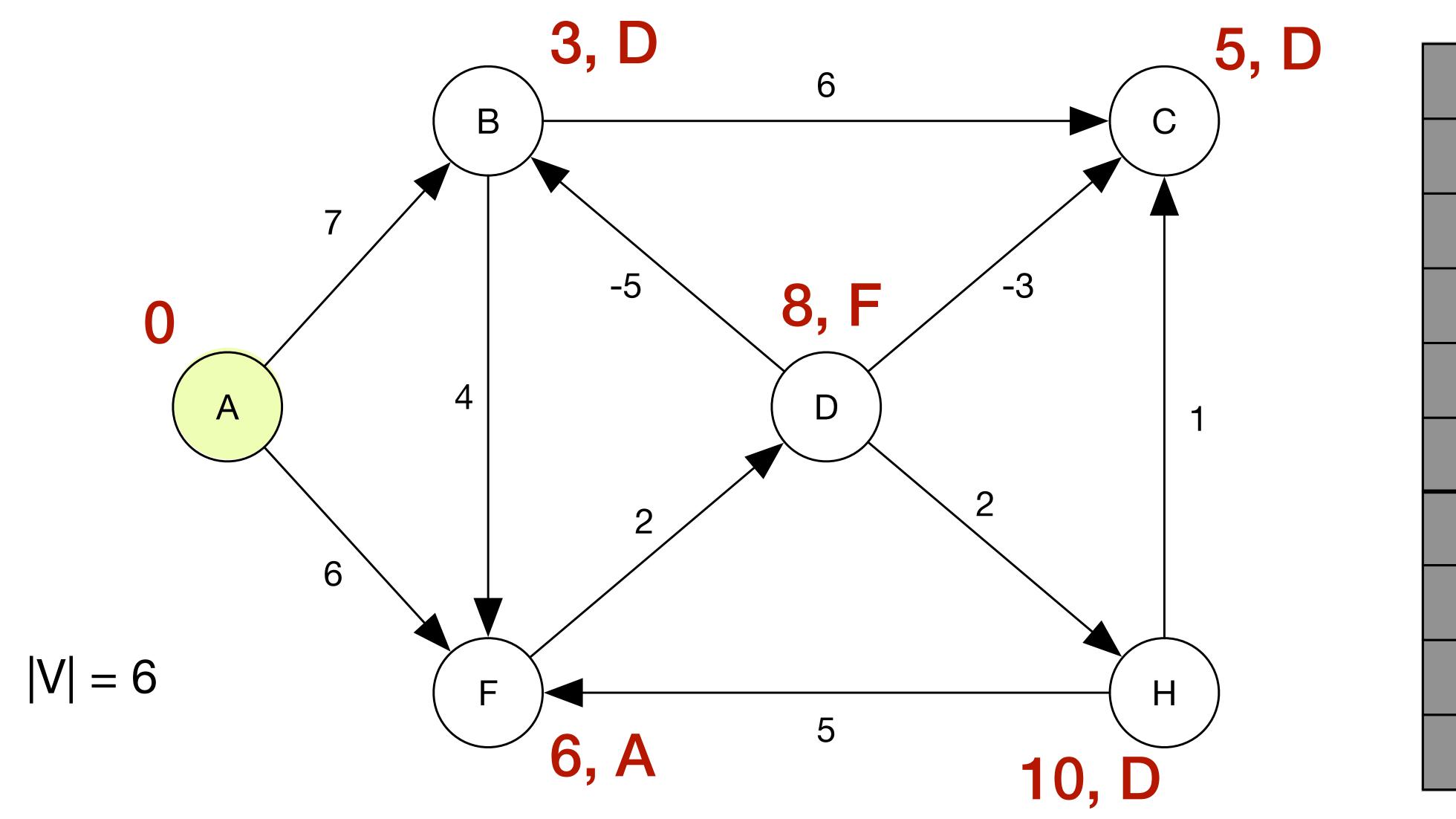








Done!



AB

AF

BF

BC

DB

DC

DH

FD

HC

HF

Why do we need up to |V| - 1 iterations?

Why do we need up to |V| - 1 iterations? If we have |V| nodes, then the shortest path can have no more than |V| - 1 edges. When we iterate, at the kth iteration, we know we've covered all shortest paths up to length k. To consider all possible shortest paths, we need k = |V| - 1.

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How does the check for negative cycles work?

