

## The Tautochronous Pendulum.

Consider a cylinder of radius  $a$ . Let the cylinder roll to the right without slipping on a horizontal surface from initial point of contact  $O$  to new point of contact  $Q$  (see Figure 1). Let  $O$  be the fixed origin of the coordinate system. Note that the initial point of contact at  $O$  has moved to a new position  $P$ . The coordinates of that point are the cycloid coordinates:

$$x = a\theta - a \sin \theta \quad (1)$$

$$y = a - a \cos \theta \quad (2)$$

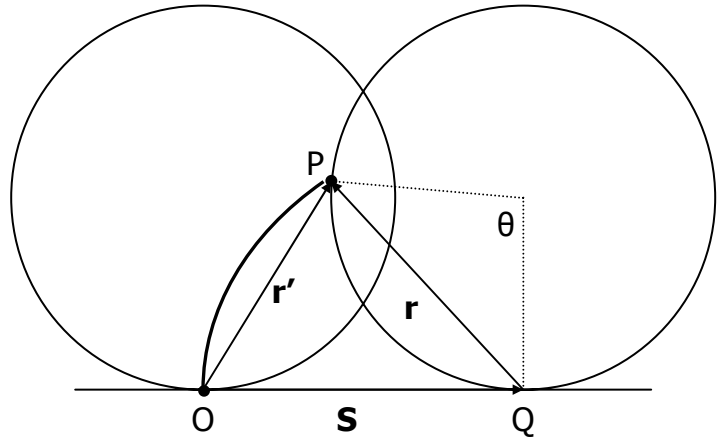


Figure 1.

**Proposition I: Segment QP is perpendicular to the cycloid line at P.**

Proof

We need show that the line element  $ds$  that is tangent to the cycloid at  $P$  is perpendicular to  $QP$ . Consider vectors  $\mathbf{S}$ ,  $\mathbf{r}$  and  $\mathbf{r}'$  as shown in the drawing. Clearly,  $\mathbf{r} = \mathbf{r}' - \mathbf{S}$ . Then,

$$\mathbf{r}' = (a\theta - a \sin \theta) \mathbf{e}_x + a(1 - \cos \theta) \mathbf{e}_y$$

$$\mathbf{S} = a\theta \mathbf{e}_x$$

$$\mathbf{r} = \mathbf{r}' - \mathbf{S} = -a \sin \theta \mathbf{e}_x + a(1 - \cos \theta) \mathbf{e}_y$$

Now

$$d\mathbf{s} = dx \mathbf{e}_x + dy \mathbf{e}_y = a(1 - \cos \theta) d\theta \mathbf{e}_x + a \sin \theta d\theta \mathbf{e}_y$$

and,

$$d\mathbf{s} \cdot \mathbf{r} = -a^2 \sin \theta (1 - \cos \theta) d\theta + a^2 \sin \theta (1 - \cos \theta) d\theta = 0.$$

Therefore,  $ds$  is perpendicular to  $QP$  at  $P$ , QED.

**Proposition II: The length of arc segment OP along the cycloid is  $s = 4a(1 - \cos \frac{\theta}{2})$**

Proof

$$ds = \sqrt{(dx)^2 + (dy)^2}$$

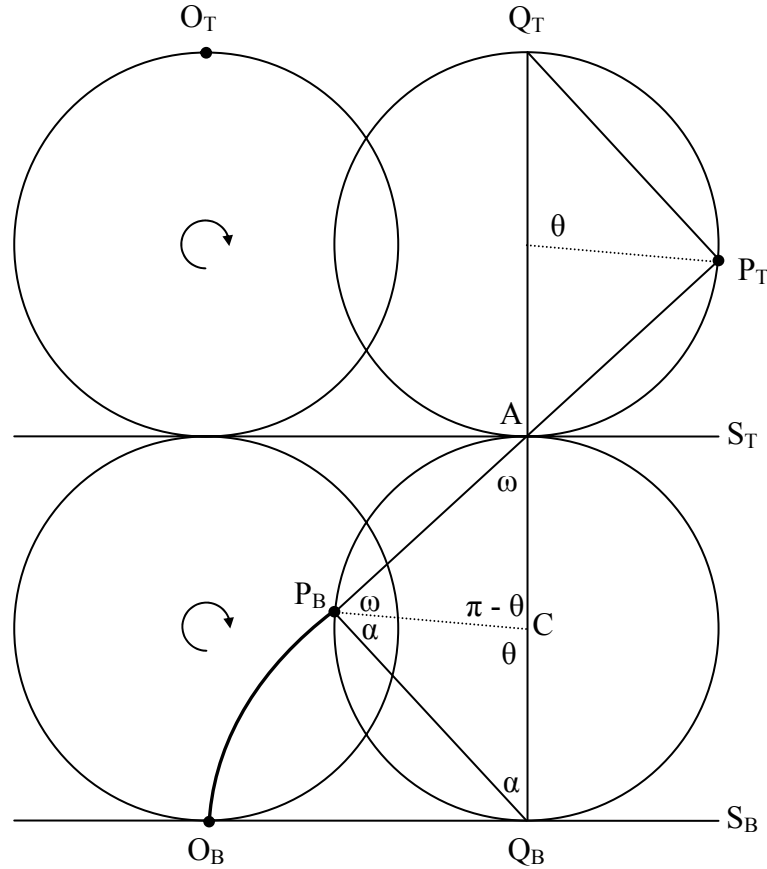
$$dx = (1 - \cos \theta)a d\theta; \quad dy = a \sin \theta d\theta$$

