

# One.II Linear Geometry

*Linear Algebra*

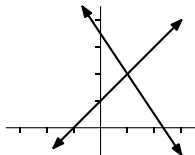
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<http://joshua.smcvt.edu/linearalgebra>

# Geometry

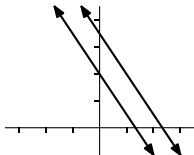
We can draw two-unknown equations as lines. Then the three possibilities for solution sets become clear.

*Unique solution*



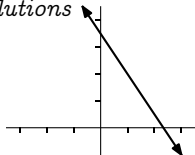
$$\begin{aligned}3x + 2y &= 7 \\ x - y &= -1\end{aligned}$$

*No solutions*



$$\begin{aligned}3x + 2y &= 7 \\ 3x + 2y &= 4\end{aligned}$$

*Infinitely many solutions*



$$\begin{aligned}3x + 2y &= 7 \\ 6x + 4y &= 14\end{aligned}$$

Besides being pretty, the geometry helps us understand what is happening.

# Vectors in space

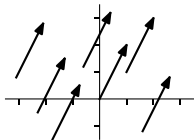
# Vectors

A *vector* is an object consisting of a magnitude and a direction.



For instance, a vector can model a displacement.

Two vectors with the same magnitude and same direction, such as all of these, are equal.



For instance, each of the above could model a displacement of one over and two up.

Denote the vector that extends from  $(a_1, a_2)$  to  $(b_1, b_2)$  by

$$\begin{pmatrix} b_1 - a_1 \\ b_2 - a_2 \end{pmatrix}$$

so the “one over, two up” vector would be written in this way.

$$\begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

We often picture a vector

$$\vec{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$$

as starting at the origin. From there  $\vec{v}$  extends to  $(v_1, v_2)$  and we may refer to it as “the point  $\vec{v}$ ” so that we may call each of these  $\mathbb{R}^2$ .

$$\{(x_1, x_2) \mid x_1, x_2 \in \mathbb{R}\} \quad \left\{ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mid x_1, x_2 \in \mathbb{R} \right\}$$

These definitions extend to higher dimensions. The vector that starts at  $(a_1, \dots, a_n)$  and ends at  $(b_1, \dots, b_n)$  is represented by this column

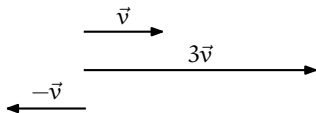
$$\begin{pmatrix} b_1 - a_1 \\ \vdots \\ b_n - a_n \end{pmatrix}$$

and two vectors are equal if they have the same representation. Also, we aren't too careful about distinguishing between a point and the vector which, when it starts at the origin, ends at that point.

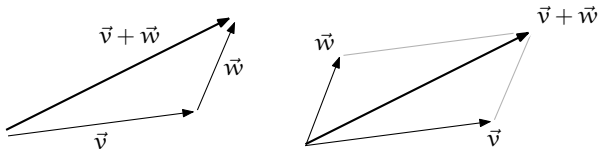
$$\mathbb{R}^n = \left\{ \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix} \mid v_1, \dots, v_n \in \mathbb{R} \right\}$$

## Vector operations

Scalar multiplication makes a vector longer or shorter, including possibly flipping it around.



Where  $\vec{v}$  and  $\vec{w}$  represent displacements, the vector sum  $\vec{v} + \vec{w}$  represents those displacements combined.

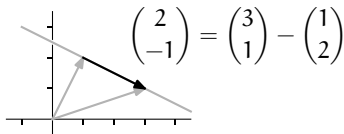


The second drawing shows the *parallelogram rule* for vector addition.

## Lines

The line in  $\mathbb{R}^2$  through  $(1, 2)$  and  $(3, 1)$  is comprised of the vectors in this set

$$\left\{ \begin{pmatrix} 1 \\ 2 \end{pmatrix} + t \begin{pmatrix} 2 \\ -1 \end{pmatrix} \mid t \in \mathbb{R} \right\}$$



(that is, it is comprised of the endpoints of those vectors). The vector associated with the parameter  $t$

$$\begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

is a *direction vector* for the line. Lines in higher dimensions work the same way.