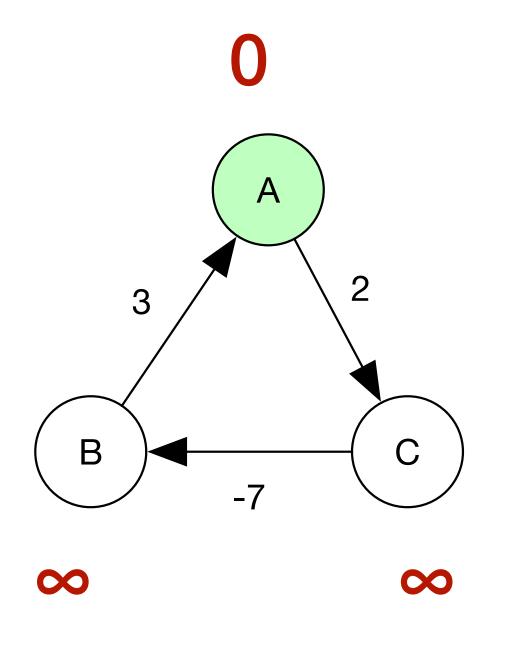
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How does the check for negative cycles work? Once we've processed the graph with |V| - 1 iterations, we check weights. For each edge (U, V) if the distance to V is greater than the sum of the distance to U plus the edge weight from U -> V, then we know we have a negative cycle.

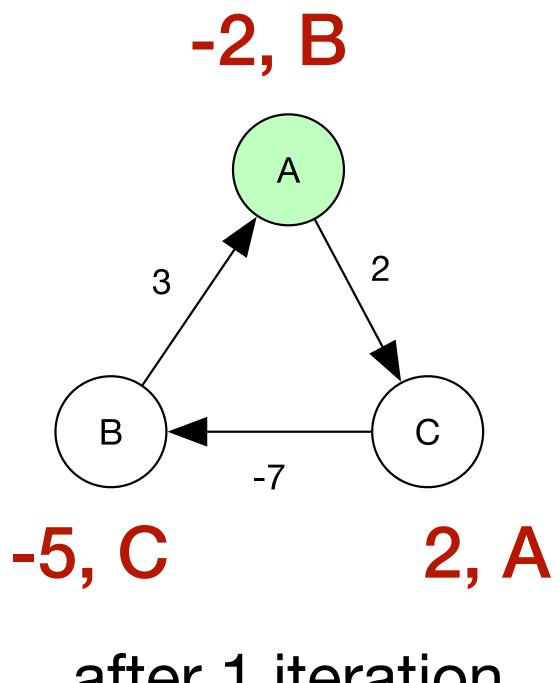
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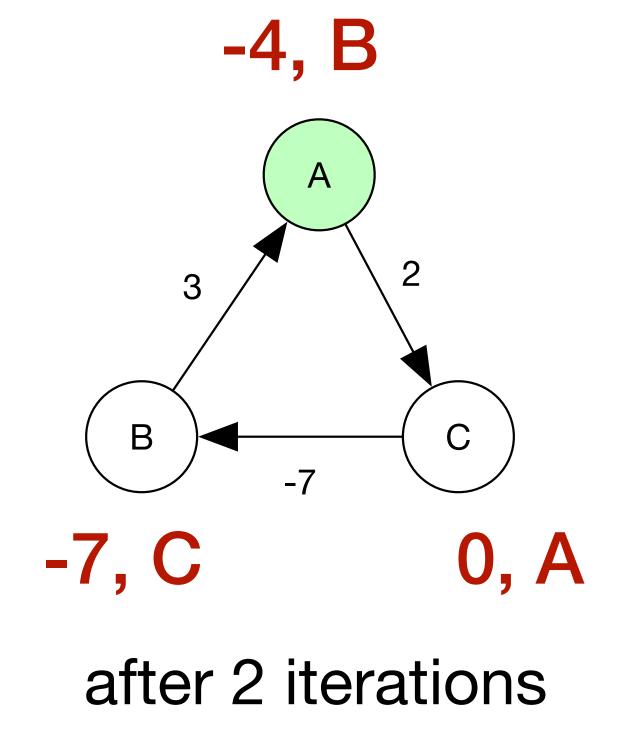
#### Negative cycle detection