$$ds = a d\theta \sqrt{(1 - \cos \theta)^2 + (\sin \theta)^2} = a d\theta \sqrt{2(1 - \cos \theta)} = 2a \sin \frac{\theta}{2} d\theta$$

$$s = 2a \int_0^\theta \sin \frac{\theta}{2} d\theta = 4a \left[ -\cos \frac{\theta}{2} \right]_0^\theta = 4a \left( 1 - \cos \frac{\theta}{2} \right)$$

QED.

**Proposition III:** Consider two identical cylinders, bottom and top. They roll without slipping on bottom and top surfaces  $S_B$  and  $S_T$  with identical velocities to the right (see figure 2). Let  $O_B$  and  $O_T$  be cycloid generator points for each cylinder. **When the cylinders have rotated by angle  $\theta$ , line segment  $P_T P_B$  is tangent to the cycloid at point  $P_B$ .**



**Figure 2.**

Proof:

We need to show that segment  $P_T P_B$  is perpendicular to segment  $Q_B P_B$  at point  $P_B$ . Then, by Proposition I, segment  $P_T P_B$  is tangent to the cycloid at point  $P_B$ .

First we note that, by symmetry, triangles  $A Q_B P_B$  and  $A Q_T P_T$  are congruent. This means that line  $P_T P_B$  has to pass through point  $A$ , the point at which the cylinders are tangent to one another.

From isosceles triangle  $\triangle C P_T P_B$  we have

$$2\alpha + \theta = \pi \rightarrow \alpha = \frac{\pi}{2} - \frac{\theta}{2}$$

and from isosceles  $\triangle C A P_B$

$$2\omega + (\pi - \theta) = \pi \rightarrow \omega = \frac{\theta}{2}$$

Adding the two equations gives  $\alpha + \omega = \frac{\pi}{2}$  which proves the proposition. It follows from the

above that segment  $P_T P_B$  is perpendicular to the tangent of the top cycloid at point  $P_T$ .

**Proposition IV: The length of curvilinear segment  $O_B P_B P_T$  is constant and equal to  $4a$ .**

To find the length of the curvilinear segment, we need to add the curved segment  $s$  from Proposition II, to the length of straight line segment  $P_B P_T$ . The coordinates of  $P_B$  are given by equations (1) and (2):

$$x_B = a\theta - a \sin \theta$$

$$y_B = a - a \cos \theta$$

The equation for the top cycloid with origin at  $O_B$  can easily be found to be

$$x_T = a\theta + a \sin \theta$$

$$y_T = 3a + a \cos \theta$$

The length of segment  $P_B P_T$  is

$$d = \sqrt{(x_T - x_B)^2 + (y_T - y_B)^2} = \sqrt{(2a \sin \theta)^2 + (2a + 2a \cos \theta)^2} = 2a\sqrt{2(1 + \cos \theta)}.$$

Now,

$$1 + \cos \theta = 1 + \cos^2 \frac{\theta}{2} - \sin^2 \frac{\theta}{2} = 2 \cos^2 \frac{\theta}{2}.$$

Therefore,

$$d = 4a \cos \frac{\theta}{2}$$

The length of the curvilinear segment is the sum:

$$L = s + d = 4a \left(1 - \cos \frac{\theta}{2}\right) + 4a \cos \frac{\theta}{2} = 4a, \text{ QED.}$$

Now pretend that gravity acts (unconventionally) from bottom to top. If a string of length  $4a$  is attached to a fixed support at  $O_B$  and a mass is attached to the other end at point  $P_T$ , the mass will move under the influence of gravity in a cycloid, i.e. we have the brachistochrone problem with the following non-essential difference: In the brachistochrone problem the track provides the normal force; here it is the tension that provides the normal force.

In the brachistochrone, we have seen that the time required for the mass to reach the horizontal position from any starting position is the same and equal to  $\pi\sqrt{a/g}$ . This says that the tautochronous pendulum has a period that is independent of the amplitude. Since the time required to reach the equilibrium position starting from anywhere is one-quarter of the period, the period of the tautochronous pendulum is  $T = 4\pi\sqrt{a/g}$ .