

Qualifying Examination

Spring 2016

For passing this exam, four problems must be done completely correctly and one problem must be at least 75% correct. Of the four completed problems, two must come from each part of the exam. (E.g., completing problems 1, 2, 3, 4 and doing problem 5 at 75% will not be a passing score; on the other hand, completing 1, 2, 4, 6 and doing either 3 or 5 at 75% will constitute a pass.)

You have three hours to complete the exam.

Note: Make sure to provide **explanations** to all steps of your solutions and to **explain** all answers to posed questions.

Part 1

1. Consider $f(x) = \ln(x + 3)$.
 - (a) Use $x_0 = 0$, $x_1 = 0.2$ and $x_2 = 0.5$ to construct the Lagrange interpolating polynomial of degree at most two to approximate $f(0.25)$ and find the absolute error of this approximation.
 - (b) Use the Theorem on polynomial interpolation error to find an error bound for the above approximation.
2. Find the natural cubic spline for the data points $(1, 5)$, $(2, 3)$ and $(3, -1)$.
3. (a) Starting from $p_0(x) = 1$, $p_1(x) = x$ and $p_2(x) = x^2$, compute a set of orthogonal polynomials: $q_0(x)$, $q_1(x)$ and $q_2(x)$, subject to the following inner product:

$$\langle f, g \rangle = \int_{-1}^1 x^2 f(x)g(x)dx.$$

Then find the two roots, x_1 and x_2 , of $q_2(x)$.

- (b) Determine the coefficients A_1 and A_2 that make the following formula exact for all polynomials of maximum degree m :

$$\int_{-1}^1 x^2 f(x)dx \approx A_1 f(x_1) + A_2 f(x_2),$$

where x_1 and x_2 are found in (a). What is m ?

See Part 2 on next page.

Part 2

4. Method

$$Y_{n+1} = \frac{1}{3}(2Y_n + Y_{n-1}) + \frac{h}{3}(f_{n-1} + f_n + 2f_{n+1}),$$

where $f_n = f(x_n, Y_n)$, etc., can be used to solve an ordinary differential equation (ODE) $y' = f(x, y)$ or systems of first-order ODEs.

(a) Show that this method is second-order accurate.

(b) Write out the difference equations that result when this method is applied to integrate the equation of the harmonic oscillator $u'' = -\Omega^2 u$.

5. (a) Propose a 2nd-order accurate discretization of the equation

$$(p(x)u_x)_x = q(x)u + r(x). \quad (1)$$

Explain why it is 2nd-order accurate.

(b) Use this discretization to set up a linear system for the boundary-value problem given by Eq. (1) and by the boundary conditions

$$u_x(0) = \alpha, \quad u(1) = \beta, \quad (2)$$

where α, β are some given constants.

Specifically, make sure to use a 2nd-order accurate approximation to handle the Neumann boundary condition at $x = 0$. Then, explain how you will determine the unknown solution u at all grid nodes that you have introduced.

6. Consider the Heat equation $u_t = u_{xx}$ on the domain $0 \leq x \leq 1$ and subject to the Dirichlet boundary conditions. For future reference, a first-order in time, explicit scheme for this equation is:

$$U_m^{n+1} - U_m^n = r(U_{m+1}^n - 2U_m^n + U_{m-1}^n), \quad (1)$$

where $r = \kappa/h^2$ and κ and h are the step sizes in time and space, respectively. The amplification coefficient, obtained by the von Neumann analysis, of one time step of scheme (1) equals:

$$\rho = 1 - 4r \sin^2 \frac{\beta h}{2}, \quad (2)$$

where β is the wavenumber of the Fourier harmonic $\exp[i\beta mh]$. The stability condition for scheme (1) is: $r \leq 0.5$. You do *not* need to derive any of the results stated above.

(a) Write out a fully *implicit*, first-order in time scheme for the Heat equation. (Just stating the scheme is enough; you do *not* need to prove that it is first-order accurate.) Use the von Neumann analysis to derive its amplification coefficient of one time step and determine the stability condition for this scheme.

(b) Suppose your initial condition is a discontinuous function of x . Which scheme, (1) or the one you have derived in part (a), will more efficiently smoothen out the discontinuity? Answer this question for each of the two values of r : $r = 0.2$ and $r = 0.4$.