initial state

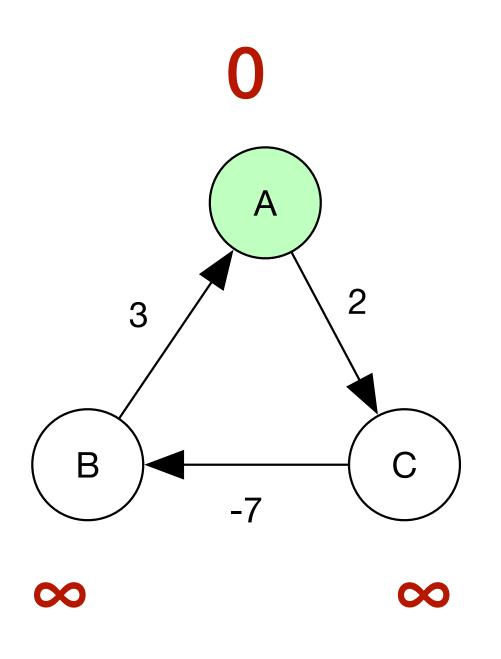


after 1 iteration

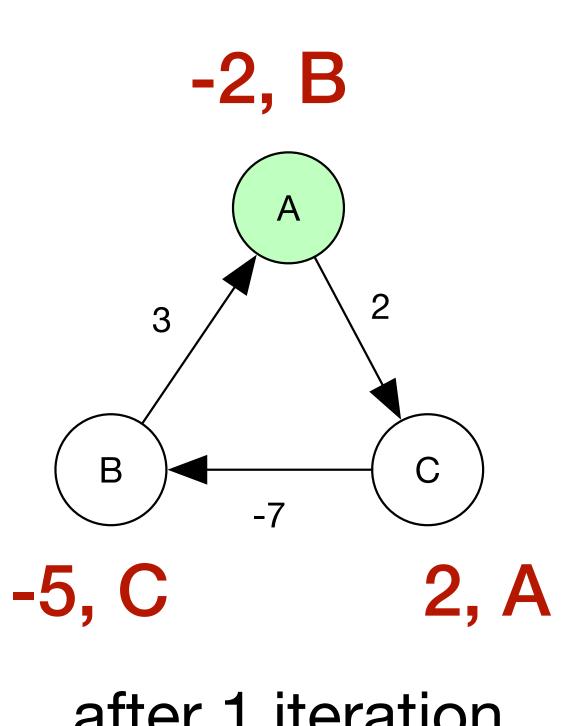


#### Negative cycle detection

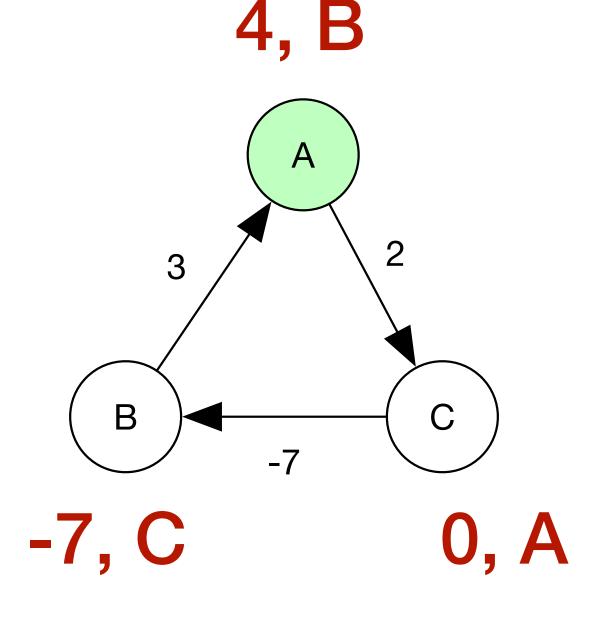
for edge (U, V), if distance[V] > distance[U] + weight of edge then we have a negative cycle



initial state



after 1 iteration



after 2 iterations

$$4 > -7 + 3$$

Why do we need up to |V| - 1 iterations? If we have |V| nodes, then the shortest path can have no more than |V| - 1 edges. When we iterate, at the kth iteration, we know we've covered all shortest paths up to length k. To consider all possible shortest paths, we need k = |V| - 1.

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#### **Shortest Path**

Algorithm	Dijkstra	Bellman - Ford
Worst-case complexity	O(( V  +  E ) log  V )	O( V  x  E )

Restrictions

Edge weights must be non-negative

No negative cycles